VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI
SCHEME OF TEACHING AND EXAMINATION 2017-2018

B.E. Mechatronics Engineering

CHOICE BASED CREDIT SYSTEM (CBCS)

III SEMESTER

Sl. No.	Subject Code	Title	Teaching Department	Teaching Hours /Week			Examination				Credit s
				Lecture	Tutorial	Practical	Duration (Hours)	SEE Marks	CIE Marks	Total Marks	
1	17MAT31	Engineering Mathematics – III	MATHS	04	01		03	60	40	100	4
2	17MT32	Material Science& Technology	MT	04			03	60	40	100	4
3	17MT33	Mechanics of Materials	MT	03	02		03	60	40	100	4
4	17MT34	Control Systems	MT	03	02		03	60	40	100	4
5	17MT35	Analog and Digital Electronics	MT	03	02		03	60	40	100	4
6	17MT36	Computer Organization	MT	04		4	03	60	40	100	3
7	17MTL37	Machine shop and Material Testing Lab	MT	1		2	03	60	40	100	2
8	17MTL38	Analog And Digital Electronics Lab	MT	1		2	03	60	40	100	2
9	17KL/CP H39/49	Kannada/Constitution of India, Professional Ethics and Human Rights	Humanities	1			01	30	20	50	1
TOTAL				**25**	**07**	**08**		**510**	**340**	**850**	**28**

VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI
SCHEME OF TEACHING AND EXAMINATION 2017-2018

B.E. Mechatronics Engineering

CHOICE BASED CREDIT SYSTEM (CBCS)

IV SEMESTER

Sl. No	Subject Code	Title	Teaching Department	Teaching Hours /Week			Examination				Credits
				Lect	Tuto	Practical	Duration (Hours)	SEE Marks	CIE Marks	Total Marks	
1	17MAT41	Engineering Mathematics – III	Maths	04	01		03	60	40	100	04
2	17MT42	Fluid Mechanics and Machines	MT	03	02		03	60	40	100	04
3	17MT43	Micro Controller	MT	03	02		03	60	40	100	04
4	17MT44	Manufacturing Technology	MT	04			03	60	40	100	04
5	17MT45	Theory of Machines	MT	03	02		03	60	40	100	04
6	17MT46	Instrumentation and Measurement	MT	04			03	60	40	100	03
7	17MTL47	Fluid Mechanics, Machines and Pneumatic Lab	MT	1		2	03	60	40	100	02
8	17MTL48	Micro Controller Lab	MT	1		2	03	60	40	100	02
9	17KL/CPH39/49	Kannada/Constitution of India, Professional Ethics and Human Rights	Humanities	1			01	30	20	50	1
TOTAL				**24**	**07**	**04**		**510**	**340**	**850**	**28**

VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI
SCHEME OF TEACHING AND EXAMINATION 2017-2018

B.E. Mechatronics Engineering

CHOICE BASED CREDIT SYSTEM (CBCS)

V Semester

Sl. No.	Subject Code	Title	Teaching Hours /Week			Examination				Credits
			Lecture	Tutorial	Practical	Duration (Hours)	SEE Marks	CIE Marks	Total Marks	
1	17MT51	Design Of Machine Elements	3	2	0	03	60	40	100	4
2	17MT52	Virtual Instrumentation	4	0	0	03	60	40	100	4
3	17MT53	Hydralics and Pneumatics	4	0	0	03	60	40	100	4
4	17MT54	Micro and Smart Systems Technology	4	0	0	03	60	40	100	4
5	17MT55X	Professional Elective-I	3	0	0	03	60	40	100	3
6	17MT56X	Open Elective-I	3	0	0	03	60	40	100	3
7	17MTL57	Virtual Instrumentation Lab	1	0	2	03	60	40	100	2
8	17MTL58	Micro and Smart Systems Technology Lab	1	0	2	03	60	40	100	2
TOTAL			**23**	**02**	**04**	**24**	**480**	**320**	**800**	**26**

Professional Elective-I		Open Elective-I	
17MT551	Wireless Networks & Communication	17MT561	Mechatronics Engineering
17MT552	Operations Research	17MT562	Automation in Manufacturing
17MT553	Linear Integrated Circuits		
17MT554	Drives and Controls		

1. **Core subject:** This is the course, which is to be compulsorily studied by a student as a core requirement to complete the requirement of a programme in a said discipline of study.
2. **Professional Elective:** Elective relevant to chosen specialization/ branch
3. **OpenElective**: Electives from other technical and/or emerging subject areas.

VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI
SCHEME OF TEACHING AND EXAMINATION 2017-2018

B.E. Mechatronics Engineering

CHOICE BASED CREDIT SYSTEM (CBCS)

VI SEMESTER

Sl. No	Subject Code	Title	Teaching Hours /Week			Examination				Credits
			Lecture	Tutorial	Practical	Duration (Hours)	SEE Marks	CIE Marks	Total Marks	
1	17MT61	PLC & SCADA	4	0	0	03	60	40	100	4
2	17MT62	Embedded Systems (ARM)	4	0	0	03	60	40	100	4
3	17MT63	Power Electronics	3	2	0	03	60	40	100	4
4	17MT64	Computer Aided Machine Drawing	2	0	4	03	60	40	100	4
5	17MT65X	Professional Elective-II	3	0	0	03	60	40	100	3
6	17MT66X	Open Elective-II	3	0	0	03	60	40	100	3
7	17MTL67	PLC & SCADA Lab	1	0	2	03	60	40	100	2
8	17MTL68	Power Electronics Lab	1	0	2	03	60	40	100	2
TOTAL			**21**	**2**	**08**		**480**	**320**	**800**	**26**

Professional Elective-II		Open Elective-II	
17MT651	Modeling And Simulation	17MT661	Robotics and Automation
17MT652	Rapid Prototyping	17MT662	Process Instrumentation
17MT653	Mechanical Vibration		
17MT654	Satellite Communication		
17MT655	Computer Integrated Manufacturing		

1. **Core subject:** This is the course, which is to be compulsorily studied by a student as a core requirement to complete the requirement of a programme in a said discipline of study.
2. **Professional Elective:** Elective relevant to chosen specialization/ branch
3. **Open Elective**: Electives from other technical and/or emerging subject areas.

VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI
SCHEME OF TEACHING AND EXAMINATION 2017-2018

B.E. Mechatronics Engineering

CHOICE BASED CREDIT SYSTEM (CBCS)

VII SEMTSTER

Sl. No	Subject Code	Title	Teaching Hours /Week			Examination				Credits
			Lecture	Tutorial	Practical	Duration (Hours)	SEE Marks	CIE Marks	Total Marks	
1	17MT71	Industrial Robotics	4		0	03	60	40	100	4
2	17MT72	Thermal Engineering	3	2	0	03	60	40	100	4
3	17MT73	Signal Process	3	2	0	03	60	40	100	4
4	17MT74X	Professional Elective-III	3	0	0	03	60	40	100	3
5	17MT75X	Professional Elective-IV	3	0	0	03	60	40	100	3
6	17MTL76	Robotics Lab	1	0	2	03	60	40	100	2
7	17MTL77	Signal Process - Lab	1	0	2	03	60	40	100	2
8	17MTP78	Project Phase – I Seminar	-	-	-	-	-	100	100	2
TOTAL			**18**	**4**	**04**		**420**	**380**	800	**24**

Professional Elective			
17MT741	Automation In Process Control	17MT751	Biomedical Signal Processing
17MT742	Nano Technology	17MT752	Machine Learning
17MT743	Real Time Systems	17MT753	Safety and Security of Automotive Systems
17MT744	OOPS using C++	17MT754	Digital Image Processing
17MT745	Analytical Instrumentation	17MT755	Artificial Neural Networks

1. **Core subject:** This is the course, which is to be compulsorily studied by a student as a core requireMTnt to complete the requireMTnt of a programMT in a said discipline of study.
2. **Professional Elective:** Elective relevant to chosen specialization/ branch

VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI
SCHEME OF TEACHING AND EXAMINATION 2017-2018

B.E. Mechatronics Engineering

CHOICE BASED CREDIT SYSTEM (CBCS)

VIII SEMESTER

Sl. No	Subject Code	Title	Teaching Hours /Week			Examination				Credits
			Lecture	Tutorial	Practical	Duration (Hours)	SEE Marks	CIE Marks	Total Marks	
1	17MT81	Automotive Electronics & Hybrid Vehicles	3	2	0	03	60	40	100	4
2	17MT82	Communication System	4	0	0	03	60	40	100	4
3	17MT83X	Professional Elective-V	3	0	0	03	60	40	100	3
4	17MT84	Internship/Professional Practice	Industry Oriented			03	50	50	100	**4**
5	17MTP85	Project Work	-	6	-	03	100	100	200	6
6	17MTS86	Seminar	-	4	-	-	-	100	100	1
TOTAL			**10**	**12**	**-**		**330**	**370**	**700**	**22**

Professional Elective-V	
17MT831	Product Design and Development
17MT832	Artificial Intelligence
17MT833	Digital Control System
17MT834	Management Information Systems
17MT835	Radar Engineering

1. **Core subject:** This is the course, which is to be compulsorily studied by a student as a core requirement to complete the requirement of a programme in a said discipline of study.
2. **Professional Elective:** Elective relevant to chosen specialization/ branch
   Internship / Professional Practice: To be carried out between 6^{th}& 7^{th} semester vacation or 7^{th}& 8^{th} semester vacation.

MATERIAL SCIENCE AND TECHNOLOGY
B.E, III Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT32**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

1. gain knowledge of Mechanical behavior of metals, composite materials and smart materials
2. understand the mechanism of metallurgical process, manufacturing process of composites and working of smart sensors
3. know applications of metallurgical process, production process of composites and smart materials for various engineering solutions.

Module - 1

Mechanical Behavior : Stress- Strain diagram showing ductile and brittle behavior of materials, Liner and non-linear elastic behavior and properties, mechanical Properties in plastic range, Yield strength offset yield strength, ductility, ultimate tensile strength, toughness plastic deformation of single crystal by slip and twinning.
Atomic diffusion, flick's laws of Diffusion, Factors attaching the Diffusion

Fracture: Types, creep: Description of the phenomenon with examples, 3 stages of creep properties, stress relaxation fatigue: types of fatigue lauding with examples, Mechanism of fatigue, Fatigue properties, Fatigue testing and S-N diagram.

Module - 2

Heat Treating of metals: TTT curves, Continuous cooling curves, Annealing and its types, Normalizing, Hardening, Tempering, Martempering, Austemparing, hardenability, Surface hardening methods like Carburizing, Cyaniding Nitriding, flame hardening and induction hardening, age hardening of aluminum and copper alloys.

Ferrous and non ferrous materials: Properties composition and use of grey cush iron, malleable iron, SG iron and steel. Copper alloys- brasses and bronzes, aluminum alloys Al-Cu, Al-Si, Al-Zn alloys.

Module - 3

Solidification and phase diagram: Mechanism of solidification, Homogenous and Heterogeneous nucleation. Cristal Growth, Cast metal strictures, Phase diagram. Solid solutions
Substitution and Interstitial solid solution, Hume rothary rule, Intermediate phase, construction of equilibrium diagram involving complete and partial solubility, lever rule, Gibb's phase rule.

Module - 4

Composite materials: Definition, classification, type of matrix materials and reinforcements, advantages and application of composites**.**

Processing of FRP Composites: Layup and curing, fabricating process, open and closed mould process, hand layup technique; structural laminate bag molding, production procedures for bag molding; filament winding, pultrusion, pulforming, thermo-forming, injection molding, blow molding.

Metal Matrix Composites: Reinforcement materials, types, characteristics and selection, base metals selection. Need for MMC's and its application.

Module - 5

Smart Materials: Piezoelectric Materials, Electrostrictive Materials, Magnetostrictive Materials, Magnetoelectric Materials. Magnetorheological Fluids, Electrorheological Fluids, Shape Memory Materials, Fiber-Optic Sensors.

Smart Sensor, Actuator and Transducer Technologies: Smart Sensors: Accelerometers; Force Sensors; Load Cells; Torque Sensors; Pressure Sensors; Microphones; Impact Hammers

Course outcomes:

At the end of the course, the students will:

CO1:have knowledge of -Mechanical behavior of metals, Smart materials, composite materials, Alloys, Heat treatment process & phase diagrams. CO2:understand the mechanism of various Metallurgical process & manufacturing process of composite materials & working of smart sensors,. CO3:application of metallurgical process, production process of composite & working principle of smart sensor for various engineering solutions.

TEXT BOOKS:

1. Materials Science and Engineering,William D. Callister Jr., John Wiley & Sons. Inc, 5th Edition, 2001.
2. Mechanics of Composite Materials, Second Edition, Autar K. Kaw, CRC Press, 2005.
3. Smart Materials and Structures - M. V. Gandhi and B. So Thompson - Chapman & Hall, London; New York - 1992 (ISBN: 0412370107).
4. Materials Science and Engineering,William D. Callister Jr., John Wiley & Sons. Inc, 5th Edition, 2001
5. Materials Science, Shackleford.,& M. K. Muralidhara, Pearson Publication – 2007.
6. "Material Science & Metallurgy For Engineers", Dr. V.D. Kodgire& S. V. Kodgire, Everest Publication.
7. "Mechanical Behavior & Testing Of Materials", A. K. Bhargava, C.P. Sharma.P H I Learning Private Ltd.

REFERENCE BOOKS

1. An Introduction to Metallurgy; Alan Cottrell, Universities Press India Oriental Longman Pvt. Ltd., 1974.
2. Engineering Materials Science, W.C.Richards, PHI, 1965
3. Physical Metallurgy; Lakhtin, Mir Publications
4. Materials Science and Engineering, V.Raghavan,PHI, 2002
5. Elements of Materials Science and Engineering, H. VanVlack, Addison- Wesley Edn., 1998
6. Materials Science and Engineering,William D. Callister Jr., John Wiley & Sons. Inc, 5th Edition, 2001.
7. The Science and Engineering of Materials, Donald R. Askland and Pradeep.P. Phule, Cengage Learning, 4th Ed., 2003.

MECHANICS OF MATERIALS
B.E, III Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT33**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**05**	**SEE Marks**	**60**
Total Number of Lecture Hours	**60(12 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

- 1. gain knowledge of linear elastic properties stress strain relations
- 2. derive the stress strain equations in bars, beams, shafts, cylinders, columns subjected to external load.
- 3. compute the stress strain for bars, beams, shafts, and column

Module - 1

Simple Stress and Strain: Introduction, Concept of Stress and Strain, Linear elasticity, Hooke's Law and Poisson's ratio. Extension / Shortening of a bar, bars with varying cross sections (step and tapering circular and rectangular), Elongation due to self weight, Principle of super position, St. Venant's Principle.

Simple shear stress and Shear strain. Volumetric strain: expression for volumetric strain, Elastic Constants and relations. Stresses in Composite Section.

Module - 2

Compound Stresses: Introduction, Concept of Plane stress, Stress tensor for plane stress, stresses on inclined sections, principal stresses and maximum shear stresses, Mohr's circle for plane stress.

Module - 3

Bending Moment and Shear Force in Beams: Introduction, Sign conventions, relationship between shear force and bending moments. Shear force and bending moment diagrams for Cantilever, simply supported and overhanging beams subjected to concentrated loads, uniformly distributed load
(UDL), uniformly varying load (UVL) and couple, simple numerical.

Module – 4

Bending and Shear Stresses in Beams: Introduction, Theory of simple bending, assumptions in simple bending. General equation for bending. Moment carrying capacity of a section. Shearing stresses in beams, shear stress across rectangular, symmetrical I and T sections. (Composite / notched beams not included).

Deflection of Beams: Introduction, Differential equation for deflection. Equations for deflection, slope and bending moment. Double integration method for cantilever and Macaulay's method for simply supported beams for point load, UDL and Couple. (Simple Numericals)

Module – 5

Torsion of Circular Shafts: Introduction. Pure torsion, assumptions, derivation of torsional equations, polar modulus, torsional rigidity / stiffness of shafts. Power transmitted by solid and hollow circular shafts.

Elastic Stability of Columns: Euler's theory for axially loaded elastic long columns. Derivation of Euler's load for various end conditions, limitations of Euler's theory, Rankine's formula.

Course outcomes:

At the end of the course, the student will be able to:

CO1: Have knowledge of stress-strain relations in linear elastic members
CO2: Describe stress- strain equation for axial, bending and torsion loads.
CO3: Determine the stress & strain for simple stresses, compound stresses, beams, shafts & columns.

TEXT BOOKS:

1. "Mechanics of Materials", by R.C.Hibbeler, Prentice Hall. Pearson Edu., 2011.
2. "Mechanics of materials", James.M.Gere, Thomson, Eighth edition2013.
3. "Mechanics of materials", in SI Units, Ferdinand Beer & Russell Johston, 5th Ed., TATA McGraw Hill- 2003.
4. "Mechanics of Materials", K.V. Rao, G.C. Raju, Subhash Publication, Fourth Edition, 2013

REFERENCE BOOKS

1. "Strength of Materials", S.S. Rattan, Tata McGraw Hill, 2009.
2. "Strength of Materials", S.S.Bhavikatti, Vikas publications House -1 Pvt. Ltd., 2nd Ed., 2006.
3. "Engineering Mechanics of Solids", Egor.P. Popov, Pearson Edu. India, 2nd, Edition, 1998.
4. "Strength of Materials", W.A. Nash, 5th Ed., Schaum's Outline Series, Fourth Edition-2007.

CONTROL SYSTEMS
B.E, III Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT34**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will have to

□□knowledge of fundamental concepts of Control systems, mathematical modeling of the system and to study
□□expose to the knowledge of the concept of time response and frequency response of the system and teach the basics of stability analysis time response and frequency response of the system of the system.
□□study stability of System

Module – 1

Modeling of Systems and Block diagram: Introduction to Control Systems, Types of Control Systems, with examples. Concept of mathematical modeling of physical systems- Mechanical, Translational (Mechanical accelerometer, systems excluded), and Rotational systems, Analogous systems based on force voltage analogy and force current analogy. Introduction to Block diagram algebra. Numerical problems on all topics.

Module – 2

Signal Flow graph: Introduction to Signal Flow graph, Mason's gain formula. Obtaining Transfer functions for the given SFG using Mason's gain formula. **Time response analysis:** Introduction. Standard test signals, response of first order & second order systems for unit step input. Steady state errors & Error constants. Numerical problems on all topics.

Module – 3

Concepts of stability: The Concept of stability. Necessary conditions for stability. Hurwitz stability criterion. Routh stability criterion. Relative stability analysis using RH Criterion.
The Root Locus Technique: Introduction. Root locus concepts. Construction of root loci. Stability analysis using Root locus Technique Numerical problems on all topics.

Module – 4

Frequency domain Analysis: Introduction to frequency domain analysis, Correlation between time & frequency response, Bode plots.
Polar Plot: Introduction to Polar plot and Nyquist plots, Nyquist stability criterion. Stability analysis using Polar plot. Numerical problems on all

Module – 5

State space Analysis: Concept of state, state variables and state model. State diagrams and State models for Linear continuous-time systems (Electrical systems): State space representation using Physical and Phase variables. Derivation of transfer functions from the state model. Numerical problems on all topics.
Solution of state equations: Solutions of homogeneous and Nonhomogeneous state equations. Properties of state transition matrix, computation of state transition matrix by matrix exponential and Laplace transform method. Numerical problems

Course outcomes:

After studying this course, students will:

CO1: have knowledge of types of control systems, mathematical modeling of physical systems(Mechanical and Electrical System)

CO2: apply the Modeling system for physical systems and carry out stability analysis in time and frequency domain

CO3: analysis of time and frequency domain for Stability of System & Design the system for the desired operating conditions

TEXT BOOKS:

1. "Control Systems Engineering", I.J. Nagarath and M. Gopal ,New Age International (P) Limited, Publishers, Fifth edition – 2012.

2. "Modern Control Engineering ", K. Ogata, Pearson Education Asia/ PHI, 4th Edition, 2002.

REFERENCE BOOKS:

1. "Automatic Control Systems", Benjamin C. Kuo, John Wiley India Pvt. Ltd., 8th Edition, 2008. 2. "Feedback and Control System", Joseph J Distefano III et al., Schaum's Outlines, TMH, 2nd Edition 2007

ANALOG & DIGITAL ELECTRONICS
B.E, III Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT35**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: student will be able to

- gain knowledge of Analog & Digital Electronic Circuits.
- understand the behavior of Electronic Circuits.
- derive the relations for Voltage Gain ,Frequency of Various Electronics Circuits
- design Electronics Systems for various Applications.

Module – 1

Op-Amp active filters : Introduction**,** Active filters, I order low pass filter: Design, frequency scaling, II order low pass filter: Design, I order high pass filters: Design, II order high pass filters: Design, wide Band pass filter, Narrow band pass filter, and Band reject filter: wide Band reject filter, Narrow band reject filter, All pass filter.

Module - 2

Oscillators and Comparators: Principles, Types, Frequency Stability**,** phase shift oscillator, wein bridge oscillator.
Comparators: Basic comparators, zero crossing detector, schimitt trigger, problems.

Module - 3

555 timers and Its applications: Introduction, the 555 timer pin diagram, architecture of 555 timers, 555 timer as monostable multivibrator, 555 timer as astable multivibrator, applications of astable multivibrator. Problems.

Module - 4

Combinational Logic: Introduction to K-Maps: 2,3 and 4 variable maps**,** Adders: Half adder and Full adder, subtractor: half subtractor and full subtractor multiplexers: 4:1 multiplexer, quadruple 2 to 1 line multiplexer, Boolean function implementation, demultiplexers: 1:4 demux, implementation using decoder, encoders: Octal to binary encoder, decoders: 3 to 8 line decoder, BCD to Decimal decoder.

Module - 5

Sequential Logic: Introduction**,** Flip flops: Basic circuits, RS flip flop, D-flipflop, clocked D-flipflop, JK flip flop, clocked JK flipflop, T-flipflop, clocked T flipflop, Counters: Binary Ripple counter, BCD ripple counter, synchronus counter: Binary up-down counter, Binary counter.

