

DYNAMICS OF MACHINERY
B.E, VSemester, Mechanical Engineering
[As per Choice Based Credit System (CBCS) scheme]

Course Code	17ME52	CIE Marks	40
Number of Lecture Hours/Week	04	SEE Marks	60
Total Number of Lecture Hours	50(10 Hours per Module)	Exam Hours	03

Credits – 04

Course Objectives:

1. To gain the knowledge static and dynamic equilibrium conditions of mechanisms subjected forces and couple, with and without friction.
2. Analyze the mechanisms for static and dynamic equilibrium.
3. To understand the balancing principles of rotating and reciprocating masses, governors and gyroscopes.
4. Analyze the balancing of rotating and reciprocating masses, governors and gyroscopes.
5. To understand vibrations characteristics of single degree of freedom systems.
6. Characterize the single degree freedom systems subjected to free and forced vibrations with and without damping.

Module - 1

Static force Analysis: Static equilibrium. Equilibrium of two and three force members. Members with two forces and torque, Free body diagrams, Static force analysis of four bar mechanism and Slider-crank mechanism with and without friction.

Dynamic force Analysis: D'Alembert's principle, Inertia force, Inertia torque. Dynamic force analysis of four-bar mechanism and Slider crank mechanism without friction, numerical problems.

Module - 2

Balancing of Rotating Masses: Static and dynamic balancing, balancing of single rotating mass by balancing masses in same plane and in different planes. Balancing of several rotating masses by balancing masses in same plane and in different planes.

Balancing of Reciprocating Masses: Inertia effect of crank and connecting rod, Single cylinder engine, balancing in multi cylinder-inline engine (primary and secondary forces), numerical problems.

Module - 3

Governors: Types of governors, force analysis of Porter and Hartnell governors. Controlling force, Stability, Sensitiveness, Isochronism, Effort and Power.

Gyroscope: Vectorial representation of angular motion, Gyroscopic couple. Effect of gyroscopic couple on plane disc, aeroplane, ship, stability of two wheelers and four wheelers, numerical problems.

Module - 4

Introduction & Undamped free Vibrations (Single Degree of Freedom)

Types of vibrations, Definitions, Simple Harmonic Motion (SHM), Work done by harmonic force, Principle of super position applied to SHM. Methods of analysis – (Newton's, Energy & Rayleigh's methods). Derivations for spring mass systems, Natural frequencies of simple systems, Springs in series and parallel, Torsional and transverse vibrations, Effect of mass of spring and problems.

Module - 5

Damped free Vibrations (Single Degree of Freedom)

Types of damping, Analysis with viscous damping - Derivations for over, critical and under damped systems, Logarithmic decrement and numerical problems.

Forced Vibrations (Single Degree of Freedom):

Analysis of forced vibration with constant harmonic excitation, Magnification factor (M.F.), Vibration isolation - Transmissibility ratio, Excitation of support (absolute and relative), Numerical problems.

Course outcomes:

1. Determine the forces and couples for static and dynamic conditions of four bar and slider crank mechanisms to keep the system in equilibrium.
2. Determine magnitude and angular position of balancing masses under static and dynamic condition of rotating masses in same and different planes.
3. Determine unbalanced primary, secondary forces and couples in single and multi-cylinder engine.
4. Determine sensitiveness, isochronism, effort and power of porter and hartnell governors.
5. Determine gyroscopic couple and effects related to 2, 4 wheeler, plane disc, ship and aeroplanes.
6. Understand types of vibration, SHM and methods of finding natural frequencies of simple mechanical systems.
7. Determine equation of motion, natural frequency, damping factor, logarithmic decrement of damped free vibration (SDOF) systems.
8. Determine the natural frequency, force and motion transmissibility of single degree freedom systems.
9. Determine equation of motion of rotating and reciprocating unbalance systems, magnification factor, and transmissibility of forced vibration (SDOF) systems.

TEXT BOOKS:

1. Theory of Machines, Sadhu Singh, Pearson Education, 2nd Edition. 2007.
2. Mechanism and Machine Theory, A. G. Ambekar PHI, 2007
3. Mechanical Vibrations, V. P. Singh, Dhanpat Rai and Company,
4. Mechanical Vibrations, G. K. Grover, Nem Chand and Bros.

REFERENCE BOOKS

1. Theory of Machines, Rattan S.S. Tata McGraw Hill Publishing Company Ltd., New Delhi, 3rd Edition, 2009.
2. Mechanical Vibrations, S. S. Rao, Pearson Education Inc, 4th edition, 2003.