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VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI-

590 018



A MICRO PROJECT REPORT ON
“An advanced alcohol sensing and engine locking system for cars”

Submitted By,

| | |
|-------------------------------|-------------------|
| K H Abdul Rajaque Shah | 4AL20CV006 |
| Pratham P | 4AL20AI031 |
| Pavan K H | 4AL20EC030 |
| Shreya P J | 4AL20CS142 |

Under the Guidance of

Dr. Jayarama A
Department of Physics



DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES


CERTIFICATE

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| K H Abdul Rajaque Shah | 4AL20CV006 |
| Pratham P | 4AL20AI031 |
| Pavan K H | 4AL20EC030 |
| Shreya P J | 4AL20CS142 |

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Dr. Jayarama A
Mini Project Guide


Dr. Ramaprasad A.T,
HOD Physics
H. O. D.
Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

This is used to detect and drive the ignition on/off relay for the drug driver control system. We have implemented an alarm system in this device that will send the car's location to the nearest police station or the driver's relatives if the alcohol level is above the normal permitted level, and the ignition system of the car will turn off after the detection.

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590 018



**A MICRO PROJECT REPORT ON
“SMART DYNAMIC INFORMATION- BASED CAR
PARKING GUIDANCE”**

Submitted By,

| | |
|------------------------------|-------------------|
| Shivakumar K N | 4AL20CV023 |
| Shailesh Rao | 4AL20AI039 |
| Anson Sarosh D' Souza | 4AL20IS006 |
| Suchith H C | 4AL20CS153 |

Under the Guidance of

**Mr. Sandeep Kumar
Department of Civil Engineering**



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ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MOODBIDRI-574225, KARNATAKA

2020-2021

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MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

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| | |
|------------------------------|-------------------|
| Shivakumar K N | 4AL20CV023 |
| Shailesh Rao | 4AL20AI039 |
| Anson Sarosh D' Souza | 4AL20IS006 |
| Suchith H C | 4AL20CS153 |

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A handwritten signature in blue ink, appearing to read "Sandeep", is written over a horizontal line.

Mr. Sandeep Kumar
Mini Project Guide

A handwritten signature in blue ink, appearing to read "R. A. T.", is written over a horizontal line.

Dr. Ramaprasad A.T,
HOD Physics

J. H. O. D.

Dept. of Physics

Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

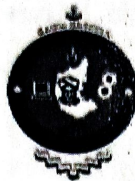
ABSTRACT

This paper focus on dynamic car parking information optimization .The large number of vehicle constantly seeking access to congested areas in cities means that finding a public parking place in often difficult and causes problems for drivers and citizen alike. To break down these problems this paper idea implemented 'DYNAMIC CAR PARKING NEGOTIATION AND GUIDANCE USING AN AGENT BASED PLATFORM'

B18

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590 018



**A MICRO PROJECT REPORT ON
“DTMF Based Home Automation”**

Submitted By,

Prajwal R

4AL20EC033

Abubakkar Siddiq

4AL20CS005

Shramik S Shetty

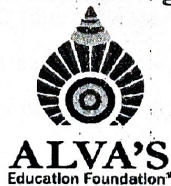
4AL20IS046

Usha G M

4AL20CS165

Under the Guidance of

**Mr. Arjun S Rao
Department of Electronics and
Communication Engineering**



DEPARTMENT OF BASIC SCIENCES

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MOODBIDRI-574225, KARNATAKA

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

This is to certify that the Micro-Project entitled **"DTMF Based Home Automation"** has been Successfully Completed by

Prajwal R

4AL20EC033

Abubakkar Siddiq

4AL20CS005

Shramik S Shetty

4AL20IS046

Usha G M

4AL20CS165

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Mr. Arjun S Rao
Mini Project Guide

Dr. Ramaprasad A.T,
HOD Physics
H. O D.

Dept. Of Physics
Alva's Institute of Engg. & Technology,
Mijar, MOODBIDRI - 574 225

ABSTRACT

In Mobile Controlled Home Automation using DTMF, a smart logic control based on embedded systems has been implemented. The DTMF based home automation is controlled by mobile signals.

Mobilecontrolled Home Automation system using DTMF technique is all about controlling a relay using DTMF decoder . The relay is controlled from a mobile phone even at a far away distance by making a call to the other mobile phone attached to the DTMF decoder in the home automation system. During the course of the call, if any button is pressed, the tone corresponding to the button pressed is heard at the other end. This tone is called "Dual Tone Multi Frequency tone (DTMF)". Using DTMF code, each relay corresponding to a particular code turns ON/OFF. The relay will be attached to a corresponding appliance at home. When each appliance needs to be turned ON , the corresponding relay needs to be ON as well. This circuit can also be used to control the water tank motor by setting the ontime.