Course outcomes:
By the end of the course the student will be able to:

1. have knowledge of Analog & Digital Electronic Circuits.
2. understand the characteristics & operation of Electronic Circuits.
3. formulate the relations for Voltage Gain ,Frequency of Various Electronics Circuits.
4. design the Electronics Systems for Required Specifications

TEXT BOOKS:

1. "Opamp and Linear Integrated Circuits", Ramakant A Gayakwad 3rd edition, PHI.
2. "Digital Logic and Computer Design", M Morris Mano, 2000 edition, PHI.

REFERENCE BOOKS:

1. **"Digital Electronics: Principles and Integrated cir cuits", Anil K Maini, 2008, wiley India.**
2. **"Linear Integrated Circuits", D. Roy Choudhury and Shail B Jain, 2nd edition, Reprint 2006, New Age International.**
3. **"Digital Principles and applications", Malvino & Leach, Tata Mc. Graw Hill.**

Computer Organization
B.E, III Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT36**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives:
This course enables students to:

- understand basic structure of computers, machine instructions and programs, different addressing modes, output operations, Stacks and Queues, Subroutines and Additional Instructions, IEEE standard for Floating point Numbers.
- Understand the accessing of I/O Devices, Interrupts, Direct Memory Access, Busses, Interface Circuits, and Standard I/O Devices.
- Gain the concepts of Semiconductor RAM Memories, Read Only Memories, Cache Memories, Performance Considerations and Virtual Memories.

Module - 1

Basic Structure of Computers: Computer Types, Functional Units, Basic Operational Concepts, Bus Structures, Software, Performance – Processor Clock, Basic Performance Equation.

Machine Instructions and Programs: Numbers, Arithmetic Operations and Characters, Memory Location and Addresses, Memory Operations, Instructions and Instruction Sequencing.

Module - 2

Machine Instructions and Programs (Continued): Addressing Modes, Assembly Language, Basic Input and Output Operations, Stacks and Queues, Subroutines, Additional Instructions. IEEE standard for Floating point Numbers (6.7.1 of Chapter 6)

Module - 3

Input/output Organization: Accessing I/O Devices, Interrupts, Direct Memory Access, Busses, Interface Circuits, Standard I/O Devices.

Module - 4

Memory System: Some Basic Concepts, Semiconductor RAM Memories, Read Only Memories, Cache Memories, Performance Considerations, and Virtual Memories.

Module - 5

Basic Processing Unit: Some Fundamental Concepts, Execution of a Complete Instruction, Microprogrammed Control, Hardwired Control.

Course outcomes:

After studying this course, students will :

CO1 have the knowledge of architectural concepts of computer and machine instructions. different addressing modes Understand the interfacing concepts.
CO2: describe the memory subsystems and various I/O devices and interfacing circuits.

TEXT BOOKS:

1. Carl Hamacher, Zvonko Vranesic, Safwat Zaky, "Computer Organization", McGraw Hill, 5th Edition, 2015, ISBN:9781259005275.

REFERENCE BOOKS

1. David A. Patterson, John L. Hennessy, "Computer Organization and Design – The Hardware / Software Interface ARM", Elsevier.
2. William Stallings, "Computer Organization & Architecture", Pearson.
3. Vincent P. Heuring & Harry F. Jordan, "Computer Systems Design and Architecture", Pearson.

Machine Shop & Material Testing Lab
B.E, III Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MTL37	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction + 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**
Credits – 02			

Course Objectives: Students will able to

1. Understand the characteristics and behavior of Engineering materials used for engineering applications.
2. To provide training to students to enrich their practical skills.

PART – A

1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine.
2. Torsion Test.
3. Bending Test on Non metallic specimens.
4. Izod and Charpy tests on M.S Specimen.
5. Brinell and rockwelll hardness test.

PART B

1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling.
2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination)

Course outcomes:
By the end of the course the student will be able to:

1. Demonstrate the knowledge & skill to conduct and analysis the result with respect to Hardness testing, and different loads.
2. Demonstrate the various skills of Turning Facing, Knurling and Thread cutting using lathe.

Scheme of Examination:

ONE question from part -A: 40 Marks
ONE question from part -B: 40 Marks
Viva -Voice: 20 Marks

Total : 100 Marks

ANALOG AND DIGITAL ELECTRONICS LAB
B.E, III Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17**MTL38**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction + 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**

Credits – 02

Course Objectives: Students will able to

1) Is to understand the characteristics and working of analog and digital components.
2) Is to design and develop analog and digital applications

PART-A:

1. Clipper circuits and Clamper circuits using diodes.
2. Single stage RC coupled amplifier using BJT and its frequency respons.
3. Invering Amplifier, Non inverting Amplifier, voltage Follower using Opamp.
4. Astable and Monostable multivibrator using timer 555.

5. RC phase shift Oscillator using BJT.

PART-B:

6. Simplification and realization of Boolean expression using logic gates/ universal gates.
7. Half adder and Full Adder using logic gates.
8. Decoder and Encoders
9. Multiplexers and demultiplexers.
10. Realization of counters.

Course outcomes:

By the end of the course the student will be able to:

- Analyze the Importance & Applications of Diode as Rectifiers, Filters, Zener Diode Regulators, Switching Circuits &Filters.
- Design and Develop Analog and Digital Circuits.
- Understand, Design and Develop counters, Registers for memory applications.

One Model from Part – A	40 Marks
One Model from Part – B	40 Marks
Viva Voce	20 Marks
Total	**100 Marks**

FLUID MECHANICS AND MACHINES
B.E, IV Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT42**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: student will be able to

1. gain fundamentals knowledge of fluid physical properties, pressure and its measurements, fluid statics, kinematics, dynamics and turbo machines.
2. understand the concepts of Fluid statics, Fluid dynamics, Fluid kinematics, Dimensional analysis, turbo machines, Hydraulic turbines & steam turbines
3. apply the principles of turbo machines, fluid mechanics and machines

Module - 1

Physical properties of fluids: Introduction, Types of fluids, Properties of fluids, viscosity, surface tension, vapor pressure and cavitation.

Fluid pressure and its Measurement: Intensity of pressure, Pascal's law, Hydrostatic law,atmospheric, gauge and vacuum pressures, Piezometer, U-tube and differential manometers.

Fluid Statics: Total pressure and center of pressure on submerged plane surfaces; horizontal, vertical and inclined plane surfaces submerged in liquid.

Module - 2

Fluid Kinematics: Types of fluid flow, continuity equation in 2D and 3D (Cartesian Co-ordinates only), velocity and acceleration, velocity potential function and stream function, problems.

Fluid Dynamics: Introduction, Euler's equation of motion, Bernoulli's equation from first principles and also from Euler's equation, limitations of Bernoulli's equation, problems.

Module - 3

Dimensional Analysis: Introduction, derived quantities, dimensions of physical quantities, dimensional homogeneity, Rayleigh's method, Buckingham's π-theorem, dimensionless numbers, similitude, types of similitudes.

Fluid Flow Measurements: Venturimeter, orificemeter, pitot-tube, V-Notch and rectangular notches (Derivations Venturimeter and V-Notch only), Problems.

Module - 4

Turbomachines: Definition of a Turbomachine, parts of a Turbomachine, Comparison with positive displacement machine; Classification.

Energy transfer in turbo machine: Euler Turbine equation, alternate form of Euler turbine equation, components of energy transfer, Degree of reaction, general analysis of a Turbo machine – effect of blade discharge angle on energy transfer and degree of reaction.

Module - 5

Hydraulic Turbines: Classification; Constructional features, Velocity triangles and Efficiencies of Pelton Turbine, Francis Turbine and Kaplan Turbine, and simple problems. Function of a Draft tube, types of draft tubes.

Steam Turbines: Classification, Single stage impulse turbine - Condition for maximum blade efficiency, stage efficiency, Compounding, need for compounding, methods of compounding. Reaction turbine - Parson's reaction turbine, condition for maximum blade efficiency, reaction staging, simple problems.

Course outcomes:

At the end of the course, the student will be able to:

- have fundamental knowledge of -fluid properties, pressure and its measurements, fluid statics, kinematics, dynamics & turbo machines.
- understand the concepts of Fluid statics, Fluid dynamics, Fluid kinematics, Dimensional analysis, turbo machines, hydraulic turbines & steam turbines.
- applications of Fluid flow measurements, dimensional analysis, turbo machines, hydraulic turbines & steam turbines and determine the various parameters of flow through pipes, channels, dimensional analysis.

TEXT BOOKS:

6. Fluid Mechanics, Oijush.K.Kundu, IRAM COCHEN, ELSEVIER, 3rd Ed. 2005.
7. Fluid Mechanics and Fluid Machines, Dr. Bansal, R.K.Lakshmi Publications, 2004.
8. Textbook of Turbomachines, M S Govinde Gowda, M M Publishers, 2011

REFERENCE BOOKS

8. Fluid Mechanics and hydraulics, Dr.Jagadishlal: MetropolitanBook Co-Ltd., 1997.
9. Fluid Mechanics (SI Units), Yunus A. Cengel John M.Oimbala, 2ndEd., Tata McGraw Hill, 2006.
10. Fluid Mechanics, John F.Douglas, Janul and M.Gasiosek and john A.Swaffield, Pearson Education Asia, 5th ed., 2006
11. Fluid Mechanics and Fluid Power Engineering, Kumar.D.S, Kataria and Sons., 2004
12. Fluid Mechanics -. Merle C. Potter, Elaine P.Scott. Cengage learning.

MICROCONTROLLER

B.E, IV Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT43	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives:

1. gain knowledge of microcontrollers, microprocessors, Different memory Architecture, interfacing techniques, Assembly and C programming .
2. understand to generate delays for different time period, exchanging of information between two devices using serial communication.
3. interfacing the controller to build the real-time applications such as switches, display devices, motors, converters etc.
4. differentiate between different microprocessor, microcontrollers, memory architecture and different Instruction sets.

Module - 1

Microprocessors and microcontroller. Introduction, Microprocessors and Microcontrollers, A Microprocessors survey. RISC & CISC CPU Architectures, Harvard & Von-Neumann CPU architecture. The 8051 Architecture: Introduction, 8051 Microcontroller Hardware, Input / Output Pins, Ports and Circuits External Memory, Counter and Timers, Serial Data Input / Output, Interrupts.

Module - 2

Addressing Modes and Operations: Introduction, Addressing modes, External data Moves, Code Memory, Read Only Data Moves / Indexed Addressing mode, PUSH and POP Opcodes, Data exchanges, Byte level logical Operations, Bit level Logical Operations, Rotate and Swap Operations, Arithmetic Operations: Flags, Incrementing and Decrementing, Addition, Subtraction, Multiplication and Division, Decimal Arithmetic.
Jump and Call Instructions: The JUMP and CALL Program range, Jumps, calls and Subroutines, Interrupts and Returns.

Module - 3

8051 programming in C and Timers: Data types and time delays in 8051C, I/O programming, logic operations, data conversion programs, data serialization.

Timer / Counter Programming in 8051: Programming 8051 Timers, Counter Programming, programming timers 0 and 1 in 8051 C.

Module - 4

8051 Serial Communication and Interrupts: Basics of Serial Communication, 8051 connections to RS-232, 8051 Serial communication Programming, Programming the second serial port, Serial port programming in C. Interrupts Programming,8051 Interrupts, Programming Timer Interrupts, Interrupt Priority in the 8051/52.

Module - 5

UNIT 5: 8051 Interfacing and Applications: Hardware & Software (Assembly code / C code) Interfacing of 8051 to simple switches and LEDs, LCD, ADC, Stepper motor,
DC motor, Temperature sensor, Wave form generation

Course outcomes:

Student will be able to

1. have knowledge of Microcontrollers, Microprocessors, architecture , instruction set, memory concepts , delay generation ,interfacing of external hardware peripherals.
2. describe the concepts of Assembly and C instruction set, memory management, serial communication, interrupt handling and time delay generation using Timer.
3. compute time delays, baudrates and write program using assembly and C language for different applications like display data on LCD, generate waveforms, temperature controller, keyboard interface and Motors etc
4. compare between microprocessor, microcontrollers, memory architecture, different Instruction sets and calculate the delay for different time periods

TEXT BOOKS:

1. "The 8051 Microcontroller and Embedded Systems – using assembly and C "-, Muhammad Ali Mazidi and Janice Gillespie Mazidi and Rollin D. Mc Kinlay; PHI, 2006 / Pearson, 2006
2. "The 8051 Microcontroller", Dr. K Uma Rao, Dr. Andhe Pallavi, Sanguine Technical publishers, Bangalore-2009

REFERENCE BOOKS

5. Microcontrollers: Architecture, Programming, Interfacing and System Design",Raj Kamal, "Pearson Education, 2005
6. "Microcontrollers- Theory and Applications", Aja y V.Deshmukh; TMH,2005
7. "Microcontroller and its applications", Dr.Raman i Kalpathi and Ganesh Raja; Sanguine Technical publishers, Bangalore- 2005.

MANUFACTURING TECHNOLOGY

B.E, IV Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT44	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: students should be able to

1. gain fundamental knowledge of manufacturing process.
2. understand the Techniques used in Traditional, Non Traditional Machining process, advanced Welding Process & CNC Machines
3. know the applications of various Traditional , Non Traditional manufacturing process & CNC machines.

Module - 1

Introduction to Manufacturing Process: Concept of Manufacturing process, its importance. Classification of Manufacturing processes.
Casting: Introduction to Casting process &steps involved. Various components produced by casting process, Advantages & Limitations.
Patterns: Definition and types.
Sand Moulding: Binders and Additives: Definition, Need and Types.Types of base sand, requirements of base sand.Types of Sand Moulding.Cores: Definition, Need and Types. Concept of Gating & Risers**:** Principle and types.
Introduction to Die Casting and injection moulding.

Module - 2

Introduction to metal working: Classification of metal working processes, characteristics of wrought products, advantages and limitations of metalworking processes.
Forging: Classification, Forging machines & equipment. Die-design parameters. Forgingdefects, Residual stresses in forging, Applications of forging.
Rolling: Classification, Types of rolling mills, Defects in rolled products. Rolling variables, Applications of Rolling.
Drawing: Drawing equipment & dies,drawing variables, Tube drawing,classification of tube drawing, Applications

Module - 3

Extrusion: Types of extrusion processes, extrusion equipment & dies,Extrusion ofseamless tubes, lubrication & defects in extrusion, Extrusion variables, Applications

Sheet & Metal Forming: Forming methods dies & punches, progressivedie, compound die, combination die. Rubber forming. Open back inclinablepress (OBI press), piercing, blanking, bending, deep drawing, defects of drawn products, stretch forming, Roll bending & contouring, Applications.

Advanced Welding processes: Classification, Advantages & limitations of welding. Metal Arc welding (MAW), Flux Shielded Metal Arc Welding (FSMAW), Inert Gas Welding (TIG & MIG) Submerged Arc Welding (SAW) and Atomic Hydrogen Welding processes (AHW), Resistance welding, Applications.

Module - 4

Non-traditional Machining Processes: Need for non-traditional machining, Principle, equipment & operation of Laser Beam, Plasma Arc Machining, Electro Chemical Machining, Ultrasonic Machining, Abrasive Jet Machining, Water Jet Machining, Electron Beam Machining, Electron Discharge Machining and Plasma Arc Machining.

Module - 5

Introducing to CNC machines: Basics of Turning tool Geometry, ATC, Programming methods. – Manual part programming, Milling, Turning, (Simple Programs), Computer Aided part programming (Simple problems, DNC, Types, Applications, Types of CNC Programming Software's, Over view CNC machining centers, Turning centre.

Course outcomes:

At the end of this course students will

1. have Fundamental knowledge of casting, forging, rolling ,drawing. Extrusion, Sheet Metal Forming, Advanced Welding Process, Non Traditional Machining process & CNC Machines. [PO: a,]
2. understand the Various Techniques used in casting, forging, rolling ,drawing. Extrusion, Sheet Metal Forming, Advanced Welding Process, Non Traditional Machining process & CNC Machines . [PO: b, g, h, j]
3. 3. applications of various Traditional , Non Traditional manufacturing process & CNC machines [PO: b, g, h, j]

TEXT BOOKS:

1. Manufacturing Technology, Serope Kalpakjain, Steuen.R.Sechmid, Pearson Education Asia, 5th Ed. 2006.
2. Manufacturing Technology Vol 1&2, PN Rao, Tata McGraw Hill, 2001 NC Machine Programming and Software Design, ChnoHwachang, Michel. A. Melkanoff, Prentice Hall, 1989

REFERENCE BOOKS

1. Process and Materials of Manufacturing, Roy A Lindberg, 4th Ed. Pearson Ed. 2006.
2. Workshop technology, Hazara Choudhry, Vol-I &II, Media Promoters & Publishers Pvt Ltd. 2004.
3. Production technology, HMT, Tata McGraw Hill, 2001.
4. Manufacturing Science, AmitabhGhosh and Mallik, affiliated East West press, 2003.
5. Fundamentals of metal Machining and machine Tools, G. Boothroyd, McGraw Hill. 2000.
6. Automation Production system and Computer Integrated Manufacturing Mikell. O. Grover, PHI, New Delhi, 2002.

THEORY OF MACHINES
B.E, IV Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT45**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**05**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

1. To gain knowledge of Kinematics and Dynamics associated with machine elements.
2. To understand the techniques for studying motions and forces of machines and their components.
3. To calculate mobility, power loss due to friction, balancing mass and its position, stability of a governor and effect of gyroscopic couple.
4. To Construct different cam profiles.

Module - 1

Introduction: Definitions Link or element, Kinematic pairs, Degrees of freedom, Grubler's criterion (without derivation), Kinematic chain, Mechanism, Structure, Mobility of Mechanisms (with problems), Inversion, Machine. Inversion of single slider and four bar mechanisms. Intermittent Motion - Geneva wheel mechanism and Ratchet and Pawl mechanism. Steering gear
mechanism, Ackerman steering gear

Module - 2

Gears and Gear Trains: Gear terminology, law of gearing, Path of contact Arc of contact, Contact ratio of spur gears. Simple gear trains, Compound gear trains for large speed. Reduction, Epicyclic gear trains. Tabular methods of finding velocity ratio of epicyclic gear trains.

Module - 3

Cams: Types of cams, Types of followers. Displacement, Velocity and, Acceleration time curve for cam profiles. Disc cam with reciprocating follower having knife-edge, roller follower, Disc cam with oscillating roller follower. Follower motions including SHM, Uniform acceleration and retardation and Cycloidal motion.

Module - 4

Balancing of Rotating Masses: Static and dynamic balancing. Balancing of single rotating mass by balancing masses in same plane and in different planes.Balancing of several rotating masses by balancing masses in same plane and in different planes.

Belt Drivers: Belt Drives: Flat Belt Drives, Ratio of Belt Tensions, Centrifugal Tension, power Transmitted.

Module - 5

Gyroscope: Vectorial Representation of Angular Motion, Gyroscopic Couple. Effect of Gyroscopic Couple on Ship, Plane Disc, Aircraft, Stability of Two Wheelers.

Governors: Types of governors; force analysis of Porter and Hartnell governors. Controlling force, stability, sensitiveness,

isochronism, effort and power.

Course outcomes:

At the end of the course, the student will have:

1. Have fundamental knowledge of Kinematics and Dynamics of Machines.
2. Understand the geometry and the motion of the parts of a machine and forces that produces this motion.
3. Determine the mobility, power loss due to friction in various machine elements, balancing mass and its position, stability of a governor and effect of gyroscopic couple on plane disk, Aircraft, stability of two wheelers and ship.
4. Construction of different types of cam profiles for a given data.

TEXT BOOKS:

1. Theory of Machines: Sadhu Singh, Pearson Education, 2nd edition, 2007.
2. Theory of Machines: Rattan S.S Tata McGraw Hill Publishing Company Ltd., New Delhi, 2nd Edition, 2006.
3. Theory of Machines, R. S. Khurmi, J. K. Gupta, Eurasia Publishing House, 2008 Revised Edition.

REFERENCE BOOKS

1. Theory of Machines and Mechanisms, John Joseph Uicker, G. R. Pennock, Joseph Edward Shigley, Oxford University Press, 2003.
2. Theory of Machines and Mechanisms, Amitabha Ghosh and Mallick, East West Press, 3rd Edition 2006.

1. Theory of Machines, Thomas Bevan, CBS Publication 1984.

INSTRUMENTATION AND MEASUREMENTS
B.E, IV Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT46	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**
Credits – 04			

Course Objectives: Students Will able to

- Gain Knowledge to learn the concepts of developing basic skills necessary for Functional Elements of Instruments and Measurement of Strain , Pressure , Force , Displacement ,Level and Study of Various Kinds of Transducers.
- Students will expose to the Understand the various Concepts related to Static and Dynamic Characteristics and Various Measurement Technology
- Determine the problem related to measurements of Resistance capacitance and induction using standard Bridge Circuits.

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Module - 1

Classification and Functional Elements of Instrument/ measurement system: Measurement, significance of measurement, instruments and measurement systems, mechanical, electrical and electronic instruments, Deflection & Null type instruments and their comparison, Analog and digital modes of operation, functions of instruments and measurement systems, applications of measurement systems, Elements of generalized measurement system, Input-output configuration of measuring instruments and measurement systems, methods of correction for interfering and modifying inputs. Transducers, Classifications of transducers-primary & secondary,
active & passive, analog and digital transducers.

Module - 2

Static and Dynamic Characteristics: Accuracy and precision, indications of precision, static error, scale range and scale span, reproducibility and drift, repeatability, signal to noise ratio, sensitivity, linearity, hysteresis, threshold, dead zone and dead time, resolution, signal to noise ratio. Dynamic response – dynamic characteristics, time domain analysis & different types of inputs, frequency domain analysis. Time domain response – zero order system, first order electrical system, response of a first order system to step & ramp input, Second order system, response of a second order system to step input, time domain specifications, frequency
response of first and second order system.

Module - 3

Measurement of Displacement: Introduction, Principles of Transduction, Variable resistance devices, Variable Capacitance Transducer, Hall Effect Devices, Proximity Devices.
Measurement of Level: Capacitance probes, conductivity probes, differential pressure level detector, float level devices, optical level
switches, radiation level sensor, ultrasonic level detector, thermal level sensors

Module - 4

Measurement of Strain: Introduction, Factors affecting strain measurements, Types of Strain Gauges, Theory of operation of resistance strain gauges, Types of Electrical Strain Gauges – Wire gauges, unbounded strain gauges, foil gauges, semiconductor strain gauges (principle, types & list of characteristics only), Strain gauge Circuits – Wheatstone bride circuit, Applications.
Measurement of resistance, induction and capacitance: Whetstone's bridge, Kelvin Bridge; ACbridges, Capacitance Comparison Bridge,
Maxwell's bridge, wein's bridge, Wagners's earth connection.

