

VISVESVARAYA TECHNOLOGICAL UNIVERSITY

"Jnana Sangama" Belagavi – 590 010



PROJECT REPORT ON
“INTELLIGENT VISION BASED ROBOT USED IN
SECURITY FOR IDENTIFYING AND FIRING
ENEMIES”

Submitted in partial fulfillment of the requirements for the award of degree

BACHELOR OF ENGINEERING
IN
ELECTRONICS & COMMUNICATION ENGINEERING

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DEPARTMENT OF ELECTRONICS & COMMUNICATION ENGINEERING

CERTIFICATE

Certified that the project work entitled "INTELLIGENT VISION BASED ROBOT USED IN SECURITY FOR IDENTIFYING AND FIRING ENEMIES" is a bona fide work carried out by

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in partial fulfillment for the award of BACHELOR OF ENGINEERING in **ELECTRONICS & COMMUNICATION ENGINEERING** of the **VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI** during the year 2016–2017. It is certified that all corrections/suggestions indicated for Internal Assessment have been incorporated in the report deposited in the departmental library. The project report has been approved as it satisfies the academic requirements in respect of Project work prescribed for the Bachelor of Engineering Degree.

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ABSTRACT

The Border Security Force (BSF) of nation plays an important role in preventing the entry of terrorists and illegal people with drugs and weapons. The BSF is the primary border guarding force of India. It ensures the security of the borders of India and the matters connected with it. India shares its borders with six nations namely China, Pakistan, Bangladesh, Nepal, Myanmar and Bhutan. There exist some dangerous borders where BSF men find it very difficult to operate there. The Line of Control (LOC) between India and Pakistan and the Siachen, world's highest battle field have witnessed the loss of many lives of soldiers whenever there is a terror attack. To overcome above stated problems, an Intelligent vision based robot used in security for identifying and firing enemies which continuously monitors the given real time area and if at all some terrorists or enemies try to enter into that area they are shot.

An USB camera which is used for the continuous monitoring of the real time scenario sends the data to the monitoring PC. The PC performs certain MATLAB operations with the real time images; this data is sent to the microcontroller ATmega328 serially through ZigBee. The robot performs the operations based on the data sent by the microcontroller. The system is provided with the intelligence to discriminate between enemies/terrorists and our soldiers by the presence of Phototransistor circuit. If the detected intruder is an enemy, then the system automatically fires against the enemies using the laser gun.