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590 018



**A MICRO PROJECT REPORT ON
“Two-Way Wireless Anti-Theft Alarm for Two-Wheeled
Vehicles”**

Submitted By,

| | |
|----------------------------|-------------------|
| Rohan H | 4AL20EC043 |
| Adarsh Suresh Ajila | 4AL20CS009 |
| Tejas R | 4AL20IS055 |
| Varsha U K | 4AL20CS167 |

Under the Guidance of

**Mr. Pramod N
Department of Mechanical
Engineering**



**DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA**

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA




DEPARTMENT OF BASIC SCIENCES


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| | |
|----------------------------|-------------------|
| Rohan H | 4AL20EC043 |
| Adarsh Suresh Ajila | 4AL20CS009 |
| Tejas R | 4AL20IS055 |
| Varsha U K | 4AL20CS167 |

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Mr. Pramod N. 13
Mini Project Guide


Dr. Ramaprasad A.T,
HOD Physics
H. O. D.
Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

The main goal of this project is to keep track of a two-wireless wheeler's anti-theft alarm system. The proposed project is simple to use and operates effectively

Bul
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590 018



**A MICRO PROJECT REPORT ON
“SMART DYNAMIC INFORMATION- BASED CAR
PARKING GUIDANCE”**

Submitted By,

Gautham J S

4AL20AI015

Ashwini

4AL20CS025

Harsha K

4AL20AI017

Nandini S

4AL20CV011

Under the Guidance of

**Mr. Gopala Krishnna
Department of Mechanical
Engineering**



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ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA**

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MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

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Gautham J S

4AL20AI015

Ashwini

4AL20CS025

Harsha K


4AL20AI017

Nandini S

4AL20CV011

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Mr. Gopala Krishna
Mini Project Guide


Dr. Ramaprasad A.T,
HOD Physics

H.O.D.
Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

This paper focus on dynamic car parking information optimization .The large number of vehicle constantly seeking access to congested areas in cities means that finding a public parking place in often difficult and causes problems for drivers and citizen alike. To break down these problems this paper idea implemented 'DYNAMIC CAR PARKING NEGOTIATION AND GUIDANCE USING AN AGENT BASED PLATFORM'.

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590 018



**A MICRO PROJECT REPORT ON
“Detection of Speed of Vehicles”**

Submitted By,

| | |
|------------------------------|-------------------|
| Tarun D R | 4AL20AI046 |
| Bugade Poonam Gajanan | 4AL20CS031 |
| Prajwal P Paveseekar | 4AL20AI028 |
| Priyanka Malagitti | 4AL20CV016 |

Under the Guidance of

**Ms. Sowmya
Department of Mathematics**



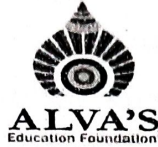
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ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
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ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

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This is to certify that the Micro-Project entitled “Detection of Speed of Vehicles” has been Successfully Completed by

Tarun D R

4AL20AI046

Bugade Poonam Gajanan

4AL20CS031

Prajwal P Paveseekar

4AL20AI028

Priyanka Malagitti

4AL20CV016

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Ms. Sowmya
Mini Project Guide

Dr. Ramaprasad A.T,
HOD Physics

H.O.D.

Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

India is the country with the highest number of road fatalities, the most of which are caused by excessive speeding. There have been numerous attempts to develop reliable and effective methods of detecting overspeeding automobiles. One such device is a hand held over a speeding detector. The problem of such a gadget was that it was bulky and operated only with professional hands; also, by the time a speed reading was received, the vehicle would have already left.

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590 018



**A MICRO PROJECT REPORT ON
“USING LOOP DETECTORS CONTROLLING TRAFFIC
LIGHT”**

Submitted By,

Abhiram H A

4AL20CS002

Shwetha C

4AL20CS032

Prasanna Narayana P

4AL20AI030

Sandeep

4AL20CV021

Under the Guidance of

**Dr. Ramaprasad A.T
Department of Physics**



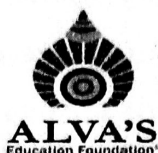
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MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

This is to certify that the Micro-Project entitled **“USING LOOP DETECTORS CONTROLLING TRAFFIC LIGHT”** has been Successfully Completed by