Module - 5

Transducers – I: Introduction, Electrical transducers, Selecting a transducer, Resistive transducers, Resistive position transducer, Resistance thermometer, Thermistor, Inductive transducer,Differential output transducers **and** LVDT.
Transducers – II: Piezoelectric transducer, Photoelectric transducer,Photovoltaic transducer, Semiconductor photo devices, Temperature
transducers-RTD, Thermocouple(b) Display Devices: Digital display system, classification of display, Display devices, LEDs, LCD displays

Course outcomes:

After studying this course, students will able to:

- Have a knowledge of Instrumentation domain on Functional Element of Instruments and Measurement of Strain , Pressure , Force , Displacement ,Level and Study of Various Kinds of Transducers.
- Understanding the Static and Dynamic Characteristics and Various Measurement Technology including Transducers.
- Determine the extent and nature of electronic circuitry in Measurement Technology including Measuring and determination of Resistance, Capacitance and Inductance using various bridge control circuits.

TEXT BOOKS:

1. Electrical and Electronic Measurements and Instrumentation – A. K. Sawhney, 17th Edition (Reprint 2004), DhanpatRai& Co. Pvt. Ltd., 2004. (Module 1 & 2)
2. Instrumentation: Devices and Systems- C. S. Rangan, G. R. Sarma, V. S. V. Mani, 2nd Edition (32nd Reprint), McGraw Hill
Education (India), 2014. (Module 3-Displacement measurement, Module 4,

3. Process Measurement Instrument Engineers Handbook- Bela G. Liptak, Revised Edition, Chilton Book Company, 1982. (Module 3 – Level measurement,)
4."Electronics Instrumentation", H.S. Kalsi, TMH, 2004-Module 5

REFERENCE BOOKS

1. Transducers and Instrumentation – D.V.S.Murty, 2nd Edition, PHI, 2009.
2. Introduction to Measurements and Instrumentation - A. K. Ghosh, 2nd Edition, PHI, 2007.
3. Instrumentation Measurement and Analysis- B.C.Nakra and K.K.Choudhry, 3rd Edition, McGraw Hill Education (India) Pvt.Ltd. 2009.
4. Measurement Systems Application and Design- Ernest O.Doeblin and Dhanesh N Manik, 5th Edition, McGraw Hill, 2007

Fluid Mechanics, Machines and Pneumatic Lab

B.E, IV Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MTL37**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03** **(1Hour instruction + 4 hours Practice)**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50**	**Exam Hours**	**03**
Credits – 03			

Course Objectives:

1. gain knowledge about fluid flow measurements and performance analysis of hydraulic turbines.
2. determine the coefficient of discharge through pipes, channels and performance of hydraulic turbines.

PART A

1. Calibration of flow measuring devices:
    a. Orifice Plate meter,
    b. Venturimeter,
    c. V-notch
2. Performance testing of Turbines
    a. Pelton wheel
    b. Francis Turbine

c. Kaplan Turbine

PART B

1. Speed Control Circuit on Hydraulic/Pneumatic Trainer
2. Sequencing Circuit on Hydraulic/Pneumatic Trainer
3. Regenerative Circuit on Hydraulic/Pneumatic Trainer
4. Synchronizing Circuit on Hydraulic/Pneumatic Trainer

Course outcomes:

By the end of the course the student will be able to:

1. have knowledge about fluid flow measurements and performance analysis of hydraulic turbines.
2. understand the coefficient of discharge through pipes, channels and performance of hydraulic turbines.

Scheme of Examination:

ONE question from part -A: 40Marks
ONE question from part -B: 40 Marks Viva -Voice: 20 Marks
Total : 100 Marks

MICRO CONTROLLER LAB

B.E, IV Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MTL48	CIE Marks	40
Number of Lecture Hours/Week	03 (1Hour instruction + 2 hours Laboratory)	SEE Marks	60
RBT Levels	L1, L2, L3	Exam Hours	03

Credits – 02

Course Objectives:

- To study assembly language programming in 8051
- To study interfacing of various peripherals using 8051
- To design and develop applications using 8051

PART A

1. Data Transfer - Block move, Exchange, Sorting, Finding largest element in an array.
2. Arithmetic Instructions - Addition/subtraction, multiplication and division, square, Cube (16 bits Arithmetic operations – bit addressable).
3. Counters.
4. Boolean & Logical Instructions (Bit manipulations).
5. Conditional CALL & RETURN.
6. Code conversion: BCD – ASCII; ASCII – BCD, ASCII -Decimal; Decimal - ASCII; HEX - Decimal and decimal - HEX.
7. Programs to generate delay, Programs using serial port and on-Chip timer / counter.

PART B

1. Write C programs to interface 8051 chip to Interfacing modules to develop single chip solutions.
2. Simple Calculator using 6 digit seven segment display and Hex Keyboard interface to 8051.
3. Interfacing of 8051 to LCD.
4. External ADC and Temperature control interface to 8051.
5. Generate different waveforms Sine, Square, Triangular, Ramp etc. using DAC interface to 8051; change the frequency and amplitude.
6. Stepper and DC motor control interface to 8051.

Course outcomes:

By the end of the course the student will be able to:

CO1: build application on 8051 using assembly language.
CO2: able to interface between external peripherals to 8051 using C programming.

Students should make observations on nature of failure and manifestations of failure in each of the experiments apart from reporting values of mechanical properties determined after conducting the tests.

Scheme of Examination:

ONE question from part -A:	**40Marks**
ONE question from part -B:	**40 Marks**
Viva -Voice:	**20 Marks**
Total :	**100 Marks**

DESIGN OF MACHINE ELEMENTS

B.E, V Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT51	**CIE Marks**	**40**
Number of Lecture Hours/Week	**05**	**SEE Marks**	**60**
Total Number of Lecture Hours	**60(12 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

1. gain knowledge of theories of failures, stress concentration and machine elements.
2. understand the techniques in machine elements
3. determine the parameters of machine elements subjected to various load condition.
4. design of various machine elements

Module - 1

Introduction: Machine design, classification of machine design, design consideration, Tri axial stresses, Stress Tensor. Codes and Standards. Factor of Safety, design procedure for simple and combined stresses (No Numerical). Introduction to Stress Concentration, Stress concentration Factor and its effects (Simple problems).

Introduction to Theories of failure: Maximum Normal Stress Theory, Maximum Shear Stress Theory, Distortion Energy Theory.

Module - 2

Design of Keys, Couplings and Joints: Keys: Types of keys, Design of keys, Design of Couplings: Flange coupling, Bush and Pin type coupling. Design of cotter and knuckle joint.

Module - 3

Design of Shafts: Design for strength and Rigidity with Steady loading, ASME & BIS codes for Power Transmission shafting, Shafts under Fluctuating loads and combined loads.

Module - 4

Design of Spur Gears: Beam strength of spur gear, Stresses in gear teeth (Lewis equation), dynamic tooth load, design for wear

Design of helical gears: Beam strength of helical gear, Stresses in gear teeth (Lewis equation), dynamic tooth load, design for wear.

Module - 5

Design of Journal Bearings: Types of bearings, bearing characteristic number, coefficient of friction, minimum oil film thickness, Heat Generated, Heat dissipated, Bearing Materials.

Course Outcomes: On completion of the course the student will

1. have knowledge of theories of failures, stress concentration, power screws, shafts, keys, couplings, gears, bearings and springs.
2. understand the technique of theories of failure, stress concentration, fatigue strength etc.
3. calculate the stresses, parameters of machine elements subjected to various loads also make proper assumptions with respect to material, FOS for various machine components.

1. design machine elements like shafts, keys, couplings, gears, bearings.

TEXT BOOKS:

1. Mechanical Engineering Design, Joseph E Shigley and Charles R. Mischke. McGraw Hill International edition, 6th Edition 2009.
2. Design of Machine Elements, V.B. Bhandari, Tata McGrawHill Publishing Company Ltd., New Delhi, 3rd Edition 2010.
3. Machine Design, by Dr. P C Sharma and Dr. D K Aggarwal, S. K. Kataria& Sons, 11th Edition 2009.

DESIGN DATA HANDBOOK:

1. Design Data Hand Book, K. Lingaiah, McGraw Hill, 2nd Edition.
2. Data Hand Book, K. Mahadevan and Balaveera Reddy, CBSPublication.
3. Design Data Hand Book, H.G. Patil, I. K. International Publisher, 2010.

REFERENCE BOOKS

1. Machine Design, Robert L. Norton, Pearson Education Asia, 2001.
2. Design of Machine Elements, M. F. Spotts, T. E. Shoup, L. E. Hornberger, S. R. Jayram and C. V. Venkatesh, Pearson Education,2006.
3. Machine Design, Hall, Holowenko, Laughlin (Schaum's Outlines series) Adapted by S.K. Somani, Tata McGraw Hill Publishing Company Ltd., New Delhi, Special Indian Edition, 2008.

Virtual Instrumentation

B.E, V Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT52	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

1. gain knowledge to learn the concepts of developing basic skills necessary for importance Virtual Instrumentation and Lab View
2. understand the basic programming concepts and various Operation using DAQ Devices used in Virtual Instrumentation and Lab View.

3. diagnosis the problem related types of I/O module, Data Acquisition System and Communication Networks (Bus Systems) using Standard Protocol

Module - 1

CONCEPT OF VIRTUAL INSTRUMENTATION – Historical perspective – Need of VI – Advantages of VI – Define VI – Block diagram & Architecture of VI – Data flow techniques – Graphical programming in data flow – Comparison with conventional programming.PC based data acquisition – Typical on board DAQ card – Resolution and sampling frequency - Multiplexing of analog inputs – Single-ended and differential inputs – Different strategies for sampling of multi-channel analog inputs. Concept of universal DAQ card

Module - 2

DATA ACQUISITION BASICS: Introduction to data acquisition on PC, Sampling fundamentals, Input/Output techniques and buses. ADC, DAC, Digital I/O, counters and timers, DMA, Software and hardware installation, Calibration, Resolution, Data acquisition interface requirements.

Module - 3

GRAPHICAL PROGRAMMING ENVIRONMENT IN VI

Concepts of graphical programming – Lab-view software – Concept of VIs and sub VI ,Loops(While Loop and For Loop) , Structures(Case, Formula node, and sequence structures) Arrays Operations, Strings Operations, and file I/O. Examples on each.

Module - 4

CLUSTER OF INSTRUMENTS IN VI SYSTEM

Interfacing of external instruments to a PC – RS232, RS 422, RS 485 and USB standards - IEEE 488 standard – ISO-OSI model for serial bus – Introduction to bus protocols of MOD bus and CAN bus.

Module - 5

USE OF ANALYSIS TOOLS AND APPLICATION OF VI Fourier transform - Power spectrum - Correlation – Windowing and filtering tools – Simple temperature indicator – ON/OFF controller – P-I-D controller - CRO emulation - Simulation of a simple second order system – Generation of HTML page.

Course outcomes: On completion of the course the student will

1. have a knowledge of Virtual Instrumentation and Lab View domain on various I/O Module , Sensor, DAQ Devices ,Communication and Measurement System
2. understanding the basic programming concepts and various logical Instructions, DAQ Operation used in Virtual Instrumentation and Lab View .
3. determine the extent and nature of electronic circuitry in Virtual Instrumentation and Lab View including Signal monitoring and control circuits for Communication and Interfacing.

TEXT BOOKS:

1. “Virtual Instrumentation using LabVIEW” Jovitha Jerome, PHI publication

2."Virtual Instrumentation, LABVIEW", Sanjay Gupta, TMH,NewDelhi,2003

REFERENCE BOOKS

1. "PC Interfacing for Data Acquisition and Process Control",S.Gupta and JP Gupta InstrumentSocietyofAmerica,1994
2. Kevin James, PC Interfacing and Data Acquisition: Techniques for Measurement, Instrumentation and Control, Newnes, 2000.

HYDRAULICS AND PNEUMATICS

B.E, V Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT53	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

1. gain knowledge of basics of hydraulic and pneumatic systems.
2. understanding the working principles of hydraulics and pneumatics components
3. Engineering application of hydraulic and pneumatic systems

Module - 1

Introduction to Hydraulic Power: Definition of hydraulic system, advantages, limitations, applications, Pascal's law, structure of hydraulic control system, problems on Pascal's law.

The source of Hydraulic Power: Pumps Classification of pumps, Pumping theory of positive displacement pumps, construction and working of Gear pumps, Vane pumps, Piston pumps, fixed and variable displacement pumps, Pump performance characteristics, pump Selection factors, problems on pumps.

Module - 2

Hydraulic Actuators and Motors: Classification cylinder and hydraulic motors, Linear Hydraulic Actuators [cylinders], single and double acting cylinder, Mechanics of Hydraulic Cylinder Loading, mounting arrangements, cushioning, special types of cylinders, problems on cylinders, construction and working of rotary actuators such as gear, vane, piston motors, Hydraulic Motor Theoretical Torque, Power and Flow Rate, Hydraulic Motor Performance, problems, symbolic representation of hydraulic actuators (cylinders and motors).

Control Components in Hydraulic Systems: Classification of control valves, Directional Control Valves- Symbolic representation, constructional features of poppet, sliding spool, rotary type valves solenoid and pilot operated DCV, shuttle valve, check valves, Pressure control valves - types, direct operated types and pilot operated types. Flow Control Valves -compensated and non-compensated FCV, needle valve, temperature compensated, pressure compensated, pressure and temperature compensated FCV, symbolic representation.

Module - 3

Hydraulic Circuit Design And Analysis: Control of Single and Double -Acting Hydraulic Cylinder, Regenerative circuit, Pump Unloading Circuit, Double Pump Hydraulic System, Counter balance Valve Application, Hydraulic Cylinder Sequencing Circuits, Automatic cylinder reciprocating system, Locked Cylinder using Pilot check Valve, Cylinder synchronizing circuit using different methods, factors affecting synchronization, Speed Control of Hydraulic Cylinder, Speed Control of Hydraulic Motors, Safety circuit, Accumulators, types, construction and applications with circuits.

Maintenance of Hydraulic System: Hydraulic Oils - Desirable properties, general type of Fluids, Sealing Devices, Reservoir System, Filters and Strainers, wear of Moving Parts due to solid - particle Contamination, temperature control (heat exchangers), Pressure switches, trouble shooting.

Module - 4

Introduction to Pneumatic Control: Definition of pneumatic system, advantages, limitations, applications, Choice of working medium. Characteristic of compressed air. Structure of Pneumatic control System,fluid conditioners and FRL unit. Pneumatic Actuators: Linear cylinder - Types, Conventional type of cylinder- working, End position cushioning, seals, mounting arrangements- Applications. Rod - Less cylinders types, working, advantages, Rotary cylinders- types construction and application, symbols.

Pneumatic Control Valves: DCV such as poppet, spool, suspended seat type slide valve, pressure control valves, flow control valves, types and construction, use of memory valve, Quick exhaust valve, time delay valve, shuttle valve, twin pressure valve, symbols. Simple Pneumatic Control: Direct and indirect actuation pneumatic cylinders, speed control of cylinders - supply air throttling and Exhaust air throttling and Exhaust air throttling.

Module - 5

Signal Processing Elements: Use of Logic gates - OR and AND gates in pneumatic applications. Practical Examples involving the use of logic gates, Pressure dependant controls- types - construction - practical applications, Time dependent controls principle, Construction, practical applications.

Multi- Cylinder Application: Coordinated and sequential motion control, Motion and control diagrams. Signal elimination methods, Cascading method- principle, Practical application examples (up to two cylinders) usingcascading method (using reversing valves).

Electro- Pneumatic Control: Principles - signal input and output, pilot assisted solenoid control of directional control valves, Use of relay and contactors. Control circuitry for simple signal cylinder application.

Course outcomes: On completion of the course the student will

- have knowledge of hydraulic and pneumatic system and its components .
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- understand the working principle of various hydraulic and pneumatic components .
-
- apply working principles of Hydraulic and Pneumatic Systems for various applications.
  determine cause for hydraulic and pneumatic system break down and performance of hydraulic pumps, motors.

TEXT BOOKS:

1. “Fluid Power with Applications”, Anthony Esposito, Sixth edition, Pearson Education, Inc, 2000.
2.
3. 'Pneumatics and Hydraulics', Andrew Parr, Jaico Publishing Co

REFERENCE BOOKS:

1. 'Oil Hydraulic systems', Principles and Maintenance S. R. Majurr, Tata McGraw Hill Publishing Company Ltd. - 2001
2. 'Industrial Hydraulics', Pippenger, Hicks" McGraw Hill, New York
3. 'Hydraulic & Pneumatic Power for Production', HarryL. Stewart
4. 'Pneumatic Systems', S. R. Majumdar, Tata McGraw Hill Publish 1995
5. 'Hydraulic & Pneumatics' CMTI Data Book

MICRO & SMART SYTEMS TECHNOLOGY
B.E, V Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT54	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

1. gain knowledge of Smart Materials, Sensors & Actuators, Microsystems.
2. understand the Operation of Smart Devices & Systems, Electronic Circuits & Control for MEMS, Methodology of Micro-manufacturing.

Module - 1

Introduction to Micro and Smart systems: Miniaturization, Microsystems versus MEMS, Micro-fabrication, Smart Materials, Structures & Systems, Integrated Microsystems ,Application of Smart Materials & Microsystems.

Module - 2

Micro and Smart Devices and Systems: Principles and Materials: Definitions and salient features of sensors, actuators, and systems.Sensors: silicon capacitive accelerometer, piezoresistive pressure sensor, Portable blood analyzer, conductometric gas sensor. Actuators: Micromirror Array for Video Projection, Piezo-electric based inkjet print head,electrostatic comb-drive, Magnetic microrelay.

Module - 3

Micromachining Technologies: Silicon as a Material for Micromachining, Silicon wafer preparation, thin-film deposition techniques, Lithography, Etching, Silicon micromachining:surface micromachining bulk micromachining. Specialized Materials for Microsystems.

Module - 4

Electronics Circuits for Micro and Smart Systems. Semiconductor devices: Diode, Schottky diode,Tunnel diode,BJT ,MOSFET,CMOS circuits ,Electronics Amplifiers ,Op-Amp based circuits ,Practical Signal Conditioning Circuits for Microsystems. Circuits for Conditioning Sensed Signals.

Module - 5

Implementation of Controllers for MEMS & Case Studies of Integrated Microsystems. Design Methodology, PID controller, Circuit Implementation, Digital controller, Microcontroller & PLC. Case Studies of Integrated Microsystems: BEL pressure sensor, design considerations, performance parameters, practical implementations, design of electronics circuits, Integration of pressure Sensor and Smart Structure in vibration control.

Course outcomes: On completion of the course the student will

1. have knowledge of Smart Materials, Sensors & Actuators ,Microsystems.
2. understand the Working Methodology of Smart Devices & Systems, Electronics Circuits & Control for MEMS, Methodology of Micro-manufacturing.

TEXT BOOKS:

1. 1.Micro and Smart Systems: G.K.Ananthasuresh, K.J.Vinoy, S.Gopalakrishnan, K.N.Bhat, V.K.Aatre,Wiley India 2010.

REFERENCE BOOKS

1. Design and Development Methodologies, Smart Material Systems and MEMS: V. Varadan, K. J. Vinoy, S. Goplakrishnan, Wiley.
2. MEMS- Nitaigour Premchand Mahalik, TMH 2007.

MEMS & Microsystems: Design and Manufacture, Tai-Ran Hsu, Tata Mc-Graw-Hill.

WIRELESS NETWORKS AND COMMUNICATION

B.E, V Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT551	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

1. gain knowledge of the fundamental concepts of wireless communication and networks.
2. understand the operation of modern network architectures from a design and performance perspective .

Module - 1

Review of Fundamentals of Wireless Communication and Networks:

Wireless Communications, Wireless Communication channel specifications, Wireless Communication problems, wireless networks, Switching technology, wireless network issues and standards.

Module - 2

Wireless body area networks

Properties, Network Architecture, components, technologies, design issues protocols and applications.

Wireless personal area networks

Components, Requirements, Technologies and Protocols, Bluetooth & Zigbee.

Module - 3

Wireless Modulation

Wireless modulation techniques and hardware, characteristics of air interface, path loss models, wireless coding techniques, Digital modulation techniques, OFDM, UWB radio techniques, Diversity techniques, GSM hardware.

Module - 4

Wireless LAN, WMAN, WWAN

WLAN architecture, Components, Requirement, WLAN protocols, Applications WMAN architecture, components, Requirements, WMAN protocols, Application WWAN architecture, components, requirements, WWAN protocols, Application.

Module - 5

Wireless Adhoc networks

Mobile adhoc networks, Sensor networks, Mesh networks, VANETs.

Course outcomes: On completion of the course the student will

1. have knowledge of fundamental concepts of wireless communication and networks.
2. understand the Working of modern network architectures from a design and performance perspective.

TEXT BOOKS:

1. SS Manvi, MS Kakkasageri, "Wireless and Mobile Network concepts and protocols".Willy, first edition.2010.
2. Wireless Telecom systems and networks, Mullet: Thomson Learning 2006.

REFERENCE BOOKS

1. P Kavesh, Krishnamurthy, "Principals of wireless networks: A unified approach', PHI, 2006.
2. Iti Saha Mishra, "Wireless communication and networks 3G and beyond", MGH, 2009.
3. Mullet, "Introduction to wireless telecommunication systems and networks",cengage, 2009.
4. DP Agarwal, Qing An Zeng, "Introduction to wireless and mobile systems", Cengage,2008.
5. Ivan Stojmenovic, "Handbook of wireless networks and mobile computing', Willy,2009.

OPERATIONS RESEARCH
B.E, V Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT552	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40 (8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

1. gain knowledge of basics of operation research.
2. understanding various techniques of operation research for solving business decision and engineering problems.
3. determination of optimization solutions, effective decision making, model formulation and applications.

Module - 1

Introduction: Evolution of OR, definition of OR, scope of OR, application areas of OR, steps (phases) in OR study, characteristics and limitations of OR, models used in OR, linear programming (LP) problem-formulation and solution by graphical method.

Solution Of Linear Programming Problems: The simplex method canonical and standard form of an LP problem.

Module - 2

Transportation Problem: Formulation of transportation problem, types, initial basic feasible solution using different methods, optimal solution by MODI method, degeneracy in transportation problems, application of transportation problem concept for maximization cases.

Module - 3

Pert-CPM Techniques: Introduction, network construction - rules, Fulkerson's rule for numbering the events, AON and AOA diagrams; Critical path method to find the expected completion time of a project, floats; PERT for finding expected duration of an activity and project, determining the probability of completing a project, predicting the completion time of project; crashing of simple projects.

Module - 4

Queuing Theory: Queuing systems and their characteristics, Pure-birth and Pure-death models (only equations), empirical queuing models – M/M/1 and M/M/C models and their steady state performance analysis.

Module - 5

Game Theory: Formulation of games, types, solution of games with saddle point, graphical method of solving mixed strategy games, dominance rule for solving mixed strategy games.

Sequencing: Basic assumptions, sequencing 'n' jobs on single machine using priority rules, sequencing using Johnson's rule-'n' jobs on 2 machines, 'n' jobs on 3 machines, 'n' jobs on 'm' machines. Sequencing 2 jobs on 'm' machines using graphical method.

Course outcomes: On completion of the course the student will

1. have knowledge of linear programming, Transportation, PERT-CPM, Sequencing, Queuing Theory, and Game theory.
2. understanding the techniques of linear programming, Transportation, PERT-CPM, Sequencing, Queuing Theory, and Game theory for various engineering problems.
3. determination of optimization of solutions, effective decision making model formulation and applications that are used in solving business decision problems.

TEXT BOOKS:

1. Operations Research, P K Gupta and D S Hira, Chand Publications, New Delhi – 2007
2. Operations Research, Taha H A, Pearson Education.
3. Operations Research S.D. Sharma, LedarnathRamanath& Co, 002

REFERENCE BOOKS

1. Operations Research, A P Verma, S K Kataria&Sons, 2008
2. Operations Research, Paneerselvan, PHI
3. Operations Research, A M Natarajan, P Balasubramani, Pearson Education, 2005
4. Introduction to Operations Research, Hillier and Liberman,8th Ed., McGraw Hill
5. Operations Research, S Kalavathy, Vikas Publishing House Pvt Ltd, 2002

Linear Integrated Circuits
B.E, V Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT553	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40 (8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

1. gain knowledge of Operational Amplifiers,Oscillators.555 Timers,
2. understand the Operation of Op-Amp as Amplifiers, Oscillators. Filters, & 555 timer operation as multi vibrators.

Module - 1

Operational Amplifier Fundamentals: Basic Op-amp circuit, Op-Amp parameters – Input and output voltage, CMRR and PSRR, offset voltages and currents, Input and output impedances, Slew rate and Frequency limitations.

Module - 2

Op-Amps as AC Amplifiers: Capacitor coupled voltage follower, High input impedance – Capacitor coupled voltage follower, Capacitor coupled non inverting amplifiers, High input impedance – Capacitor coupled Non inverting Amplifiers.

OP-Amp Applications: Voltage sources, current Sources and current sinks, current amplifiers, instrumentation amplifier, precision rectifiers. (Text1)

Module - 3

More Applications : Limiting circuits, Clamping circuits, Peak detectors, Sample and hold circuits, V to I and I to V converters, Differentiating Circuit, Integrator Circuit, Phase shift oscillator, Wein bridge oscillator, Crossing detectors, inverting Schmitt trigger. (Text 1)
Log and antilog amplifiers, Multiplier and divider. (Text2)

Module - 4

Active Filters: First order and second order active Low-pass and high pass filters, Bandpass Filter, Bandstop Filter. (Text 1)
Voltage Regulators: Introduction, Series Op-amp regulator, IC voltage regulators. 723 general purpose regulators. (Text 2)

Module - 5

Phase locked loop: Basic Principles, Phase detector/comparator, VCO.
DAC and ADC convertor: DAC using R-2R, ADC using Successive approximation.
Other IC Application: 555 timer, Basic timer circuit, 555 timer used as astable and monostable multi vibrator. (Text 2)

Course outcomes: On completion of the course the student will

1. have knowledge of Operational Amplifiers,Oscillators.555 Timers
2. understand the Operation of Op-Amp as Amplifiers, Oscillators. Filters & 555 timer operation as multi vibrators.

TEXT BOOKS:

1. Operational Amplifiers and Linear IC‟s", David A. Bell, 2nd edition,PHI/Pearson, 2004. ISBN 978-81-203-2359-9.
2. "Linear Integrated Circuits", D. Roy Choudhury and Shail B. Jain, 4th edition, Reprint 2006, New Age International ISBN 978-81-224-3098-1.

REFERENCE BOOKS

8. Ramakant A Gayakwad, "Op-Amps and Linear Integrated Circuits," Pearson, 4th Ed, 2015. ISBN 81-7808-501-1.
9. B Somanathan Nair, "Linear Integrated Circuits: Analysis, Design & Applications," Wiley India, 1st Edition, 2015.
10. James Cox, "Linear Electronics Circuits and Devices", Cengage Learning, Indian Edition, 2008, ISBN-13: 978-07-668-3018-7.
11. Data Sheet: http://www.ti.com/lit/ds/symlink/tl081.pdf.

DRIVES AND CONTROLS

B.E, V Semester, Mechantronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT554	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40 (8Hours per Module)**	**Exam Hours**	**03**
Credits – 03			

Course objectives: Students will be able to

1. gain knowledge of Electrical Drives, Motor Power Rating, Industrial Drives.
2. understand the Operation of Drives in various Applications & Performance of various kinds of motors.

Module - 1

Introduction to Electrical drives & its dynamics:

Advantages of electrical drives. Parts of electrical drives, choice of electrical drives, Dynamics of electrical drives, fundamental torque equation, and speed torque conventions with multi quadrant operation. Components of load torques, nature and classification of load torques.

Module - 2

Selection of motor power rating:

Thermal model of motor for heating and cooling, Classes of motor duty, determination of motor rating. Calculations of time and energy loss in transient operations, steady state stability, load equalization.

Module - 3

D C MOTOR DRIVES:

Starting, braking, transient analysis of single phases half and full controlled rectifier control of separately excited dc motor. Three phase half and full controlled rectifier control of dc separately excited motor, multi quadrant operation of dc separately excited motor fed from fully controlled rectifier. Chopper control of separately excited dc motor and series motor.

Module - 4

Induction motor Drives:

Operation with unbalanced source voltage and single phasing, operation with unbalanced rotor impedances, analysis of induction motor fed from non-sinusoidal voltage supply, starting, braking and transient analysis. Stator voltage control, variable voltage frequency control voltage source inverter control, current source inverter control, rotor resistance control, slip power recovery

Module - 5

INDUSTRIAL DRIVES:

Application in steel mills, paper mills, cement industry, textile mills, sugar mills, electric traction(requirements of electric traction and suitability of series motors), coal mining.

Course outcomes: On completion of the course the student will

1. have knowledge of Electrical Drives, Motor Power Rating, Industrial Drives.
2. understand the Operation of Drives in various Applications & Performance of various kinds of motors.

TEXT BOOKS:

1. Fundamentals of Electrical Drives, G.K Dubey , Narosa publishing house, 2nd Edition,2002.
2. Fundamentals of Industrial Drives – Sarkar B N, 2012 PHI (ISBN-978-81-203-4433-4)

REFERENCE BOOKS

1. Electrical Drives, N.K De and P.K. Sen- PHI, 2009.
2. A First Course On Electric Drives, S.K Pillai-Wiley Eastern Ltd 1990.
3. Power Electronics, Devices, Circuits and Industrial Applications, V.R. Moorthi, “Oxford University Press, 2005.
4. Electric Motor Drives,Modeling,Analysis and Control, R.Krishnan,PHI,2008.

Object Oriented Programming in C++
B.E, V Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT555	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40 (8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objective:

The general objectives of the course is to

- 1 gain knowledge of fundamentals of object-oriented programming, Operators in C++, Functions, Classes, Overload Operators.
- understand the Syntax of C++.
- develop an ability to write Programs for various applications in C++.

Module - 1

C++, AN OVERVIEW: Getting started, the C++ program, Preprocessor Directives, The Built-In Array Data Type, Dynamic Memory Allocation and Pointers, An Object – based Design, An Object-Oriented Design, An Exception – based Design, An array.

THE BASIC LANGUAGE: Literal Constant, Variables, Pointer Type, String Types, const Qualifier, Reference Types, the bool type, Enumeration types, Array types. The vector container type. .

Module - 2

OPERATORS: Arithmetic Operators, Equality, Relational and Logical operators, Assignment operators, Increment and Decrement operator, The conditional Operator, Bitwise operator, bitset operations. Statements: if, switch, for Loop, while, break, goto, continue statements.

Module - 3

FUNCTIONS: Prototype, Argument passing, Recursion and linear function.

EXCEPTION HANDLING: Throwing an Exception, Catching an exception, Exception Specification and Exceptions and Design Issues.

Module - 4

CLASSES: Definition, Class Objects, Class Initialization, Class constructor, The class destructor, Class Object Arrays and Vectors.

Module - 5

Overload Operators, Operators ++ and --, Operators new and delete.

Multiple Inheritances, public, private & protected inheritance, Class scope under Inheritance**.**

Course outcomes: On completion of the course the student will

1. have knowledge of fundamentals of object-oriented programming, Operators in C++, Functions ,Classes, Overload Operators.
2. understand the Syntax of C++.
3. write Programs for various applications in C++.

TEXT BOOKS:

1. C++ Primer, S. B. Lippman & J. Lajoie, 3rd Edition, Addison Wesley, 2000.
2. Object Oriented Programming with C++, Balaguruswamy, Tata McGraw-Hill Education, 2008 - C++

REFERENCE BOOKS

1. Introduction to Object Oriented Programming & C++, Yashawant P Kanetkar, BPB Publication, 2003
2. C++ Program Design: An Introduction to Programming and Object- Oriented Design. Cohoon and Davidson, 3rd Edn. TMH publication. 2004.
3. Object Oriented Programming using C++, R. Lafore, Galgotia Publications, 2004.

Mechatronics Engineering

B.E, V Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT561	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40 (8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objective: Students will be able to

1. gain Knowledge of basics of Mechatronics system, transducers, actuators, signal conditioning, sensors
2. understanding the working of Mechatronics components, signal conditioning & sensors

Module - 1

Introduction: Definition and Introduction to Mechatronics Systems. Modeling &Simulation of Physical systems Overview of Mechatronics Products and their functioning, measurement systems. Control Systems, simple Controllers. Study of Transducers: Pneumatic and Hydraulic Systems, Mechanical Actuation System, Electrical Actual Systems, Real time interfacing and Hardware components for Mechatronics.

Module - 2

Electrical Actuation Systems: Electrical systems, Mechanical switches, Solid state switches, solenoids, DC & AC motors, Stepper motors. System Models: Mathematical models: mechanical system building blocks, electrical system building blocks, electromechanical systems, hydro-mechanical systems.

Module - 3

Signal Conditioning: Signal conditioning, the operational amplifier, Wheatstone Bridge, Digital signals, Multiplexers, Data Acquisition, Introduction to digital system processing, pulse-modulation. MEMS and Microsystems: Introduction, Working Principle, Materials for MEMS and Microsystems, Micro System fabrication process, Overview of Micro Manufacturing.

Module - 4

Sensors Fundamentals: Basic sensor technology, Sensor Systems, Sensor Characteristics, System Characteristics, Instrument Selection, Data acquisition, Installation. process of developing sensors, sensor arrays smart sensors, Industrial sensor networking basic Elements.

Module - 5

Types of sensors and applications, over view: Process of developing sensors, trends in sensor Technology and IC Sensors, sensor array's and multi sensor systems, smart sensors, sensor networks in R & D, sensors and networks, industrial network and automation.

Course outcomes: On completion of the course the student will

1. have knowledge of Mechatronics system, transducers, actuators, signal conditioning, sensors
2. understand the working of Mechatronics components, signal conditioning & sensors

TEXT BOOKS:

1. W. Bolton, "Mechatronics" - Addison Wesley Longman Publication, 1999
2. HSU "MEMS and Microsystems design and manufacture"- Tata McGraw-Hill Education, 200
3. wireless sensor network:a networking perspective – by jun abas jamalipur. john wiley 2009

REFERENCE BOOKS

1. Sensor Technology Hand Book – By Jon's Wilson.
2. Kamm, "Understanding Electro-Mechanical Engineering an Introduction to Mechatronics"- IEEE Press, 1 edition ,1996
3. Shetty and Kolk "Mechatronics System Design"- Cengage Learning, 2010
4. Mahalik "Mechatronics"- Tata McGraw-Hill Education, 2003
5. HMT "Mechatronics"- Tata McGraw-Hill Education, 1998

Automation in Manufacturing
B.E, V Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT562**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40 (8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objective: Students will be able to

- gain knowledge of fundamental concepts of automation in manufacturing.
- understand the techniques of automation in manufacturing for industry operations.

Module - 1

Introduction: Production System Facilities, Manufacturing Support systems, Automation in Production systems, Automation principles & Strategies.

Manufacturing Operations: Manufacturing Operations, Product/Production Relationship, Production concepts and Mathematical Models & Costs of Manufacturing Operations.

Module - 2

Industrial Control System: Basic Elements of an Automated System, Advanced Automation Functions & Levels of Automation, Continuous versus Discrete control, Computer Process control, Forms of Computer Process Control.

Quality Control Systems: Traditional and Modern Quality Control Methods, Taguchi Methods in Quality Engineering. Introduction to SQC Tools.

Module - 3

Automated Manufacturing Systems: Components of a Manufacturing systems, Classification of Manufacturing Systems, overview of Classification Scheme, Single Station Manned Workstations and Single Station Automated Cells.

Manufacturing Support System: Process Planning, Computer Aided Process Planning, Concurrent Engineering & Design for Manufacturing, Advanced Manufacturing Planning, Just-in Time Production System, Basic concepts of lean and Agile manufacturing.

Module - 4

Inspection Technologies: Automated Inspection, Coordinate Measuring Machines Construction, operation & Programming, Software, Application & Benefits, Flexible Inspection System, Inspection Probes on Machine Tools, Machine Vision, Optical Inspection Techniques & Non-contact Non-optical Inspection Technologies.

Module - 5

Group Technology & Flexible Manufacturing Systems: Part Families, Parts Classification and coding, Production Flow Analysis, Cellular Manufacturing, Flexible Manufacturing Systems: What is an FMS, FMS Components, FMS Applications & Benefits, and FMS Planning &Implementation Issues.

Course Outcomes: On completion of this course the student will

1. have knowledge of fundamental concepts of automated flow lines, traditional and modern quality control methods, manufacturing supporting system, AMS, Inspection Technologies, group technologies, FMS
2. understand various automated flow lines, assembly systems and line balancing methods, importance of automated material handling and storage systems and the importance of adaptive control systems, automated inspection systems.

TEXT BOOKS:

1. Automation, Production Systems and Computer Integrated Manufacturing, M. P. Groover, Pearson education. Third Edition,2008
2. Principles of CIM, Vajpayee, PHI.

REFERENCE BOOKS

1. Anatomy of Automation, Amber G.H & P. S. Amber, PrenticeHall.
2. Performance Modeling of Automated Manufacturing Systems,Viswanandham, PHI
3. Computer Based Industrial Control, Krishna Kant, EEE-PHI

VIRTUAL INSTRUMENTATION LAB

B.E, V Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MTL57**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction+ 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**
Credits – 02			

Course Objectives: Students will be able to

1. Understanding Virtual Instrument concepts and data acquisition operation
2. Creating Virtual Instruments for practical works

PART A

1. Creating Virtual Instrumentation for simple applications- Invert The State Of Boolean Indicator Twice A See Until Program Is Stopped By User.
2. Programming exercises for loops in virtual instrumentation-Continuous Monitoring of Temperature (Generated using Random no 0<t<100). for every 250 ms.
3. Programming exercises for graphs- Display Random Number Into 3 different CHARTS (STRIP, SLOPE,SWEEP) and understand the difference between these in the UI.
4. Programming Exercises on case and sequence structures:-Design the simple Calculator, making use of the inherent GUI present in the virtual instrumentation software.
5. Programming Exercises on Arrays– Take a 2D array input from the user and perform various array(and matrix) manipulations on it.
6. Programming Exercises on File Input output System – Read and write from ASCII and TDMS files.

PART B

1. Real time temperature acquisition and continuous monitoring using Virtual Instrumentation.
2. Developing voltmeter using DAQ cards – Acquiring a voltage and displaying it on a 'meter' indicator on the UI, thus designing a voltmeter
3. Developing Signal Generator using DAQ Card – Using analog output; amplitude, shape and frequency controlled by user
4. Data acquisition through Virtual Instrumentation – Read voltage and current of the 50 Hz supply to compute power and power factor
5. Design and Development of Filter Analysis using DAQ card – Acquire audio and filter out bands using different filters and compare effects
6. Real time sequential control of any batch process – Water level control or Temperature control

Course outcomes:

- understand, design and develop data acquisition systems for Various Sensor using DAQ Cards.
- analyze the importance & applications of LabVIEW in real time Environment.

Scheme of Examination:

ONE question from part -A:40 Marks

ONE question from part -B: 40 Marks

Viva –Voice :20 Marks

Total: 100 Marks

MICRO & SMART SYSTEMS TECHNOLOGY LABORATORY

B.E, V Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MTL58	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction+ 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**
Credits – 02			

Course Objectives: Students will be able to

1. Analyse the behavior of Mechanical Components for various kinds of loads.
2. Analyse the behavior of Pressure Sensor for various kinds of Pressures applied.

PART A

1. Static structural analysis
a) 2 D Mechanical Components.
b) 3 D Mechanical Components.

2. Piezoelectric analysis: cantilever beam

PART B

1. Pressure sensor experiment
2. a) Raw pressure sensor
3. b) compensated pressure sensor

Course outcomes: On the completion of the course the student will:

- Understand, Analyze & gain ability to choose Materials for desired applications.
Understand, Analyze & gain ability to choose Sensors for desired applications.

Scheme of Examination:
ONE question from part -A: 40 Marks
ONE question from part -B: 40 Marks
Viva –Voice : 20 Marks
Total: 100 Marks

PLC AND SCADA
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT61	CIE Marks	40
Number of Lecture Hours/Week	04	SEE Marks	60
Total Number of Lecture Hours	50(10 Hours per Module)	Exam Hours	03

Credits – 04

Course Objectives: Students will be able to

- Gain the Knowledge of various skills necessary for Industrial applications of Programmable logic controller(PLC)
- Understand the basic programming concepts and various logical Instructions used in Programmable logic controller (PLC)
- Solve the problems related to I/O module, Data Acquisition System and Communication Networks using Standard Devices.

Design and analysis of general structure of an automated process for real time applications using Programmable logic controller (PLC) and SCADA

Module - 1

what is A PLC, Technical Definition of PLC, What are its advantages, characteristics functions of A PLC, Chronological Evolution of PLC, Types of PLC, Unitary PLC, Modular PLC, Small PLC, Medium PLC, Large PLC, Block Diagram of PLC: Input/output (I/O) section, Processor Section, Power supply, Memory central Processing Unit: Processor Software / Executive Software, Multi asking, Languages, Ladder Language.

Module - 2

Bit Logic Instructions: introduction: Input and Output contact program symbols, Numbering system of inputs and outputs, Program format, introduction to logic: Equivalent Ladder diagram of AND gate, Equivalent ladder diagram of or Gate, equivalents Ladder Diagram of NOT gate, equivalent ladder diagram of XOR gate, equivalent ladder diagram of NAND gate, equivalent ladder diagram of NOR gate, equivalent ladder diagram to demonstrate De Morgan theorem. Ladder design.

Examples: Training Stopping, Multiplexer, DE multiplexers

Module - 3

PLC Timers and Counters: On Delay and OFF delay timers, Timer-on Delay, Timer off delay, Retentive and non-retentive timers. Format of a timer instruction. PLC Counter: Operation of PLC Counter, Counter Parameters, Counters Instructions Overview Count up (CTU) Count down (CTD).

Advanced instructions: Introduction: Comparison instructions, discussions on comparison instructions, “EQUAL” or “EQU” instruction, “NOT EQUAL” or “NEQ” instruction, “LESS THAN” or “LESS” instruction, “LESS THANOR EQUAL’ or “LEQ” instruction, GREATER THAN” OR “GRT” instruction, “GREATER THAN OR EQUAL TO” or “GRO” instruction, “MASKED COMPARISON FOR EQUAL” or “MEQ” instruction, “LIMIT TEST” or “LIM” instruction.

Module - 4

PLC input output (I/O) modules and power supply: Introduction: Classification of I/O, I/O system overview, practical I/O system and its mapping addressing local and expansion I/O, input-output systems, direct I/O, parallel I/O systems serial I/O systems. Sinking and sourcing. Discrete input module. Rectifier with filter, threshold detection, Isolation, logic section, specifications of discrete input module, types of analog input module, special input modules, analog output module, I/O modules in hazardous locations power supply requirements, power supply configuration, filters.