Abhiram H A

4AL20CS002

Shwetha C

4AL20CS032

Prasanna Narayana P


4AL20AI030

Sandeep

4AL20CV021

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Dr. Ramaprasad A.T
Mini Project Guide


Dr. Ramaprasad A.T,
HOD Physics
H. O. D.
Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

Loop detectors ensure that traffic lights are controlled accurately and reliably. Each lane has two inductive loop detectors, one before and one after the stop line. Every passing car is tracked and recorded. It is possible to set a delay time. After that time, any car that passes is photographed twice in quick succession. The first shot depicts the crime, while the second indicates that the vehicle was in motion. The camera is set up in such a way that the red light can be seen in the image. Cars and trucks are distinguished through loop detection. For each category, a distinct speed threshold can be installed. When the lights are green, red, or amber, the traffic signal cameras can also be used to measure speed.

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590 018



**A MICRO PROJECT REPORT ON
“Automatic overspeed detector”**

Submitted By,

| | |
|------------------------|-------------------|
| Shivaprasad H S | 4AL20CS136 |
| Hemanth B | 4AL20CS047 |
| B Sai Shreya | 4AL20CS027 |
| Disha H | 4AL20EC012 |

Under the Guidance of

**Mr. Arjun S Rao
Department of Electronics and
Communication Engineering**



**DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA**

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

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| | |
|------------------------|-------------------|
| Shivaprasad H S | 4AL20CS136 |
| Hemanth B | 4AL20CS047 |
| B Sai Shreya | 4AL20CS027 |
| Disha H | 4AL20EC012 |

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Mr. Arjun S Rao
Mini Project Guide

Dr. Ramaprasad A.T,
HOD Physics

H. O. D.

Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

In this project we developed a prototype sleek hand held device that can be operated by the traffic official whenever he observes an over speeding vehicle, to obtain the correct speed of the vehicle. It has a 2 digit 7-segment display, which can display speeds up to 97km/h. It also has two switches, which are used for starting the device and for enabling it only when required. The state of the device is indicted by three status indicating LEDs which display the following conditions: a green LED indicating power on, an orange LED indicating the set or enabled condition, and a red LED indicating speeds in excess of 100 km/h.

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590 018



**A MICRO PROJECT REPORT ON
“Automated Charging Machine(ACM)”**

Submitted By,

| | |
|----------------------|-------------------|
| Harshitha D K | 4AL20EC013 |
| Ishwar Pavan | 4AL20CS050 |
| Ikshu B A | 4AL20CS048 |
| Kishan Kumar | 4AL20EC017 |

Under the Guidance of

**Mr. Pramod V B
Department of Mechanical
Engineering**



**DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA**

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA




DEPARTMENT OF BASIC SCIENCES


CERTIFICATE

This is to certify that the Micro-Project entitled "Automated Charging Machine(ACM)" has been Successfully Completed by

| | |
|---------------|------------|
| Harshitha D K | 4AL20EC013 |
| Ishwar Pavan | 4AL20CS050 |
| Ikshu B A | 4AL20CS048 |
| Kishan Kumar | 4AL20EC017 |

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Mr. Pramod V B
Mini Project Guide


Dr. Ramaprasad A.T,
HOD Physics
H. O. D.
Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

This project is related to ACM which provides the public with the ability to recharge a mobile device ,often for a small fee. Similar to vending machines , ACM's take cash ,then charge the connected devices. Basically we use PC RS232 Communication. These places include Airports, Shopping malls,parks, clubs, Supermarkets, Campuses and other popular locations. Public charging stations for mobile devices appeared around 2006. A variety of features have been introduced to these machines, including lockers, U V sanitation and wirelessly updated advertising space.

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VISVESVARAYA TECHNOLOGICAL UNIVERSITY,BELAGAVI-

590 018



**A MICRO PROJECT REPORT ON
“GSM MODULE IN REMOTE ELECTRICAL LOADS
CONTROL”**

Submitted By,

| | |
|-----------------------------|-------------------|
| Pratham | 4AL20EC035 |
| Jayesh Lokesh Korade | 4AL20CS054 |
| Priyanka Venkanna K | 4AL20CS100 |
| Prashanth V K | 4AL20EC034 |

Under the Guidance of

**Dr. Ravi Kumar
Department of Chemistry**



**DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA**

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA




DEPARTMENT OF BASIC SCIENCES


CERTIFICATE

This is to certify that the Micro-Project entitled **"GSM MODULE IN REMOTE ELECTRICAL LOADS CONTROL"** has been Successfully Completed by

| | |
|-----------------------------|-------------------|
| Pratham | 4AL20EC035 |
| Jayesh Lokesh Korade | 4AL20CS054 |
| Priyanka Venkanna K | 4AL20CS100 |
| Prashanth V K | 4AL20EC034 |

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Dr. Ravi Kumar
Mini Project Guide


Dr. Ramaprasad A.T,
HOD Physics
H.O.D.
Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

This project has low cost solution to Remote Control and Monitoring via your mobile phone. It had 2 output relay and 4 input colsure contect. Lighting,central heating boiker,pumps etc are controled by using output and input can be connected thermostats,security Sensors and flood detectors.