Module - 5

SCADA SYSTEMS

Introduction, definition and history of Supervisory Control and Data Acquisition, typical SCADA System Architecture, Communication Requirements, Desirable properties of SCADA system, Features, advantages, disadvantages and applications of SCADA. SCADA Architecture(First generation-

Monolithic, Second Generation-Distributed, Third generation-Networked Architecture), SCADA systems in operation and control of interconnected power system, Power System Automation, Petroleum Refining Process, Water Purification System, Chemical Plant

Course outcomes: On completion of the course students will

CO 1: have knowledge of Programmable Logic Controller domain on various Logical Operation and Various Advanced Logical Instruction, I/O Module, Sensor, Actuator, Communication and Measurement System.
CO 2: Understand the basic programming concepts and various logical Instructions used in Programmable logic controller (PLC).
CO 3: Compute the extent and nature of electronic circuitry in Programmable logic controller (PLC) and SCADA including monitoring and control circuits for Communication and Interfacing.
CO 4: Design and analyse the general structure of an automated process for real time industrial applications

TEXT BOOKS:

1. "PLC and Industrial application", MadhuchhandanGupts and SamarjitSen Gupta, pernram international pub. (Indian) Pvt. Ltd., 2011.
2.Ronald L Krutz, "Securing SCADA System", Wiley Publication

REFERENCE BOOKS

1.1.GaryDunning,"Introduction to Programmable Logic Controllers", Thomson,2nd Edition.
2.John W Webb, Ronald A Reis,"Programmable Logic Controllers: Principles and Application", PHI Learning, Newdelhi, 5th Edition
3.Stuart A Boyer, "SCADA Supervisory Control and Data Acqusition", ISA, 4th Revised edition

ARM BASED SYSTEM DESIGN
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT62**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives: Students will be able to

- gain the knowledge of various RISC and CISC architectures of processors.
- understand the embedded system based ARM processor , its programming with Embedded C and assembly language, various memory issues and memory mapping.

Module - 1

Introduction: The RISC design philosophy; The ARM design philosophy; Embedded system hardware and software. ARM processor fundamentals: Registers; Current Program Status Register; Pipeline; Exceptions, interrupts and the Vector Table; Core extensions; Architecture revisions; ARM processor families.

Module - 2

Arm Instruction Set And Thumb Instruction Set: ARM instruction set: Data processing instructions; Branch instructions; Load-store instructions; Software interrupt instruction; Program Status Register functions; Loading constants; ARMv5E extensions; Conditional execution. Thumb instruction set: Thumb register usage; ARM –Thumb interworking; Other branch instructions; Data processing instructions; Single-Register Load-Store instructions; Multiple-Register Load-Store instructions; Stack instructions; Software interrupt instruction

Module - 3

Writing And Optimizing ARM Assembly Code: Writing assembly code; Profiling and cycle counting; Instruction scheduling; Register allocation; Conditional execution; Looping constructs; Bit manipulation; Efficient switches; Handling unaligned data.

Module - 4

The memory hierarchy and the cache memory; Cache architecture; Cache policy; Coprocessor 15 and cache; Flushing and cleaning cache memory; Cache lockdown; Caches and software performance

Module - 5

Exception And Interrupt Handling: Exception handling; Interrupts and interrupt handling Schemes

Course outcomes: On completion of the course students will

- CO 1: have knowledge of embedded system based on the ARM processor, various cache methods and instruction set.
- CO 2: understand the various instruction set for writing and optimizing ARM assembly and C code

TEXT BOOKS:

1. ARM System Developer's Guide – Designing and Optimizing System Software – by Andrew N. Sloss, Dominic Symes, Chris Wright, Elsevier, 2004.

REFERENCE BOOKS

1. ARM Architecture Reference Manual by David Seal (Editor), 2nd Edition, Addison-Wesley, 2001.
2. ARM System-on-Chip Architecture by Steve Furber, 2nd Edition, AddisonWesley, 2000.

Power Electronics

B.E, VI Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	17MT63	CIE Marks	40
Number of Lecture Hours/Week	04	SEE Marks	60
Total Number of Lecture Hours	50(10 Hours per Module)	Exam Hours	03

Credits – 04

Course Objectives:

1. gain the knowledge of various conversion techniques of electrical energy using power electronic components.

2. understand the link between efficient usage of power and conservation of energy resources of the world

3. use various power electronic converters for different applications in industry.

Module - 1

Introduction, Power semiconductor Devices: Applications of Power Electronics, Power semiconductor devices, Control Characteristics, Types of power electronics circuits, Peripheral effects. Power MOSFETs – switching characteristics, gate drive, IGBTs, di/dt and dv/dt limitations, Isolation of gate and base drives, Simple design of gate and base drives.

Module - 2

Thyristors: Introduction, characteristics, Two Transistor Model. Turn-on and turn-off, di/dt and dv/dt protection, Thyristor types, Thyristors firing circuits, Simple design of firing circuits using UJT.

Commutation Techniques: Introduction. Natural Communication, Forced commutation: self commutation, impulse commutation, resonant pulse commutation and complementary commutations.

Module - 3

AC Voltage Controllers: Introduction. Principle of ON-OFF and phase control. Single-phase bidirectional controllers with resistive and inductive loads. **Controlled Rectifiers:** Introduction. Principle of phase controlled converter operation. Single phase semi-converters. Full converters. Three-phase half-wave converters. Three-phase full-wave converters.

Module - 4

DC Choppers: Introduction. Principle of step-down and step-up chopper with R-L load. Performance parameters. Choppers classification. Analysis of impulse commutated thyristor chopper (only qualitative analysis)

Module - 5

Inverters: Introduction, Principle of operation. Performance parameters. Single-phase bridge inverters. Three phase inverters. Voltage control of single-phase Inverters single pulse width, multiple pulse width, and sinusoidal pulse width modulation.

Course outcomes: On completion of the course student will

- CO1: have knowledge of power semiconductor devices, thyristors, AC voltage controllers, choppers and inverters.
- CO2: understand the characteristics and working principle of thyristors, AC voltage controllers, choppers and inverters.
- CO3: apply control techniques to meet desired switching objectives.

TEXT BOOKS:

1. "Power electronics", m h. Rashid 2nd edition, p. H.i/pearson, new delhi, 2002.

REFERENCE BOOKS

1. "Power Electronics – converters, Application and Design", Net Mohan, Tore M.
2. Undeland, and William P. Robins, Third Edition, John Wiley and Sons.
3. "Thyristorised Power Controllers", G. K. Dubey, S. R. Doradla, A. Joshi and R M K.
4. Sinha, New Age International Publishers.
5. "Power Electronics", M. D. Singh and Khanchandani K.B. T.M.H., 2001.
6. "Power Electronics", Cyril Lander, 3rd Edition, McGraw-Hill.
7. "Power Electronics: Principles and Applications", J.M. Jacob, Thomson-VikasPublicaions.

"Power Electronics: A Simplified Approach", R.S. Ananda Murthy and V. Nattarasu, Sanguine Technical Publisher.

Computer Aided Machine Drawing

B.E, VI Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT64**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course Objectives:

- gain knowledge about Engineering Drawing
- understand the sections of solids, orthographic views, threads, fasteners, couplings, joints and machine drawing

Part A

Sections of Solids: Sections of Pyramids, Prisms, Cones and resting only on their bases (No problems on axis inclinations, spheres and hollow solids). True shape of sections.

Orthographic Views: Conversion of pictorial views into orthographic projections of simple machine parts without sections. (Bureau of Indian Standards conventions are to be followed for the drawings).

Thread Forms: Thread terminology, sectional views of threads. ISO Metric (Internal & External) square.

Fasteners: Hexagonal headed bolt and nut with washer (assembly).

Part B

Keys & Joints :

Parallel key, Taper key, Feather key, Gib head key and Woodruff key (Only Practice)

Cotter joint, knuckle joint for two rods.

Couplings:

Protected type flanged coupling, flexible coupling

Part C
Assembly Drawings (Part drawings should be given) 1. Plummer block (Pedestal Bearing) 4. Screw jack (Bottle type) 5. Tailstock of lathe Geometric Dimensioning and Tolerances (Not for Exam): Types of Geometric tolerances, terminology for geometrical deviations, representation of geometrical tolerance on a drawing, dimensional tolerances, terminology for dimensional tolerances, selection of tolerances, representation of dimensional tolerances on a drawing.
Course outcomes: On completion of course students will : • CO 1: have knowledge about Engineering Drawing • CO 2: understand the concepts of sections of solids, orthographic views, threads, fasteners, couplings, joints and assembly drawing
TEXT BOOKS: 1. 'A Primer on Computer Aided Machine Drawing-2007', Published by VTU, Belgaum. 2. 'Machine Drawing', N.D.Bhat &V.M.Panchal
REFERENCE BOOKS 1. 'A Text Book of Computer Aided Machine Drawing', S. Trymbaka Murthy, CBS Publishers, New Delhi, 2007 2. 'Machine Drawing', K.R. Gopala Krishna, Subhash Publication

Modeling and Simulation
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT651**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

3. gain Knowledge of basics concepts and methodologies of modeling and simulation
4. understand the concepts of discrete event simulation, random number generation, test for random numbers & random varieties used in simulation study.
5. develop simulation model by simulation package for queuing system, production system and maintenance system

Module - 1

System and system environment: Component of a system – Continuous and discrets systems – Types of model; Steps in Simulation study; simulation of an event occurrence using random number table – Single server queue- two server queue- inventory systems.
Discrets Event Simulation: Concepts in discreet event simulation, manual simulation using event scheduling, single channel queue, two server queue, and simulation of inventory problem.

Module - 2

Random number generations: Properties of random numbers – Generation of Pseudo – Random numbers – techniques of generating pseudo random numbers; Test for random number; the Chisquare test-the kolmogrov smimov test – Runs test – Gap test – poker test.
FCV, symbolic representation.

Module - 3

Random – Viriate Generation: Inverse transform technique for Exponential, Uniform. Triangular, weibull, empirical, uniform and discrete distribution. Acceptance rejection method for Poisson and gamma distribution; Direct Transformation for normal distribution.

Module - 4

Analysis of simulated Data: Data collection, identifying the distribution, parameter estimations, and goodness of fit tests, verification and validation of simulation models.

Module - 5

Comparison and selection of GPSS, SIMSCRIPT, SLAM: Arena simulation languages: development of simulation models using arena simulation package for queuing system, Productions systems, maintenance system.

Course outcomes: On completion of the course students will

- CO 1: have fundamental knowledge of modeling and simulation.
- CO 2: understand the techniques of discrete event simulation, random number generation, test for random number, random variants used in simulation study & simulation packages.
- CO 3: apply simulation packages for queuing system, production system and maintenance system.

TEXT BOOKS:

1. Discrete, Event system Simulation, Banks J., Carson J.S. and Nelson B.L., 3rd Edition, Pearson education, Inc 2004 (ISBN 81-7808-505-4).

2. System Simulation, Geoffrey Gorden, Prentice Hall of India, 2003.

REFERENCE BOOKS

1. **System Simulations,** Geoffery Gorden, Prentice Hall of India, 2003.
2. **System Simulations and Modeling,**. Narsingh deo., Prentice Hall of India 2003.
3. **Computer simulations and Modeling,** Francis Neelamkovil, , john Wiley & Sons, 1987
4. **Simulation Modeling with Pascal,** Rath M.Davis & Robert M O Keefe, Prentice Hall Inc. 1989.

RAPID PROTOTYPING

B.E, VI Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT652**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

- 1. gain knowledge of Selective Laser Sintering , Fusion Deposition Modeling Solid Ground Curing, 3D Printers,
- 2. understand the working Principles of various Rapid Prototyping Manufacturing process,
- 3. know the applications of RP Technology

Module - 1

Introduction: Need for the compression in product development, history of RP systems, Growth of RP industry, and classification of RP systems.
Stereo Lithography Systems: Principle, Process parameter, data files and machine details, Application.

Module - 2

Fusion Deposition Modelling: Principle, Process parameter, Path generation, Applications.
Solid Ground Curing: Principle of operation, Machine details, Applications. Laminated Object Manufacturing: LOM materials. application.

Module - 3

Selective Laser Sintering: Type of machine, Principle of operation, process parameters, Data preparation for SLS, Applications. Thermal jet printer, ,
3-D printer

Module - 4

Rapid Tooling: Indirect Rapid tooling, Silicon rubber tooling, Aluminium filled epoxy tooling, Spray metal tooling, 3Q keltool, etc. Direct Rapid Tooling**,** Quick cast process, Sand casting tooling, Laminate tooling soft Tooling vs. Hard tooling.

Module - 5

Software for RP: STL files, Overview of Solid view, magics, imics, magic-communicator, etc. Internet based software
Rapid Manufacturing Process Optimization: factors influencing accuracy. Data preparation errors, Part building errors, Error in finishing. .

Course outcomes: On completion of course students will

- CO 1: have fundamental knowledge of Rapid Prototyping process, Selective Laser Sintering, Fusion Deposition Modeling, Solid Ground Curing, 3D Printers, Rapid Tooling, Software and Errors.
- CO 2: understand the working Principles of Selective Laser Sintering, Fusion Deposition Modeling Solid Ground Curing, 3D Printers,.
- CO 3: Know the applications of Selective Laser Sintering, Fusion Deposition Modeling, Solid Ground Curing, 3D Printers, also software tools like Magic, MMIC.

TEXT BOOKS:

1. Stereo Lithography and other RP & M Technologies, Paul F.Jacobs: SME, NY 1996.
2. Rapid Manufacturing, Flham D.T & Dinjoy S.S Verlog London2001.

REFERENCE BOOKS

1. Rapid Prototyping, Terry Wohlers Wohler's Report 2000"Wohler's Association 2000.
2. Rapid Prototyping Materials, Gurumurthi, IISc Bangalore.

3. Rapid Automated, Lament wood. Indus press New York

Mechanical Vibrations
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT653**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

- gain knowledge of different vibrations, degrees of freedom, damping systems.
- understand the mobility of different vibration systems.
- determine the mobility of single, double and multi degree vibrations using different methods

Module - 1

Introduction: Types of vibrations, Definitions, Simple Harmonic Motion (S.H.M.), Work done by harmonic force, Principle of super position applied to SHM, Beats.

Undamped Free Vibrations (Single DOF): Derivations for spring mass systems, Methods of Analysis, Natural frequencies of simple systems, Springs in series and parallel, simple problems.

Module - 2

Damped free vibrations (Single DOF): Types of damping, Analysis with viscous damping - Derivations for over, critical and under damped systems, Logarithmic decrement, simple problems.

Module - 3

Forced Vibrations (Single DOF): Introduction, Analysis of forced vibration with constant harmonic excitation - magnification factor, rotating and reciprocating unbalances, excitation of support (relative and absolute amplitudes), force and motion transmissibility, Energy dissipated due to damping, simple problems.

Module - 4

Systems with two DOF: Principle modes of vibrations, Normal mode and natural frequencies of systems (without damping) – Simple spring mass systems, masses on tightly stretched strings, Problems.

Module - 5

Numerical Methods for Multi DOF systems: Introduction, Maxwell's reciprocal theorem, influence coefficients, Rayleigh's method, Dunkerley's method, Stodola method, method of matrix iteration (up to two iterations) and Problems.

Course outcomes:

CO1: have knowledge of different vibrations, degrees of freedom, damping systems, magnification factor and transmissibility etc.
CO2: understand the mobility of different vibration systems.
CO3: determine the mobility of single, double and multi degree vibrations using different methods.

TEXT BOOKS:

1. Mechanical Vibrations, S. S. Rao, Pearson Education Inc, 4th edition, 2003.
2. Mechanical Vibrations, G. K. Grover, Nemchand and Bros, 6th edition, 1996.
3. Mechanical Vibrations, V. P. Singh, Dhanpat Rai & Company, 3d edition, 2006.

REFERENCE BOOKS

1. Theory of Vibration with Applications, W. T. Thomson, M. D. Dahleh and C. Padmanabhan, Pearson Education Inc, 5th edition, 2008.

2. Mechanical Vibrations: S. Graham Kelly, Schaum's outline Series, Tata McGraw Hill, Special Indian Edition, 2007.
3. Theory and Practice Mechanical Vibrations: J. S. Rao & K. Gupta, New Age International Publications, New Delhi, 2001.
4. Mechanical Vibrations: Dr. A. R. K Swamy & Prof. Y. Krishna Murthy, 1st edition 2009.

SATELLITE COMMUNICATION
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT654**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

- **gain Knowledge of various kinds of Satellites, Satellite Subsystems & Orbits, Trajectory, Multiple Access Techniques .**
- **understand the Operation of Satellites in space for various applications.**

Module - 1

SATELLITE ORBITS AND TRAJECTORIES: Definition, Basic Principles, Orbital parameters, Injection velocity and satellite trajectory, Types of Satellite orbits, Orbital perturbations, Satellite stabilization, Orbital effects on satellite's performance, Eclipses, Look angles: Azimuth angle, Elevation angle.

Module - 2

SATELLITE SUBSYSTEM: Power supply subsystem, Attitude and Orbit control, Tracking, Telemetry and command subsystem, Payload. Earth Station: Types of earth station, Architecture, Design considerations, Testing, Earth station Hardware, Satellite tracking.

Module - 3

MULTIPLE ACCESS TECHNIQUES: Introduction, FDMA (No derivation), SCPC Systems, MCPC Systems, TDMA, CDMA, SDMA. Satellite Link Design Fundamentals: Transmission Equation, Satellite Link Parameters, Propagation considerations.

Module - 4

COMMUNICATION SATELLITES: Introduction, Related Applications, Frequency Bands, Payloads, Satellite Vs. Terrestrial Networks, Satellite Telephony, Satellite Television, Satellite radio, Regional satellite Systems, National Satellite Systems.

Module - 5

REMOTE SENSING SATELLITES: Classification of remote sensing systems, orbits, Payloads, Types of images: Image Classification, Interpretation, Applications. Weather Forecasting Satellites: Fundamentals, Images, Orbits, Payloads, Applications. Navigation Satellites: Development of Satellite Navigation Systems, GPS system, Applications.

Course outcomes:

On completion of course students will

CO 1: have Knowledge of various kinds of Satellites, Satellite Subsystems & Orbits, Trajectory, Multiple Access techniques .
CO 2: understand the Operation of Satellites in space for various applications

TEXT BOOKS:

1. Anil K. Maini, Varsha Agrawal, Satellite Communications, Wiley India Pvt. Ltd., 2015, ISBN: 978-81-265-2071-8.

References:

1. Dennis Roddy, Satellite Communications, 4th Edition, McGraw- Hill International edition, 2006

2. Timothy Pratt, Charles Bostian, Jeremy Allnutt, Satellite Communications, 2nd Edition, Wiley India Pvt. Ltd , 2017,

ISBN: 978-81-265-0833-4

Computer Integrated Manufacturing
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT655**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

- gain Knowledge of basics concepts CIM
- understand the concepts of high volume production, flow line analysis and line balancing, automated. assembly system, computerized manufacturing planning & CNC centers .
- apply CIM technology for providing manufacturing solutions.

Module - 1

Introduction, Automation definition, Types of automation, CIM, processing in manufacturing, Production concepts, Mathematical Models-Manufacturing lead time, production rate, components of operation time, capacity, Utilization and availability, Work-in-process, WIP ratio, TIP ratio,
High Volume Production
Introduction Automated flow line-symbols, objectives, Work part transport-continuous, Intermittent, synchronous, Pallet fixtures, Transfer Mechanism-Linear-Walking beam,. roller chain drive, Rotary-rack and pinion, Rachet & Pawl, Geneva wheel, Buffer storage, control functions-sequence, safety, Quality, Automation for machining operation.

Module - 2

Analysis Of Automated Flow Line & Line BalancingProperties General terminology and analysis, Analysis of Tranfer Line without storage upper bound approach, lower bound approach and problems, Analysis of Transfer lines with storage buffer, Effect of storage, buffer capacity with simple problem, Partial automation-with numerical problems, flow lines with more than two stages, Manual Assembly lines
Minimum Rational Work Element
Work station process time, Cycle time, precedence constraints. Precedence diagram, Balance delay methods of line balancing-largest Candidate rule, Kilbridge and Westers method, Ranked positional weight method

Module - 3

Automated Assembly Systems Design for automated assembly systems,types of automated assembly system, Parts feeding devices-elements of partsdelivery system-hopper, part feeder, Selectors, feed back, escapement andplacement analysis of Multistation Assembly Machine analysis of singlestation assembly. Automated Guided Vehicle System: Introduction,Vehicle guidance and routing, System management, Quantitative analysis ofAGV\'s with numerical problems and application.

Module - 4

Computerized Manufacturing Planning System Introduction, Computer Aided Process Planning, Retrieval types of process planning, Generative type of process planning, Material requirement planning, Fundamental concepts of MRP inputs to MRP, Capacity planning.

Module - 5

CNC Machining Centers: Introduction to CNC, elements of CNC, CNC machining centers, part programming, fundamental steps involved in development of part programming for milling and turning.

Course outcomes: On completion of the course student will

CO 1: have fundamental knowledge of CIM

CO 2: understand the concepts of high volume production, flow line analysis and line balancing, automated, assembly system, computerized manufacturing planning & CNC centers.

CO 3: apply CIM technology for providing manufacturing solutions

TEXT BOOKS:

1. Automation, Production system & Computer Integrated manufacturing, M. P. Groover Person India, 2007 2nd edition.
2. Principles of Computer Integrated Manufacturing, S. Kant Vajpayee, Prentice Hall India.

REFERENCE BOOKS

1. Computer Integrated Manufacturing, J. A. Rehg & Henry. W. Kraebber.
2. CAD CAM by Zeid, Tata McGraw Hill.

ROBOTICS & AUTOMATION

B.E, VI Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT661**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives: Students will be able to

1. gain fundamental knowledge of Robotics and Automation
2. describe Control system, different motions of robots and Material handling system

Module - 1

Basic Concepts:

Definition and origin of robotics – different types of robotics – various generations of robots – degrees of freedom – Asimov's laws of robotics – dynamic stabilization of robots.

Module - 2

Power Sources And Sensors:

Hydraulic, pneumatic and electric drives – determination of HP of motor and gearing ratio – variable speed arrangements – path determination – micro machines in robotics – machine vision – ranging – laser – acoustic – magnetic, fiber optic and tactile sensors.

Module - 3

Manipulators, Actuators And Grippers:

Construction of manipulators – manipulator dynamics and force control – electronic and pneumatic manipulator control circuits – end effectors – U various types of grippers – design considerations.

Module - 4

Industrial Automation:

• List basic Devices in Automated Systems • Distinguish Different Controllers Employed In Automated Systems.
Identify Safety in Industrial Automation

Module - 5

Material handling and Identification Technologies:

Overview of Material Handling Systems, Principles and Design Consideration, Material Transport Systems, Storage Systems, Overview of Automatic Identification Methods.

Course outcomes: On completion of course students will

- **CO1:** have the knowledge of Joints, Links, Sensors, Control units, Actuators. and elements of Automation
- **CO2:** describe motions and control system of Robots**.**

TEXT BOOKS:

1. Mikell P. Weiss G.M., Nagel R.N., Odraj N.G., Industrial Robotics, McGraw-Hill
2. Singapore, 1996.
3. Ghosh, Control in Robotics and Automation: Sensor Based Integration, Allied
4. Publishers, Chennai, 1998.

REFERENCE BOOKS

1. Deb.S.R., Robotics technology and flexible Automation, John Wiley, USA 1992.
2. Asfahl C.R., Robots and manufacturing Automation, John Wiley, USA 1992.
3. Klafter R.D., Chimielewski T.A., Negin M., Robotic Engineering – An integrated approach, Prentice Hall of India, New Delhi, 1994.
4. Mc Kerrow P.J. Introduction to Robotics, Addison Wesley, USA, 1991.
5. Issac Asimov I Robot, Ballantine Books, New York, 1986.

Process Instrumentation

B.E, VI Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MT662**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course Objectives:

- Gain the Knowledge of basic principles of transducers systems.
- Understand the significant material on important specific areas such as pressure, temperature, measurement, Heat-flux sensors, flow meters etc.
- Use the Instrumentation & Controls for various industrial applications.

Module – 1

Generalized Configuration, Functional Description & Performance Characteristics Of Measuring Instruments: Functional elements of an instrument: analog & digital modes of operation: null & deflection methods: I/O configuration of measuring instruments & instrument system- methods of correction for interfering & modifying inputs. Measurement Of Displacement: Principle of measurement of displacement, resistive potentiometers, variable inductance & variable reluctance pickups, LVDT, capacitance pickup.

Module – 2

Measurement Of Force, Torque & Shaft Power: Principle of measurement of Force, Torque, Shaft power standards and calibration: basic methods of force measurement; characteristics of elastic force transducer- Bonded strain gauge, differential transformer, piezo electric transducer, variable reluctance/ FM- Oscillator digital systems, loading effects; torque measurement on rotating shafts, shaft power measurement (dynamometers).

Module – 3

Temperature Measurement: Standards & calibration: thermal expansion methods-bimetallic thermometers, liquid-in-glass thermometers, pressure thermometers; thermoelectric sensor (thermocouple)- common Thermocouples, reference junction consideration, special materials, configuration & techniques; electrical resistance sensors- conductive sensor (resistance thermometers), bulk semiconductors sensors (thermistors); junction semiconductor sensors; digital thermometers.

Module – 4

Pressure Measurement: Standards & calibration: basic methods of pressure measurement; dead weight gauges & manometer, manometer dynamics; elastic transducers, high pressure measurement; low pressure (vacuum) measurement- McLeod gauge, Knudsen gauge, momentum-transfer (viscosity) gauges, thermal conductivity gauges, ionization gauges, dual gauge technique.

Module - 5
Flow Measurement: Local flow velocity, magnitude and direction. Flow visualization. Velocity magnitude from pitot static tube. Velocity direction from yaw tube, pivoted vane, served sphere, dynamic wind vector indicator. Hot wire and hot film anemometer. Hot film shock-tube velocity sensors.
Course outcomes: On completion of the course students will CO1: have the knowledge of design instruments with good precision and Calibrate the designed instruments. CO2: understand measurement as applied to research & development operations & also to monitoring & control of industrial & military systems & processors. CO3: illustrate the various applications in the field of DCS & SCADA .
TEXT BOOKS: 1. **Measurement systems application and design-** ERNEST O DOEBELIN, 5th Edition Tata McGraw Hill.
REFERENCE BOOKS 1. Instrumentation Devices & Systems- Rangan, Mani and Sharma 2nd Edition, Tata McGraw Hill. 2. Process Instruments & Controls Hand Book Considine- D.M. Mc Graw Hill. 3. Transducers & Instrumentation- DVS Murthy, Prentice Hall of India. 4. Instrumentation & Process Measurements- W.Bolton,Universities Press.

PLC AND SCADA LABORATORY
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MTL67**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction+ 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**
Credits – 02			

Course objectives:

3) Analyse the logic Program on SCADA and PLC Interface
4) Design various applications with programmable logic controllers using relay ladder logic.

PART – A

1. Study of various logic Execution in ladder diagram.
2. Interfacing of Lamp&button with PLC for ON&OFF Operation. Verify all logic gates.
3. PLC based thermal ON/OFF Controller.
4. Develop ladder logic to develop MUX and DE-MUX
5. Combination of counter &timer for lamp ON/OFF Operation.
6. Study& implement ON delay timer in PLC
7. Study& implement OFF delay timer in PLC
8. To study&implement of counter in PLCprogramming.(counter-up)
9. To study&implement of counter in PLCprogramming.(counter-down)
10. PLC based temperature sensing using RTD
11. Parameter reading of PLC in SCADA
12. Temperature sensing using SCADA

Course outcomes:

1. Perform experiments to determine the thermal conductivity of a metal rod
2. Conduct experiments to determine convective heat transfer coefficient for free and forced convection and correlate with theoretical values.
3. Estimate the effective thermal resistance in composite slabs and efficiency in pin-fin
4. Determine surface emissivity of a test plate
5. Estimate performance of a refrigerator and effectiveness of fin
6. Calculate temperature distribution of study and transient heat conduction through plane wall, cylinder and fin using numerical approach.

Course outcomes: On completion of the course the student will

CO 1: Analyze the Importance & Applications of PLC and SCADA in real time Environment.
CO 2: Design and Develop PLC and SCADA Modules for Various Sensor Technologies.

Scheme of Examination:
ONE question from part -A: 40Marks

ONE question from part -B: 40 Marks

Viva –Voice :20 Marks

Total: 100 Marks

POWER ELECTRONICS LABORATORY
B.E, VI Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-2018]

Course Code	**17MTL68**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction+ 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**
Credits – 02			

Course objectives: Students will be able to

- verify the characteristics of different power electronic devices.
- understand the usage of power devices to control the operation of electronic systems.

PART – A

1. Static characteristics of SCR and DIAC.
2. Static characteristics of MOSFET and IGBT.
3. Controlled HWR and FWR using RC triggering circuit.
4. SCR turn off using i) LC circuit and ii) Auxiliary Commutation
5. SCR turn-on circuit using synchronized UJT relaxation oscillator.
6. SCR Digital triggering circuit for a single-phase controlled rectifier
7. Single-phase full-wave rectifier with R and R-L loads.
8. A.C. voltage controller using TRIAC and DIAC combination connected to R and R-L loads.
9. Speed control of a separately excited D.C motor using an IGBT or MOSFET chopper.
10. MOSFET OR IGBT based single-phase full-bridge inverter connected to R load.

Course outcomes: On the completion of the course students will

- understand and verify the characteristics of different power electronic devices .
- use the power devices to control the operation of electronic systems.

Scheme for Examination:

One Question from Part A - 40Marks (10 Write up +30)

One Question from Part B - 40 Marks (10 Write up +30)

Viva-Voce - 20 Marks

Total 100 Marks

INDUSTRIAL ROBOTICS

B.E, VII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT71**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course objectives: Students will be able to

3. gain knowledge of Robotics and automation.
4. understand the working methodology of robotics and automation.
5. write the program for robot for various applications

Module - 1

Fundamentals of Automation: Automation and robotics, history of robotics, robotics market and future prospects.
Fundamentals of Robotics: robot anatomy, work volume, robot drive systems, control systems, precision of movement, end effectors, robotic sensors, robot programming and work cell control, robot applications, problems. Basic control systems and components: Basic control systems concepts and models, control system analysis, robot sensors and actuators

Module – 2

Robot Motion Analysis: Introduction to manipulator kinematics, homogeneous transformations and robot kinematics, manipulator path control, robot dynamics, configuration of a robot controller.
Robot End Effectors: types of end effecters, mechanical grippers, other types of grippers, tools as end effectors, robot/end effector interface, consideration in gripper selection and design, problems.
Sensors in Robotics: Transducers and sensors, sensors in robotics, tactile sensors, proximity and range sensors, uses of sensors in robotics, problems..

Module – 3

Machine Vision, : Introduction to machine vision, sensing and digitizing function in machine vision, image processing and analysis, training the vision system, robotic applications, problems.
Robot Programming: Methods of robot programming, lead -through programming methods, a robot program as a path in space, motion interpolation, wait, signal and delay commands, branching, capabilities and limitations of lead-through methods, problems.
Artificial Intelligence (AI): Introduction & goals of AI in research, AI techniques, LISP programming, AI & robotics, LISP in factory, robotic paradigms, problems.

Module - 4

Robot Cell Design & Control : Robot cell layouts, multiple robots and machine interference, considerations in work -cell design, work-cell control, interlocks, error detection and recovery, work -cell controller, robot cycle time analysis, graphic simulation of robotic work-cells, problems.
Material Transfer, Machine Loading/Unloading :Material Transfer, Machine Loading/Unloading: General considerations in robot material handling, material transfer applications, machine loading and unloading.

Module - 5

Robots in Automatic Processing Operations: Introduction, spot welding, continuous arc welding, spray coating, other processing operations.
Assembly & Inspection: Assembly and robotic assembly automation, parts presentation methods, assembly operations, compliance and remote centre compliance (RCC) device, assembly system configurations, adaptable programmable assembly system, designing for robotic assembly, inspection automation.

Course outcomes: On completion of course students will

CO1: have knowledge of Robotics, automation, robotics motion, sensors and control, machine vision, robotic programming and roles of robots in industry

CO2: understand the working methodology of robotics and automation, motion and control, machine vision and programming, application of robots in industry.

2. CO3: write the program for robot for various applications

Text Books:

1. Mikell P. Groover, Mitchel Weiss, Roger N. Nagel, Nicholas G. Odrey and Ashish Dutta, "Industrial Robotics: Technology, Programming and Applications", 2 nd Edition, Tata McGraw Hill, 2012.
2. Roland Siegwart, Illah R. Nourbakhsh, an d Davide Scaramuzza, "Introduction to Autonomous Mobile Robots", 2 nd Edition, PHI, 2011

REFERENCE BOOKS

1. S.P. SukhatMT, Solar Energy: principles of Thermal Collection and Storage, Tata McGraw-Hill (1984).
2. C. S. Solanki, "Solar Photovoltaic's: FundaMTntal Applications and Technologies, Prentice Hall of India, 2009.
3. L.L. Freris, Wind Energy Conversion Systems, Prentice Hall, 1990.

THERMAL ENGINEERING
B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT72**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course objectives: Students will be able to

- gain fundamental knowledge of thermodynamics, and heat transfer.
- understand the laws of thermodynamics and heat transfer.
- formulate and determine thermodynamic and heat transfer parameters.

Module - 1

Thermodynamics - Fundamental Concepts & Definitions: Thermodynamics: definition and scope, Microscopic and Macroscopic approaches. Engineering thermodynamics: definition, some practical applications of engineering thermodynamic. System (Closed system) and Control Volume (open system): Characteristics of system boundary and control surface, examples. Thermodynamic properties; definition and units, intensive and extensive properties. Thermodynamic state, state point, state diagram, path and process, quasi-static process, cyclic and non-cyclic presses; Thermodynamic equilibrium; definition, mechanical equilibrium; diathermic wall, thermal equilibrium, chemical equilibrium. Statement of Zeroth law of thermodynamics. (No Numericals)

Work and Heat: Thermodynamic definition of work; examples, sign convention. Displacement work: at part of a system boundary, at whole of a system boundary, expressions for displacement work in various processes through p-v diagrams. Shaft work, Electrical work. Other types of work, Heat; definition, units and sign convention, simple problems.

Module - 2

First Law of Thermodynamics: Statement of the First law of thermodynamics, extension of the First law to non-cyclic process, energy as a property, modes of energy, pure substance; definition, two-property rule, Specific heat at constant volume, enthalpy, specific heat constant pressure. Extension of the First law to control volume; steady state-steady flow energy equation, important applications, simple problems
Second Law of Thermodynamics: Thermal Reservoir, Concepts of Heat Engine, Heat Pump, coefficients of performance. Keivin – Planck statement of the Second law of Thermodynamics; PMM II and PMM I, Claussius statement of second law of Thermodynamics, equivalence of the two statements; reversible hat engines, Carnot cycle, Carnot principles. Thermodynamic temperature scale, simple problems.

Module - 3

Air Standard cycles: Carnot, Otto, Diesel, Dual and Stirling cycles, P-V and T-S diagrams, description, efficiencies and mean effective pressures, Comparison of Otto, Diesel and dual cycles, simple problems.
Heat Transfer - Introductory Concepts and Definitions: Modes of heat transfer: Basic laws governing conduction, convection, and radiation heat transfer; Thermal conductivity; convective heat transfer coefficient; radiation heat transfer; combined heat transfer mechanics. Boundary conditions of 1^{st}, 2^{nd} and 3^{rd} Kind, simple problems.

Module - 4

Conduction: Derivation of general three dimensional conduction equations in Cartesian coordinate, special cases, discussion on 3-D conduction in cylindrical and spherical coordinate systems (No derivation). One dimensional conduction equations in rectangular, cylindrical and spherical coordinates for plane and composite walls. Overall heat transfer coefficient. Thermal contact resistance, Simple problems.

Free or Natural Convection: Application of dimensional analysis for free convection- physical significance or Grashoff number; use of correlations of free convection in vertical, horizontal and inclined flat plates, vertical and horizontal cylinders and spheres, Simple problems

Module - 5

Forced Convections: Applications of dimensional analysis for forced convection. Physical significance of Reynolds, Prandtl, Nusselt and Stanton numbers, Simple problems.

Radiation Heat Transfer: Thermal radiation; definitions of various terms used in radiation heat transfer, Stefan-Boltzman law, Kircoff's law. Planck's law and Wein's displacement law. Radiation heat exchange between two parallel infinite black surface, between two parallel infinite gray surfaces; effect of radiation shield; intensity of radiation and solid angle, Simple problems.

Course outcomes:

On completion of course students will

CO1: have knowledge of thermodynamics and heat transfer.

CO2: understand the concepts of system, energy interaction, temperature distribution, and heat transfer.

CO3: applications of laws of thermodynamics to open and closed system and of heat transfer to different shapes and types of materials. Determine the thermodynamic performance, heat transfer and temperature distribution.

1.

Text Books:

1. Basic and applied Thermodynamics, P. K. Nag, Tata McGraw Hill Pub. 2002.
2. Heat & Mass transfer, Tirumaleshwar, Pearson education 2006.
1. Engineering Thermodynamics, R K Rajput, Laxmi Publications, 2007

Reference Books:

1. **Engineering Thermodynamics,** J. B. Jones and G. A. Hawkins, John Wiley and Sons.
2. **Basic Engineering Thermodynamics data hand book,** by B. T. Nijaguna. (To be supplied in the examination)
3. **Thermodynamics, An Engineering Approach,** Yunus a. Cenegal and Michael a. Boles, Tata McGraw Hill publications, 2002.
4. **Heat and Mass Transfer,** R K Rajput, S. Chand, 2007.
5. **Heat transfer,** P. K. Nag, Tata McGraw Hill 2002.
6. **Heat transfer-A basic approach,** Ozisik, Tata McGraw Hilll 2002.
7. **Heat transfer, a practical approach,** Yunus a- Cengel Tata McGraw Hill.

SIGNAL PROCESSING

B.E, VII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT73**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course objectives: Students will be able to

1. gain knowledge of signal, system, transformation and filter.
2. understand time domain, frequency domain signals, analog and digital systems.
3. operate on signals and systems to bring out its characteristics and desired information.
4. design analog and digital filers and implement discrete time systems.

Module - 1

Introduction: Definitions of a signal and a system, classification of signals, basic Operations on signals, Basic elementary signals, properties of systems.

Module - 2

Time-domain representations for LTI systems: Convolution, impulse response representation, Convolution Sum and Convolution Integral. Properties of impulse response representation,

Module - 3

Discrete Fourier Transforms (DFT): Introduction to DFT, Properties of DFT, multiplication of two DFTs- the circular convolution, additional DFT properties, use of DFT in linear filtering, overlap-save and overlap-add method. Fast-Fourier-Transform (FFT) algorithms: Direct computation of DFT, need for efficient computation of the DFT (FFT algorithms).Radix-2 FFT algorithm for the computation of DFT and IDFT–decimation-in-time and Decimation-in-frequency algorithms

Module - 4

IIR filter design: Characteristics of commonly used analog filters – Butterworth and Chebyshev filters, analog to analog frequency transformations. Design of IIR filters from analog filters (Butterworth and Chebyshev) - impulse invariance method. Mapping of transfer functions: Approximation of derivative (bilinear transformation) method, Verification for stability and linearity during mapping

Module - 5

FIR filter design: Introduction to FIR filters, design of FIR filters using - Rectangular, Hamming, Hanning and Kaiser windows, FIR filter design using frequency sampling Technique.

Implementation of discrete-time systems: Structures for IIR and FIR systems-direct form I and direct form II systems, cascade, lattice and parallel realization.

Course outcomes: On completion of the course the student will

CO1: have knowledge of signal, system, transformation, filter design.

CO2: understand the difference between time domain, frequency domain, analog and digital filters.

CO3: transform the signals from one domain to other domain using transformation techniques.

CO4: design analog and digital filters for specific applications.

Text Books:

1. Digital signal processing – Principles Algorithms & Applications, Proakis & Monalakis, Pearson education, 4th Edition, New Delhi, 2007.
2. "Signals and Systems", Simon Haykin and Barry Van Veen John Wiley & Sons, 2001.

Reference Books:

1. Discrete Time Signal Processing, Oppenheim & Schaffer, PHI, 2003.
2. Digital Signal Processing, S. K. Mitra, Tata Mc-Graw Hill, 2nd Edition, 2004.
3. Digital Signal Processing, Lee Tan: Elsivier publications, 2007
4. Alan V Oppenheim, Alan S, Willsky and A Hamid Nawab, "Signals and Systems" Pearson Education Asia / PHI, 2nd edition, 1997. Indian Reprint 2002
5. H. P Hsu, R. Ranjan, "Signals and Systems", Scham's outlines, TMH, 2006
6. B. P. Lathi, "Linear Systems and Signals", Oxford University Press, 2005.
7. Ganesh Rao and Satish Tunga, "Signals and Systems", Sanguine Technical Publishers, 2004.

AUTOMATION IN PROCESS CONTROL

B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT741**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits –03

Course objectives: Students will be able to

- gain knowledge of developing basic skills necessary for importance Process controller (Digital and Analog Controller) Using in Various Industry.
- understand the concepts and various Operation using Automation Process System by using various Process Control System.
- determine and Diagnosis the Principles of Various Digital and Analog Controller and ADC, DAC.

Module - 1

INTRODUCTION TO PROCESS CONTROL: process control block diagram, control system evolution. Final control: introduction to final control operation, signal conversions, actuators, control elements. Alarm and annunciators, control drawing: P & ID symbols and diagrams, flow sheet symbols, inter logic symbols, graphic symbols.

Module - 2

CONTROLLER PRINCIPLES: Introduction, process characteristics, control system parameters, discontinuous control modes, continuous control modes, and composite control modes

Module - 3

DISCRETE-STATE PROCESS CONTROL: Introduction, definition and characteristics of discrete state process control. Control-loop characteristics: Introduction, control system configuration, multivariable control systems, control system quality, stability, and process loop tuning.

Module - 4

ANALOG CONTROLLERS: Introduction, general features, electronic controllers, pneumatic controllers, designs considerations.

Module - 5

DIGITAL–TO-ANALOG CONVERTERS: V-F, and F-V converters, performance specifications, D-A conversion techniques (R-2R & binary weighted) multiplying DAC applications.
A-D conversion techniques (flash, successive approximation, single slope, dual slope), over sampling converters

Course outcomes: On completion of the course the student will
CO 1: have a knowledge of Process Control System on various Process Parameter (P,PI,PID) and Converter.
CO 2: understanding the concepts of Automation in Process Control Involved in Measurement System and Controller used in Industry.

1. CO 3: Application of Digital and Analog Controller used in various Automated Application based on Controller Parameters

Text Books:

1. Process Control Instrumentation Technology-C D Johnson.
2. Design with operational amplifiers and analog integrated circuits-3rd Edition, SERGIO FRANCO, Tata McGraw Hill

Reference Books:

1. Instrument Engineers Handbook-(Vol 1 & 2)-B G Liptak,Chilton Book Company
2. Chemical process control an introduction to theory and practice-Stephanopoulos
3. A Users Handbook of D/A and A/D converters-.E.R.HNATEK, Wiley publications
4. Computer Aided Process Control- S K Singh, Prentice Hall of India.
5. Process control: Concepts, dynamics &Application-S.K. Singh, PHI.

NANO TECHNOLOGY
B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT742**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits –03

Course objectives: Students will be able to

1. gain knowledge of nano structure, properties, manufacturing, and applications of silicon and carbon materials,.
2. understand what nanotechnology is about and Fabrication methods in nanotechnology (top down & bottom up), characterization methods in nanotechnology (optical, electrical, AFM, SEM, and TEM)

Module - 1

An Overview of Nano science & Nanotechnology: Historical background – nature, scope and content of the subject – multidisciplinary aspects – industrial, economic and societal implications. Experimental techniques and methods: For investigation and manipulating materials in the nano scale – electron microscope – scanning probe microscope – optical and other microscopes

Module - 2

Fullerenes: Discovery, synthesis and purification – chemistry of fullerenes in the condensed phase – orientational ordering – pressure effects – conductivity and superconductivity – ferromagnetism – optical properties. Carbon Nano tubes: Synthesis and purification – filling of nano tubes – mechanism of growth – electronics structure – transport properties – mechanical and physical properties – applications

Module - 3

self-Assembled Monolayer's: Monolayer's on gold – growth process – phase transitions – patterning monolayer's – mixed Monolayer's – applications. Semiconductor Quantum dots: Synthesis – electronic structure of nano crystals – how quantum dots are studied – correlation of properties with size – uses

Module - 4

Monolayer – Protected Metal Nano particles: Method of preparation – characterization – functionalized metal nano particles – applications- super lattices. Core-Shell Nano particles: Types – characterization – properties – applications. Nano shells – Types – Characterization – Properties – Applications.