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590 018



**A MICRO PROJECT REPORT ON
“CELLPHONE OPERATED ROBOT”**

Submitted By,

| | |
|----------------------|-------------------|
| Shubhashri S | 4AL20EC052 |
| Karthikeyan J | 4AL20CS056 |
| Rachith M R | 4AL20CS105 |
| Preeti G M | 4AL20EC038 |

Under the Guidance of

Mr. G. B Vaggar
Department of Mechanical
Engineering



DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA

2020-2021

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MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

This is to certify that the Micro-Project entitled "CELLPHONE OPERATED ROBOT" has been Successfully Completed by

Shubhashri S

4AL20EC052

Karthikeyan J

4AL20CS056

Rachith M R

4AL20CS105

Preeti G M

4AL20EC038

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Mr. G. B Vaggar
Mini Project Guide

Dr. Ramaprasad A.T,

HOD Physics

H. O. D.

Dept. Of Physics

Alva's Institute of Engg. & Technology,

Mijar, MOODBIDRI - 574 225

ABSTRACT

The use of radio signals to remotely control a device is known as radio control (abbreviated as R/C or simply RC). The word is widely used to refer to the use of a hand-held radio transmitter to operate miniature automobiles. Radio-controlled cars are also used in [traffic] by industrial, military, and scientific research organisations.

Any mobile device that is operated by a means that does not restrict its motion with an origin external to the device is referred to as a remote control vehicle. A radio control device, a cable between the control and the vehicle, an infrared controller are common examples.

A remote control vehicle (also known as an RCV) varies from a robot in that it is always controlled by a person and does not take any positive action on its own. Remote vehicle control is one of the major technologies that underpins this sector. A vehicle must be capable of travelling accurately to a target location, navigating inside that region to complete its task, and returning to base with the same accuracy and safety

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VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI-

590 018



**A MICRO PROJECT REPORT ON
“GESTURE CONTROLLED ROBOTIC ARM”**

Submitted By,

| | |
|----------------------|-------------------|
| Ashwini | 4AL20IS007 |
| Keerthi R | 4AL20CS060 |
| Rasi K S | 4AL20CS114 |
| Sakshath Jain | 4AL20EC044 |

Under the Guidance of

Dr. Jayarama A
Department of Physics



DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA

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| | |
|---------------|------------|
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| Keerthi R | 4AL20CS060 |
| Rasi K S | 4AL20CS114 |
| Sakshath Jain | 4AL20EC044 |

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Mini Project Guide

Dr. Ramaprasad A.T,
HOD Physics
H. O. D.

Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

In this micro-project we developed an trainable remotely controlled robotic arm using DC motors. we prepared robotic arm which will perform primary pick and place operations and we can also save the movements of the arm and repeat the recorded actions without any error corrections. This arm has an 360 degrees of actions . The robotic arm is mounted on a base that allows it to perform different coordinates. we used Arduino Mega 2560 for controlling functionalities of the robot. we prepared this robot in two stages. In the first stage, the robot will be controlled with the help of potentiometer and in the second stage of development, remote functionality was added. we prepared this arm with the functionality by which the arm is controlled by the Bluetooth also. so it will make our daily life easy, better and simple.

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590 018



**A MICRO PROJECT REPORT ON
“Anti-lock brakes with traction control at a low cost”**

Submitted By,

| | |
|-----------------------------|-------------------|
| Finny Paul | 4AL20IS018 |
| Laxmish Vishnu Hegde | 4AL20CS064 |
| Shravika I P | 4AL20CS141 |
| Shwetha | 4AL20EC053 |

Under the Guidance of

**Mr. Gopala Krishnna
Department of Mechanical
Engineering**



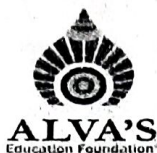
**DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA**

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

This is to certify that the Micro-Project entitled “**Anti-lock brakes with traction control at a low cost**” has been Successfully Completed by

| | |
|-----------------------------|-------------------|
| Finny Paul | 4AL20IS018 |
| Laxmish Vishnu Hegde | 4AL20CS064 |
| Shravika I P | 4AL20CS141 |
| Shwetha | 4AL20EC053 |

The bonafide students of **Department of Basic Sciences, Alva's Institute of Engineering and Technology**, affiliated to **VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI**, during the academic year 2020–2021. It is certified that all corrections/suggestions indicated for Internal Assessment have been incorporated in the report. The report has been approved as it satisfies the academic requirements in respect of Micro-Project work prescribed for Bachelor of Engineering.

Mr. Gopala Krishnna
Mini Project Guide

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HOD Physics

H.O.D.
Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

In this project we created a traction control system that detects wheel slip and adjusts the wheel velocity as needed. Robotic vehicles are growing more complicated, and high levels of movement control are frequently required. When a vehicle's wheels start to slip, it's best to modify the speed of the wheels so that the vehicle moves in the desired direction.

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590 018



**A MICRO PROJECT REPORT ON
“Efficient Power Manager Project”**

Submitted By,

Sujan PS

4AL20IS051

Arpitha

4AL20CS073

Aravinda

4AL20EC006

Keerthana G

4AL20IS020

Under the Guidance of

**Dr. Ramaprasad A.T
Department of Physics**



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MOODBIDRI-574225, KARNATAKA

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

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Sujan PS

4AL20IS051

Arpitha

4AL20CS073


Aravinda


4AL20EC006

Keerthana G

4AL20IS020

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Dr. Ramaprasad A.T
Mini Project Guide


Dr. Ramaprasad A.T,
HOD Physics

H.O.D.

Dept. Of Physics
Alva's Institute of Engg. & Technology
Mijar, MOODBIDRI - 574 225

ABSTRACT

The technology is designed to use the least amount of energy possible by keeping track of the number of people in the space. When someone enters the room, the electric loads are turned on, and they are turned off when no one is present. In order to accomplish this, the system employs Infrared Sensor pairs, which saves a significant amount of energy. Each pair consists of two sensor pairs set in opposing directions at a certain distance from one another. The IR transmitter sends infrared rays directly to the receiver, which receives the signal and passes it to an 8051 microcontroller. The IR sensor module detects when a person enters the room and sends this information to the microcontroller. This input is processed by the microcontroller, which then turns on the load. The system also counts the number of persons present at this time and increments a counter with each arrival; this count is displayed on a 7-segment display. The sensor detects no presence when the last person leaves the room and so turns off the load/lamp. To demonstrate as a burden, a tiny lamp is employed.

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590 018



**A MICRO PROJECT REPORT ON
“AC Power Strength Controller System”**

Submitted By,

| | |
|--------------------------|-------------------|
| Akshar N | 4AL20ME002 |
| Mohammed Fahiz | 4AL20CS076 |
| Chaithrashree M G | 4AL20EC008 |
| Nayana T | 4AL20IS028 |

Under the Guidance of

**Dr. Ravi Kumar
Department of Chemistry**



**DEPARTMENT OF BASIC SCIENCES
ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY
MOODBIDRI-574225, KARNATAKA**

2020-2021

ALVA'S INSTITUTE OF ENGINEERING AND TECHNOLOGY

MIJAR, MOODBIDRI D.K. -574225

KARNATAKA



DEPARTMENT OF BASIC SCIENCES

CERTIFICATE

This is to certify that the Micro-Project entitled “AC Power Strength Controller System” has been Successfully Completed by

| | |
|--------------------------|-------------------|
| Akshar N | 4AL20ME002 |
| Mohammed Fahiz | 4AL20CS076 |
| Chaithrashree M G | 4AL20EC008 |
| Nayana T | 4AL20IS028 |

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A handwritten signature in blue ink, appearing to be "Ravi Kumar", written over a horizontal line.

Dr. Ravi Kumar
Mini Project Guide

A handwritten signature in blue ink, appearing to be "Ramaprasad A.T.", written over a horizontal line.

Dr. Ramaprasad A.T,
HOD Physics
H. O. D.

Dept. Of Physics
Alva's Institute of Engg. & Technology
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ABSTRACT

The project's purpose is to manage AC power using the concept of thyristor firing angle control. The required proportion of power supply can be entered using a keypad. The data is delivered to an 8051 microcontroller, which initiates the firing angle and changes the load power. To match the power to the needed one, a TRIAC is used in series with the AC load. An LCD panel shows the percentage of power delivered by the user.