Module - 5

Nano biology – Interaction between bio molecules and nano particle surfaces – materials used for synthesis of hybrid nano-bio assemblies – biological applications – nano probes for analytical applications – nano biotechnology – future perspectives. Nano sensors: What make them possible – nano scale organization for sensors – characterization – nano sensors based on optical properties – nano sensors based on quantum size effects – electrochemical sensors – sensors based on physical

Course outcomes: On completion of the course the student will

CO1: have the knowledge of essential concepts used in nanotechnology.

1. CO2:understand the methods used to characterize different nano materials

Text Books:

1. NANO: The Essentials, Understanding Nano science and Nanotechnology; T. Pradeep (Professor, IIT Madras); Tata McGraw-hill India (2007)
2. Nanotechnology, Richard Booker & Earl Boysen; Wiley (2005).

Reference Books:

1. Introduction to Nano scale Science and Technology [Series: Nanostructure science and Technology], Di Ventra, et al (Ed); Springer (2004).
2. Nanotechnology Demystifies, Linda Williams & Wade Adams; McGraw-Hill (2007)
3. Introduction to Nanotechnology, Charles P Poole Jr. Frank JH Ownes, Wiley Pvt. Ltd., New Delhi, 2007.

REAL TIME SYSTEMS

B.E, VII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT743**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits –03

Course objectives: Students will be able to

- gain knowledge of real time systems, computer control, hardware & software requirements, operating systems, RTS developing methodologies.

understand the operation of real time systems, computer control, hardware & software implementation for RTS, operating systems, RTS developing methodologies.

Module - 1

Introduction to real-time systems: historical background, rts definition, classification of real-time systems, time constraints, classification of programs.

Concepts of computer control: introduction, sequence control, loop control, supervisory control, centralized computer control, distributed system, human-computer interface, benefits of computer control systems

Module - 2

Computer Hardware requirements for RTS: Introduction, General purpose computer, single chip microcontroller, specialized processors, Process-related Interfaces, Data transfer techniques, Communications, Standard Interface..

Module - 3

Languages for Real-Time applications: Introduction, Syntax layout and readability, declaration and Initialization of Variables and Constants, Modularity and Variables. Compilation. Data types ,Control Structure, Exception Handling, Low-level facilities, Co routines, Interrupts and Device handling, concurrency, Real-time support, Overview of real-time languages.

Module - 4

Operating Systems: Introduction, Real-time multi-tasking OS, Scheduling strategies. Priority Structures, Task management, Scheduler and real-time clock interrupt handles. Memory Management, Code sharing, Resource control, task co-operation and communication, Mutual exclusion, Minimum OS kernel.

Module - 5

Design of rtss- general introduction: introduction, specification documentation, preliminary design, single-program approach, foreground/background systems.
rts development methodologies: introduction, yourdon methodology, ward and mellor method, hately and pirbhai method.

Course outcomes: On completion of the course the student will

CO1: have knowledge of real time systems, computer control, hardware & software requirements, operating systems, RTS developing methodologies.

CO2: understand the operation of real time systems, computer control, hardware & software implementation for RTS, operating systems, RTS developing methodologies.

Text Books:

1. Real – time Computer Control – an introduction, Sturt Bennel, 2ne Edn. Pearson Education. 2005.

Reference Books:

1. Real-Time Systems Design and Analysis, Philip, a. Laplante, second edition, PHI, 2005.
2. Real-Time Systems Development, Rob Williams, 2006.
3. Embedded Systems, Raj Kamal, Tata McGraw Hill, India, 2005.

Object Oriented Programming Using C++
B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT744**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits –03

Course objectives: Students will be able to

- gain Knowledge of fundamentals of C++, classes, objects, constructors & destructors, function prototypes, private and public access and class implementations with inheritance and polymorphism.
- understand the C++ Programming using classes, objects, constructors & destructors, function prototypes, private and public access and class implementations with inheritance and polymorphism.

Module - 1

Beginning with C++ and its features: What is C++, Applications and structure of C++ program, Different Data types, Variables, Different Operators, expressions, operator overloading and control structures in C++ (Topics from Ch -2,3 of Text).

Module - 2

Functions, classes and Objects: Functions, Inline function, function overloading, friend and virtual functions, Specifying a class, C++ program with a class, arrays within a class, memory allocation to objects, array of objects, members, pointers to members and member functions (Selected Topics from Chap-4,5 of Text)..

Module - 3

Constructors, Destructors and Operator overloading: Constructors, Multiple constructors in a class, Copy constructor, Dynamic constructor, Destructors, Defining operator overloading, Overloading Unary and binary operators, Manipulation of strings using operators (Selected topics from Chap-6, 7 of Text).

Module - 4

Inheritance, Pointers, Virtual Functions, Polymorphism: Derived Classes, Single, multilevel, multiple inheritance, Pointers to objects and derived classes, this pointer, Virtual and pure virtual functions (Selected 6 topics from Chap-8, 9 of Text).

Module - 5

Streams and Working with files: C++ streams and stream classes, formatted and unformatted I/O operations, Output with manipulators, Classes for file stream operations, opening and closing a file, EOF (Selected topics from Chap-10, 11 of Text)

Course outcomes: On completion of course students will

CO1: have Knowledge of fundamentals of C++, classes, objects, constructors & destructors, function prototypes, private and public access and class implementations with inheritance and polymorphism.

CO2: understand the C++ Programming using classes, objects, constructors & destructors, function prototypes, private

1. and public access and class implementations with inheritance and polymorphism

Text Books:

1. Object Oriented Programming with C++, E.Balaguruswamy, TMH, 6th Edition, 2013.

Reference Books:

1.Object Oriented Programming using C++, Robert Lafore, Galgotia publication 2010.

ANALYTICAL INSTRUMENTATION

B.E, VII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017]

Course Code	**17MT745**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8Hours per Module)**	**Exam Hours**	**03**

Credits –03

Course objectives: Students will be able to

- gain knowledge of developing basic skills necessary for importance Analytical Instrumentation
- understand the basic concepts and various Operation using Analytical Devices used in Biomedical Industry.

Module - 1

Visible ultraviolet spectrophotometers: Electromagnetic radiation, Beer Lambert law, absorption instruments, colorimeters, spectrophotometers, infrared spectroscopy theory, instrument and its types.

Module - 2

Chromatography: Gas chromatograph- basic concepts, parts of gas chromatograph. Method of peak areas, liquid chromatography- basic concepts, types if liquid chromatography, the liquid chromatograph.

Module - 3

Mass spectrometer & NMR spectrometer: Basic concept, types of mass spectrometer, components of mass spectrometer, resolution and applications. Principle of NMR, constructional details, sensitivity enhancement for analytical NMR spectroscopy. Use of computers with NMR spectrometers.

Module - 4
Fluorimeters & phosphorimeters: Principle of fluotrscence, measurement of fluotrscence, spectro fluotrscence, microprocessor based spectro fluotrscence, Measurement of Phosphorescence
Module - 5
Blood gas analyzer: Principle of pH measurement, electrode of pH measurement, Blood pH measurement, measurement of Blood pCO_2, measurement of Blood pO_2, complete Blood gas analyzer, commercially available Blood gas analyzers..
Course outcomes: On completion of the course the student will **CO 1:** have knowledge of Analytical Instrumentation on various Biomedical Module and Different Types of Measurement Meters and Measurement System **CO 2:** understanding the basic concepts of Analytical Instrumentation and various Measurement Meters and Measurement System used in Biomedical Industry.
Text Books: 1. Hand book of analytical Instruments by R. S. Khandpur, TMH Publications 1st Ed 1989, New Delhi
Reference Books: 1. Instrumental methods of analysis by H. H. Willard, L. L. Merritt & J. A. Dean, CBS Publications 7th Ed 1988 2. Principles of Instrumental analysis by S. J. Holler & T. A. Nilman Saunders college Publications 5st Ed 1998

BIOMEDICAL SIGNAL PROCESSING
B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017]

Course Code	17MT751	CIE Marks	40
Number of Lecture Hours/Week	03	SEE Marks	60
Total Number of Lecture Hours	40(8 Hours per Module)	Exam Hours	03

Credits –03

Course objectives: Students will be able to

1. gain Knowledge of Biomedical Signals, ECG, Signal Conversion & Averaging ,Adaptive Noise Cancellation, Data Compression Techniques, Cardiological signal processing, Neurological signal processing.
2. understand the operation of Biomedical Signal Processing ,ECG Signal Conversion & Averaging ,Adaptive Noise Cancellation, Data Compression Techniques, Cardiological signal & Neurological signal processing

Module - 1

Introduction to Biomedical Signals: The nature of Biomedical Signals, Examples of Biomedical Signals, Objectives and difficulties in Biomedical analysis.
Electrocardiography: Basic electrocardiography, ECG lead systems, ECG signal characteristics.
Signal Conversion :Simple signal conversion systems, Conversion requirements for biomedical signals, Signal conversion circuits (Text-1)

Module - 2

Signal Averaging: Basics of signal averaging, signal averaging as a digital filter, a typical averager, software for signal averaging, limitations of signal averaging. **Adaptive Noise Cancelling**:Principal noise canceller model, 60-Hz adaptive cancelling using a sine wave model, other applications of adaptive filtering.
(Text-1)

Module - 3

Data Compression Techniques: Turning point algorithm, AZTEC algorithm, Fan algorithm, Huffman coding, data reduction algorithms The Fourier transform, Correlation, Convolution, Power spectrum estimation, Frequency domain analysis of the ECG (Text-1)

Module - 4

Cardiological signal processing: Basic Electrocardiography, ECG data acquisition, ECG lead system, ECG signal characteristics (parameters and their estimation), Analog filters, ECG amplifier, and QRS detector, Power spectrum of the ECG, Band pass filtering techniques, Differentiation techniques, Template matching techniques, A QRS detection algorithm, Realtime ECG processing algorithm, ECG interpretation, ST segment analyzer, Portable arrhythmia monitor. (Text -2).

Module - 5

Neurological signal processing: The brain and its potentials, The electrophysiological origin of brain waves, The EEG signal and its characteristics (EEG rhythms, waves, and transients), Correlation. Analysis of EEG channels: Detection of EEG rhythms, Template matching for EEG, spike and wave detection (Text-2).

Course outcomes:
On completion of course students will

CO1: Have Knowledge of Biomedical Signals, ECG, Signal Conversion & Averaging ,Adaptive Noise Cancellation, Data Compression Techniques,

Cardiological signal processing, Neurological signal processing.

CO 2: Understand the operation of Biomedical Signal Processing ,ECG Signal Conversion & Averaging ,Adaptive Noise Cancellation, Data Compression Techniques, Cardiological signal & Neurological signal processing.

Text Books:

1. Biomedical Digital Signal Processing- Willis J. Tompkins, PHI 2001.
2. Biomedical Signal Processing Principles and Techniques- D C Reddy, McGrawHill publications 2005

Reference Book:

1. Biomedical Signal Analysis-Rangaraj M. Rangayyan, John Wiley & Sons 2002

Machine Learning

B.E, VII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	17MT752	CIE Marks	40
Number of Lecture Hours/Week	03	SEE Marks	60
Total Number of Lecture Hours	40(8 Hours per Module)	Exam Hours	03

Credits –03

Course objectives: Students will be able to

- gain Knowledge of Machine Learning, Decision Tree Learning, Artificial Neural Networks, Bayesian Learning, Evaluating Hypothesis.
- understand the working methodology of Machine Learning, Decision Tree Learning, Artificial Neural Networks, Bayesian Learning, evaluating Hypothesis

Module - 1

Introduction: Well posed learning problems, Designing a Learning system, Perspective and Issues in Machine Learning.

Concept Learning: Concept learning task, Concept learning as search, Find-S algorithm, Version space.

Module - 2

Plasticity effects: Irwin plastic zone correction. Dugdale's approach. The shape of the plastic zone for plane stress and plane strain cases.Theplate thickness effect, nuMTrical problems.Determination of Stress intensity factors and plane strain fracture toughness: Introduction, estimation of stress intensity factors. ExperiMTntal MTthod- Plane strain fracture toughness test, The Standard test,sizerequireMTnts,etc.

Module - 3

Artificial Neural Networks: Introduction, Neural Network representation, Appropriate problems, Perceptrons, Backpropagation algorithm.

Module - 4

Bayesian Learning: Introduction, Bayes theorem, Bayes theorem and concept learning, ML and LS error hypothesis, ML for predicting probabilities, MDL principle, Naive Bayes classifier.

Module - 5

Evaluating Hypothesis: Motivation, Estimating hypothesis accuracy, Basics of sampling theorem, General approach for deriving confidence intervals, Difference in error of two hypothesis, Comparing learning algorithms.

Course outcomes:

On completion of course students will

CO1: Have Knowledge of Machine Learning ,Decision Tree Learning , Artificial Neural Networks, Bayesian Learning, Evaluating Hypothesis.

CO2: Understand the working methodology of Machine Learning ,Decision Tree Learning , Artificial Neural Networks, Bayesian Learning, Evaluating Hypothesis.

Text Books:

1. Tom M. Mitchell, Machine Learning, India Edition 2013, McGraw Hill Education.

Reference Books:

1. Trevor Hastie, Robert Tibshirani, Jerome Friedman, The Elements of Statistical Learning, 2nd edition, springer series in statistics.
Ethem Alpaydın, Introduction to machine learning, second edition, MIT press.

SAFETY AND SECURITY OF AUTOMOTIVE SYSTMES			
Course Code	**17MT753**	CIE Marks	40
Number of Lecture Hours/Week	04	SEE Marks	60
Total Number of Lecture Hours	40 (10 Hours per Module)	Exam Hours	03

Credits – 03

Course objectives: Students will be able to

1. Gain knowledge of IC Engines, Fuel, Ignition , Lighting System
2. Understand the working Principles of Transmission system ,Gear box, Lubrication system , CMV safety rules.

Module -1

Types of automobiles: Limiting Dimensions as per Central Motor Vehicles Rules. Engines – classification, Construction, Materials of engine components. Prototype Testing as per Central motor Vehicles Rules.Fuel system – Fuel tank, Fuel filter, Types of fuel system. Carburetor – Simple and Modern, Fuel injection System. Emission standards as per CMV Rules.

Module -2

Electrical System: Storage battery Operations and Maintenance, Ignition System – Coil and Magneto Ignition System. Starting System, Lighting system, Horn System. Wiper motors, fans, heaters, trafi cators, automobile air conditioning. Central motor vehicles rules regarding lighting, windshields, Wipers.

Module -3

Transmission system: clutches – operation and fault finding of clutches, fluid flywheel, Gear box-types, steer systems, chassis springs, and suspension.

Module -4

Differential, dead and Live axles: Rims, Tyre etc. Brakes – types, construction and fault finding, CMV rules – brakes, Steering & tyre.

Module -5

Lubrication systems: types, components, lubricating oil, cooling system – details of components, study of systems, types.
Miscellaneous – special gadgets and accessories for fire fighting vehicles. Automobile accidents. CMV rules regarding safety devices for drivers, passengers.

Course outcomes:

On completion of course students will

- **CO1:** have knowledge of IC Engines, Fuel, Ignition , Lighting System
- **CO2:** understand the working Principles of Transmission system ,Gear box, Lubrication system , CMV safety rules.

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 20 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. CBS Narang, **Automobile Engineering.**
2. Kirpal Singh, **Automobile Engineering.**

Reference Books:

1. William H. Crouse, **Automobile Chassis and Body constructions**, operation and Maintenance.
2. William H. Crouse, **Automobile machines – Principles & operations.**
3. Joseph Heitner, **Automotive Mechanics-Principles &Practices**
4. P. L. Kohli, **Automotive Electrical Equipments.**
5. **The central Motor Vehicles Rules,** 1989.

DIGITAL IMAGE PROCESSING

B.E, VII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT754**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits –03

Course Objective:

1. gain knowledge of image, sampling, quantization, enhancement, and restoration of image.
2. understand different methods of image enhancement and restoration.
3. transform image using different transformations.

Module - 1

Digital image fundamentals: What is Digital image processing? Fundamental steps in digital image processing, components of an image processing system, elements of Visual Perception.

Module - 2

Images sensing and Acquisition: images sampling and Quantization's, Some Basic Relationships between Pixels, Linear and Nonlinear Operations.

Module - 3

Image Transforms: Two-dimensional orthogonal & unitary transforms, properties of unitary transforms, two dimensional discrete Fourier transform. Discrete cosine transform, Hadamard transform, Haar transform,

Module - 4

Image Enhancement: Image Enhancement in Spatial domain, Some Basic Gray Level Transformations, Histogram Processing, Enhancement using Arithmetic/Logic Operations. Basics of Spatial Filtering Image enhancement in the Frequency Domain filters, Smoothing Frequency Domain filters, Sharpening Domain filters, homomorphic filtering.

Module - 5

Model of image degrading/restoration process: noise models, Restoration in the Present of Noise, Linear Position-Invariant Degradations, inverse filtering, minimum mean square error (Weiner) filtering. Color Fundamentals. Color Models, Pseudo color. Image Processing., processing basics of full color image processing

Course outcoMTs:

On completion of this subject, students will be able to:

CO1: have knowledge of different images, enhancement and restoration.
CO2: understand how images are formed, sampled, quantized and represented digitally.
CO3: process the images by applying different operations and transformation

TEXT BOOKS:

1. "Digital Image Processing", Rafael C. Gonzalez and Richard e. Woods, Pearson Eucation, 2001, 2nd edition.

REFERENCE BOOKS

1. "Fundamentals of Digital Image Processing", Anil K, Jain, Pearson Edun, 20010
2. "Digital Image Processing and Analysis", B. Chanda and D. Dutta Majumdar, PHI, 2003

ARTIFICIAL NEURAL NETWORKS
B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	**17MT755**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits –03

Course Objective: Students will be able to

7. gain Knowledge of Artificial Neural Networks, Supervised Learning, Support Vector Machines and Radial Basis Function, Attractor Neural Networks, Self-organization Feature Map.
8. understand the working methodology of Artificial Neural Networks, Supervised Learning, Support Vector Machines and Radial Basis Function, Attractor Neural Networks, Self-organization Feature Map.

Module - 1

Introduction: Biological Neuron – Artificial Neural Model - Types of activation functions – Architecture: Feed forward and Feedback, Convex Sets, Convex Hull and Linear Separability, Non-Linear Separable Problem. Xor Problem, Multilayer Networks. Learning: Learning Algorithms, Error correction and Gradient Descent Rules, Learning objective of TLNs, Perceptron Learning Algorithm, Perceptron Convergence Theorem.

Module - 2

Supervised Learning: Perceptron learning and Non Separable sets,α-Least Mean Square Learning, MSE Error surface, Steepest Descent Search, μ-LMS approximate to gradient descent, Application of LMS to Noise Cancelling, Multi-layered Network Architecture, Backpropagation Learning Algorithm, Practical consideration of BP algorithm.

Module - 3

Support Vector Machines and Radial Basis Function : Learning from Examples, Statistical Learning Theory,Support Vector Machines, SVM application to Image Classification, Radial Basis Function Regularization theory, Generalized RBF Networks, Learning in RBFNs, RBF application to face recognition.

Module - 4

Attractor Neural Networks: Associative Learning Attractor Associative Memory, Linear Associative memory, Hopfield Network, application of Hopfield Network, Brain State in a Box neural Network, Simulated Annealing, Boltzmann Machine, Bidirectional Associative Memory

Module - 5

Self-organization Feature Map: Maximal Eigenvector Filtering, Extracting Principal Components, Generalized Learning Laws, Vector Quantization, Self-organization Feature Maps, Application of SOM, Growing Neural Gas.

Course outcomes: On completion of this subject, students will be able to:

CO1: have Knowledge of Artificial Neural Networks, Supervised Learning, Support Vector Machines and Radial Basis Function, Attractor Neural Networks, Self-organization Feature Map.

CO2: understand the working methodology of Artificial Neural Networks, Supervised Learning, Support Vector Machines and Radial Basis Function, Attractor Neural Networks, Self-organization Feature Map.

TEXT BOOKS:

1. Neural Networks A Classroom Approach– Satish Kumar, McGraw Hill Education (India) Pvt. Ltd, Second Edition.

REFERENCE BOOKS

1. Introduction to Artificial Neural Systems-J.M. Zurada, Jaico Publications 1994.
2. Artificial Neural Networks-B. Yegnanarayana, PHI, New Delhi 1998.

ROBOTICS LABORATORY
B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	17MTL76	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction+ 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**

Credits –02

Course Objective: Students will be able to

1: Understand the Importance & Applications of Robots in Virtual Environment

2: Design the Robots system for Industrial Application

PART A

1. Design the Robot programming for Point to Point using two Cubes.
2. Design the Robot programming for Drilling Operation using Cube and Cylinder.
3. Design the Robot programming using Smart Components.
4. Design the Robot programming for Mutimove Operation.
5. Design the Robot programming for Conveyor Tracking System.
6. Design the Robot programming for Continuous Path Operation on Cylinder

PART B

1. Design a Robot System for Pick and Place Operation.
2. Design a Robot System for Point to Point operation.[Cube]
3. Design a Robot System for Continuous Path Operation.
4. Design a Robot System for Circle Path Operation.
5. Design a Robot System for Drilling Operation of Cube.
6. Design a Robot System for Continuous Path Operation for any 3 Objects [Cube, Box, Circle]

Course outcomes:

On completion of this subject, students will be able to:

CO 1: Understand the importance of Robot system in Industrial Process in Virtual Environments

CO 2: Design and Develop a Robot System for Real time Industrial Process.

ScheMT of Examination:

One question from Part A:	**40Marks**
One question from part B:	**40 Marks**
Viva- Voce:	**20Marks**
Total:	**100 Marks**

SIGNAL PROCESSING LABORATORY
B.E, VII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme 2017-18]

Course Code	17MTL77	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03 (1 Hour Instruction+ 2 Hours Laboratory)**	**SEE Marks**	**60**
RBT Levels		**Exam Hours**	**03**
Credits –02			

Course Objective:

9. 1. gain knowledge of Scientific Programming using Matlab.
10. 2. understand different functions in Matlab and TMS320C67XX board in signal processing.
11. 3. use in different functions to solve engineering problems.

PART A

1. Generation of basic elementary signals and operations on these signals.
2. Verification of sampling theorem.
3. Impulse response of a given system.
4. Solving a given difference equation.
5. Computation of N point DFT and IDFT of a given sequence and to plot magnitude and phase spectrum.
6. Design and implementation of FIR filter to meet given specifications.
7. Design and implementation of IIR filter to meet given specifications.
8. Removal of noise from an audio signal.
9. Different operations on image signal.

PART B

1. Linear convolution of two given sequences.
2. Circular convolution of two given sequences.
3. Computation of N- Point DFT of a given sequence
4. Realization of an FIR filter (any type) to meet given specifications .The input can be a Signal from function generator / speech signal.
5. Noise: Add noise above 3kHz and then remove; Interference suppression using 400 Hz tone.
6. Impulse response of first order and second order system.

Course outcoess: On completion of the course the student will

- **CO1: have knowledge of Scientific Programming using Matlab.**
- **CO2: understand the programming in Matlab software and hardware.**
- **CO3: use DSP board for real time applications.**

ScheMT for Examination:

Two Questions from Part A - 80 Marks (40 +40)

Viva-Voce - 20 Marks

Total: 100 Marks

Project Work, Phase I

Course	Code	Credits	L-T-P	AssessMTnt		Exam Duration
				SEE	CIA	
Project Work, Phase I	**17MTP78**	**2**	**0-3-0**	**100**	**-**	**-**

AUTOMOTIVE ELECTRONICS AND HYBRID VEHICLES

B.E, VIII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme-2017-2018]

Course Code	**17MT81**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course objectives: Students will be able to

- gain Knowledge of developing basic skills necessary to diagnose automotive electrical problems, to include electrical principles, use of basic electrical test equipment.
- understand the advanced automotive electrical systems, to include body electrical accessories, and basic computer control.

diagnosis the problem automotive batteries, starting, and charging, lighting systems, body electrical accessories, and basic computer control.

Module - 1

Automotive Fundamentals Overview: Four Stroke Cycle, Engine Control, Ignition System, Spark plug, Spark pulse generation, Ignition Timing, Drive Train, Transmission, Brakes, Steering System, Battery, Starting System.**Air/Fuel Systems** Fuel Handling, Air Intake System, Air/ Fuel Management

Module - 2

Sensors – Oxygen (02/EGO) Sensors, Throttle Position Sensor (TPS), Engine Crankshaft Angular Position (CKP)Sensors, Hall effect Position Sensor, Shielded Field Sensor, Optical Crankshaft Position Sensor, Manifold Absolute Pressure (MAP) Sensor – Strain gauge and Capacitor capsule, Engine Coolant Temperature (ECT) Sensor, Intake Air Temperature (IAT) Sensor, Knock Sensor, Airflow rate sensor, Throttle angle Sensor. **Actuators:** Fuel Metering Actuator, Fuel Injector, Ignition Actuator. Exhaust After-Treatment Systems – AIR, Catalytic Converter, Exhaust Gas Recirculation (EGR), Evaporative Emission Systems.

Module - 3

Automotive Instrumentation and Communication: Sampling, Measurement & Signal Conversion of various parameters (Speed, fuel, pressure). Serial Data, Communication Systems, Protection, Body and Chassis is Electrical Systems, Remote Keyless Entry, GPS

Module - 4

Vehicle Motion Control: Cruise control, Chassis, Power Brakes, Antilock Brake System (ABS), Electronic Steering Control, Power Steering, Traction Control, Electronically controlled suspension. **Automotive Diagnostics –**Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems. **Future Automotive Electronics Systems: Alternative** Fuel Engines, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Radio navigation, Advance Driver Information System

Module - 5

Introduction to Alternative Vehicles: Electric Vehicle, Hybrid Electric vehicle, Electric Hybrid Vehicle, Vehicle components, Electric and Hybrid history EV/CEV Comparison. **Alternative Vehicle Architecture:** Electric Vehicles, Hybrid Electric Vehicles, Plug-in Hybrid Electric Vehicles, Power Train component Sizing, Mass Analysis & Packaging, Vehicle Simulation.

Course outcomes: On completion of the course the student will

CO1: have knowledge of automotive electronics domain of various Engine parts, Sensor, Actuator, Communication and Measurement System.
CO2: understanding the engine parameters and a critical awareness of current problems within the automotive electronics domain using Various Measurement Technology.
CO3: determine the extent and nature of electronic circuitry in automotive systems including monitoring and control circuits for engines, transmissions, brakes, steering, suspension, climate control, instrumentation and radios and accessories involved in Automotive Industry

Text Books:

1) **Willliam B. Ribbens:** Understanding Automotive Electronics, 6th Edition, SAMS/Elsevier Publishing

1. Iqbal Husain "Electric and Hybrid Vehicles: Design fundamentals". CRC Press, 2011.

Reference Books:

1. **Robert Bosch GmbH:** Automotive Electronics Systems and Components 5th Edition, John Wiley & Sons Ltd., 2007
2. James Laminie and John Lowry. "Electric Vehicle Technology – Explained', CRC Press 2010.
3. Society of Automobile Engineers, "Hybrid Electric vehicles", CRC Press, 2011.

COMMUNICATION SYSTEM

B.E, VIII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme-2017-2018]

Course Code	**17MT82**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**04**	**SEE Marks**	**60**
Total Number of Lecture Hours	**50(10 Hours per Module)**	**Exam Hours**	**03**

Credits – 04

Course objectives: Students will be able to

- gain the Knowledge Of different modulation techniques, analog and digital modulation and demodulation, different wave form code techniques and spread spectrum
- understand the concept of methods of generating modulated and demodulated signals, encoding and decoding techniques, multiplexing and demultiplexing of signals

Module - 1

Introduction To Communication Systems: Information, Transmitter, chanel-noise, Receiver, modulation, need for modulation, band width requirements, sine wave and Fourier series review, frequency spectra of non sinusoidal waves. Basic signal processing operations in digital communication. Sampling Principles: Sampling Theorem

Module - 2

Amplitude Modulation: Introduction AM Time-Domain description, Frequency – Domain description. Generation of AM wave: square law modulator, switching modulator. Detection of AM waves: square law detector, envelop detector. Double side band suppressed carrier modulation (DSBSC): Time-Domain description, Frequency-Domain representation, Generation of DSBSC waves: balanced modulator, ring modulator. Coherent detection of DSBSC modulated waves. Costas loop..

Module - 3

Angle Modulation & Demodulation: Basic definitions, FM, narrow band FM, wide band FM, transmission bandwidth of FM waves, generation of FM waves: indirect FM and direct FM, Demodulation of FM waves, FM stereo multiplexing, Phase-locked loop, Nonlinear model of the phase – locked loop, Linear model of the phase – locked loop, Nonlinear effects in FM systems.

Module - 4

Waveform Coding Techniques: PAM, TDM. Waveform Coding Techniques, PCM, Quantization noise and SNR, robust quantization. DPCM, DM, applications. Line Codes : Unipolar RZ& NRZ, Polar RZ& NRZ, Bi-Polar RZ & NRZ ,Manchester.

Module - 5

Spread Spectrum Modulation: Pseudo noise sequences, notion of spread spectrum, direct sequence spread spectrum, coherent binary PSK, frequency hop spread spectrum, applications. Digital Multiplexers: FDM ,TDM ,Classification of Multiplexers ,T1 Carrier System

Course outcomes: On completion of the course the student will

CO 1: have Knowledge Of different modulation techniques, analog and digital modulation and demodulation, different wave form code techniques and spread spectrum

CO 2: understand the concept of generation modulated and demodulated signals, encoding and decoding techniques multiplexing and demultiplexing of signals

Text Books:

1. Communication Systems, Simon Haykins, 3rd Edition, John Willey, 1996.
2. An Introduction to Analog and Digital Communication, Simon Haykins, John Wiley, 2003
3. Digital communications, Simon Haykin, John Wiley, 2003.

Reference Books:

1. Modern digital and analog Communication systems B. P. Lathi, 3rd ed 2005 Oxford University press.
2. Communication Systems, Harold P.E, Stern Samy and A Mahmond, Pearson Edn, 2004.
3. Communication Systems: Singh and Sapre: Analog and
4. Digital and analog communication systems & An introduction to Analog and Digital Communication, K. Sam Shanmugam, John Wiley, 1996.
   2.Simon Haykin, John Wiley, 2005

PRODUCT DESIGN & DEVELOPMENT

B.E, VIII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme-2017-2018]

Course Code	**17MT831**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course objectives: Students will be able to

6. gain knowledge of Product life-cycle , Product design process, Product analysis
7. understand the value engineering, product design tools and Reverse Engineering

Module - 1

•**Product life-cycle:** Product policy of an organization. Selection of a profitable product, Product design process, Product analysis.

Module - 2

• **Value engineering in product design:** Advantages, Applications in product design, Problem identification and selection, Analysis of functions, Anatomy of function. Primary versus secondary versus tertiary/unnecessary functions, Functional analysis: Functional Analysis System Technique (FAST), Case studies.

Module - 3

Introduction to product design tools: QFD, Computer Aided Design, Robust design, DFX, DFM, DFA, Ergonomics in product design

Module - 4

Product design for manual assembly: Design guidelines for metallic and non metallic products to be manufactured by different processes such as casting, machining, injection molding etc., Rapid prototyping, needs, advantages.

Module - 5

Reverse engineering: Functionality- dimensional- developing technical data - digitizing techniques - construction of surface model - solid-part material- characteristics evaluation -software and application prototyping – verification

Course outcomes:

On completion of course students will

CO1: have knowledge of Product life-cycle , Product design process, Product analysis .

CO2: understand the value engineering, product design tools and Reverse Engineering

Text Books:

5. *Product Design* and *Development* by Karl T. Ulrich and Steven D. Eppinger (McGraw-Hill 1995, 2000, 2004, 2008)
6. Reverse Engineering, Katheryn, A. Ingle, McGraw-Hill, 1994

Reference Books:

1. "**Engineering Design**", George E.Dieter, Linda C.Schmidt, McGraw-Hill International Edition, 4th Edition, 2009, ISBN 978-007- 127189-9

2. "**Product Design and Development** ", Anita Goyal, Karl T Ulrich, Steven D Eppinger, 4th Edition, 2009, Tata McGraw-Hill Education, ISBN-10-007-14679-9

3. "**Product Design**", Kevin Otto, Kristin Wood, Indian Reprint 2004, Pearson Education,ISBN 9788177588217

4. "**Engineering Design Process**", Yousef Haik, T. M. M. Shahin, 2nd Edition Reprint, Cengage Learning, 2010, ISBN 0495668141

5. "**Engineering Design: A Project-based Introduction**", Clive L.Dym, Patrick Little, 3rd Edition, John Wiley & Sons, 2009, ISBN 978- 0-470-22596-7

ARTIFICIAL INTELLIGENCE
B.E, VIII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme-2017-2018]

Course Code	**17MT832**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course objectives: Students will be able to

- gain Knowledge of Artificial Intelligence, Production Rules, Search Algorithms, Expert System & its architectures, Machine Learning.
- understand the working methodology of Search Algorithms, Expert System & Machine Learning.

Module - 1

Artificial Intelligence: Introduction, History of AI, defining, , Importance f AI, Early Work in AI, Scope of AI, AI and Related fields, AI Techniques ,Alan Turing Machine, Intelligent Agents

Module - 2

Space Representation: Defining the Problem, Production Rules for water jug problem, Breadth-First Search Algorithm , Depth-First Search Algorithm, Generate & Test Algorithm, Hill Climbing Algorithms: Simple Hill Climbing Algorithm, Steepest-Ascent Hill Climbing Algorithm.

Module - 3
Expert Systems: Introduction, Characteristics of Expert System, Need of an Expert System, Expert System Architecture, Steps to develop an Expert System ,case studies: MYCIN ,DENDRAL. and Neural Nets: Introduction ,TAN-Toy Adaptive Node ,Network Structures, Application of Neural Nets.
Module - 4
Expert Systems Architectures: Introduction ,Rule-Based System Architectures ,Non- Production system Architectures: Semantic Network Architectures, Frame Architectures ,Decision Tree Architectures, Blackboard System Architectures, Analogical Reasoning Architectures, Neural Network Architectures.
Module - 5
Introduction to Machine Learning: Introduction**,** Perceptrons, Perceptron Learning Algorithm, Checkers Playing Examples, Learning automata:Automaton model, Temperature Control Model, CLA representation of NIM game, Genetic Algorithms, Intelligent editors .
Course outcomes: **On completion of course students will** **CO1:** have Knowledge of Artificial Intelligence, Production Rules, Search Algorithms, Expert System & its architectures, Machine Learning. **CO2:** understand the working methodology of Search Algorithms, Expert System & Machine Learning.
Text Books: 1. **Artificial Intelligence**, Elaine Rich & Kevin Knight, M/H 2004. 2. **Introduction to AI & ES**, Dan W. Patterson, Prentice Hall of India, 2012. 3. **Artificial Intelligence A Practical Approach**, Er.Rajiv Chopra, S.Chand & Company Ltd,2012.
Reference Books: **2. Principles of Artificial intelligence,** Springer Vertag, Berlin, 1981. **3. Artificial intelligence in business, Science & Industry,** Wendy B, Ranch **4. A guide to Expert systems,** Waterman, D. A. Addison – Wesley inc. 1986. **5. Building Expert Systems,** Hayes, Roth, Waterman, D. A. Addison Wesley, 1983.

DIGITAL CONTROL SYSTEM

B.E, VIII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme-2017-2018]

Course Code	**17MT833**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course objectives: Students will be able to

- gain knowledge to learn the concepts of developing State model , Linear and Non Linear Control System.
- understand the concepts Linear and Non Linear Digital Control System for observing the Controllability of the system
- determine and diagnosis the problem related Lead and Lag Networks using Plots.

Module - 1

STATE SPACE ANALYSIS OF CONTROL SYSTEMS: State space representation of systems, solving the time invariant state equations, transfer matrix, linear time invariant systems, state space representation of discrete time systems and solving discrete time state equation.

Module - 2

POLE PLACEMENT: Controllability, Observability for continuous time systems, pole placement design and state observers. Problems on Each

Module - 3

OPTIMAL AND ADAPTIVE CONTROL SYSTEMS: optimal control system based on quadratic performance index, adaptive control system..

Module - 4

DESCRIBING FUNCTION ANALYSIS OF NONLINEAR CONTROL SYSTEMS: Introduction to nonlinear systems, describing function analysis of nonlinear control systems, stability of nonlinear control system.

Module - 5

COMPENSATION TECHNIQUES: Lead, lag, lead lag network and compensator design using Bode/Root locus techniques.

Course outcomes: On completion of the course the student will

CO1: have knowledge of State model, Linear and Non Linear Control System, Controllability and Observability.

CO2: understanding the concepts State model, Linear and Non Linear Control System, Controllability and Observability used in Digital Control System .

CO3: determine the extent and nature of Lead Lag Circuitry by Plot.

Text Books:

1. Modern Control Engineering-K. Ogata, Prentice 3rd Edition, Hall of India publication.
2. Discrete time Control Systems-K.Ogata, 2nd Edition, Prentice Hall of India publication**.**

Reference Books:

1. Digital control and state variable methods-Madan Gopal, 2nd Edition, Prentice Hall of India.
2. Modern Control Engineering-Roy Choudhury, Prentice Hall of India.

Management Information Systems

B.E, VIII Semester, Mechatronics Engineering
[As per Choice Based Credit System (CBCS) scheme-2017-2018]

Course Code	**17MT834**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course objectives: Students will be able to

- gain the importance of information in business.
- understand the technologies and methods used for effective decision making in an organization.

Module - 1

INTRODUCTION: Data, Information, Intelligence, Information Technology, Information System, evolution, types based on functions and hierarchy, System development methodologies, Functional Information Systems, DSS, EIS, KMS, GIS, International Information System.

Module - 2

SYSTEM ANALYSIS AND DESIGN: Case tools - System flow chart, Decision table, Data flow Diagram (DFD), Entity Relationship (ER), Object Oriented Analysis and Design (OOAD), UML diagram.

Module - 3

DATABASE MANAGEMENT SYSTEMS: DBMS – HDBMS, NDBMS, RDBMS, OODBMS, Query Processing, SQL, Concurrency Management, Data warehousing and Data Mart.

Module - 4

SECURITY, CONTROL AND REPORTING: Security, Testing, Error detection, Controls, IS Vulnerability, Disaster Management, Computer Crimes, Securing the Web, Intranets and Wireless Networks, Software Audit, Ethics in IT, User Interface and reporting.

Module - 5

NEW IT INITIATIVES: Role of information management in ERP, e-business, e-governance, Data Mining, Business Intelligence, Pervasive Computing, Cloud computing, CMM.

Course outcomes:
On completion of course students will
CO1: have knowledge on effective applications of information systems in business.
CO2: understand the technologies and methods used for effective decision making in an organization.

Text Books:

3. **Management Information Systems – The Managers View,** Robert Schultheis and Mary Summer, Tata McGraw Hill, 2008.
4. **Management Information Systems – Managing the digital firm**, Kenneth C. Laudon and Jane Price Laudon, PHI Learning / Pearson Education, PHI, Asia, 2012.

Reference Books:

8. **MIS in Business, Government and Society**, Rahul de, Wiley India Pvt Ltd, 2012
9. **Management Information System: Conceptual Foundations, Structure and Development,** Gordon Davis, Tata McGraw Hill, 21st Reprint 2008.
10. **Management Information Systems for the Information Age,** Haag, Cummings and Mc Cubbrey, McGraw Hill, 2005. 9th edition, 2013.
11. **Information Technology for Management – Transforming Organisations in the Digital Economy,** Turban, McLean and Wetherbe, John Wiley, 6th Edition, 2008.
12. **Management Information Systems,** Raymond McLeod and Jr. George P. Schell, Pearson Education, 2007.
13. **Management Information Systems – Managing Information Technology in the E-business enterprise,** James O Brien, Tata McGraw Hill, 2004. 22 .
14. **Information Systems,** Raplh Stair and George Reynolds, Cengage Learning, 10th Edition, 2012
15. **Information Assurance for the Enterprise – A Roadmap to Information Security,** Corey Schou and Dan Shoemaker, Tata McGraw Hill, 2007.
16. **Information Technology Control and Audit,** Frederick Gallegor, Sandra Senft, Daniel P. Manson and Carol Gonzales, Auerbach Publications, 4th Edition, 2013.

RADAR ENGINEERING

B.E, VIII Semester, Mechatronics Engineering

[As per Choice Based Credit System (CBCS) scheme-2017-2018]

Course Code	**17MT835**	**CIE Marks**	**40**
Number of Lecture Hours/Week	**03**	**SEE Marks**	**60**
Total Number of Lecture Hours	**40(8 Hours per Module)**	**Exam Hours**	**03**

Credits – 03

Course objectives: Students will be able to

- gain Knowledge of Radars , The Radar Equation, MTI and Pulse Doppler Radar, Tracking Radar & The Radar Antenna.
- understand the operation of Radars , MTI and Pulse Doppler Radar, Tracking Radar & the Radar Antenna.

Module - 1

Basics of Radar: Introduction, Maximum Unambiguous Range, Radar Waveforms, Definitions w.r.t Pulse waveform - PRF, PRI, Duty Cycle, Peak Transmitter Power, Average transmitter Power. Simple form of the Radar Equation, Radar Block Diagram and Operation, Radar Frequencies, Applications of Radar, The Origins of Radar, Illustrative Problems. (Chapter 1 of Text)

Module - 2

The Radar Equation: Prediction of Range Performance, Detection of signal in Noise, Minimum Detectable Signal, Receiver Noise, SNR, Modified Radar Range Equation, Envelope Detector — False Alarm Time and Probability, Probability of Detection, Radar Cross Section of Targets: simple targets – sphere, cone-sphere, Transmitter Power, PRF and Range Ambiguities, System Losses (Qualitative treatment), Illustrative Problems. (Chapter 2, except 2.4, 2.6 2.8 & 2.11 of Text)

Module - 3

MTI and Pulse Doppler Radar: Introduction, Principle, Doppler Frequency Shift, Simple CW Radar, Sweep to Sweep subtraction and Delay Line Canceler, MTI Radar with – Power Amplifier Transmitter, Delay Line Cancelers — Frequency Response of Single Delay- Line Canceler, Blind Speeds, Clutter Attenuation, MTI Improvement Factor, N- Pulse Delay-Line Canceler, Digital MTI Processing – Blind phases, I and Q Channels, Digital MTI Doppler signal processor, Moving Target Detector- Original MTD. (Chapter 3, 3.1, 3.2, 3.5, 3.6 of Text)

Module - 4

Tracking Radar: Tracking with Radar- Types of Tracking Radar Systems, Monopulse TrackingAmplitude Comparison Monopulse (one-and two-coordinates), Phase Comparison Monopulse. Sequential Lobing, Conical Scan Tracking, Block Diagram of Conical Scan Tracking Radar, Tracking in Range, Comparison of Trackers. (Chapter 4, 4.1, 4.2, 4.3 of Text)

Module - 5
The Radar Antenna: Functions of The Radar Antenna, Antenna Parameters, Reflector Antennas and Electronically Steered Phased array Antennas. (Chapter 9: 9.1, 9.2 9.4, 9.5 of Text) Radar Receiver: The Radar Receiver, Receiver Noise Figure, Super Heterodyne Receiver, Duplexers and Receivers Protectors, Radar Displays. (Chapter 11 of Text)
Course outcomes: On completion of course students will **CO 1:** have knowledge of Radars, the Radar Equation, MTI and Pulse Doppler Radar, Tracking Radar and the Radar Antenna. **CO 2:** understand the operation of Radars, MTI and Pulse Doppler Radar, Tracking Radar & the Radar Antenna.
Text Books: 1. Introduction to Radar Systems-Merrill I Skolnik ,3e,TMH, 2001
Reference Book: 1. Radar Principles, Technology. Applications — Byron Edde, Pearson Education, 2004. 2. Radar Principles – Peebles. Jr, P.Z. Wiley. New York, 1998. 3. Principles of Modem Radar: Basic Principles – Mark A. Rkhards, James A. Scheer, William A. HoIm. Yesdee, 2013

Internship/ Professional Practice

Course	Code	Credits	L-T-P	Assessment		Exam Duration
				SEE	CIA	
Internship/ Professional Practice	17MT84	2	Industry Oriented	50	50	3 Hrs

Project Work, Phase II

Course	Code	Credits	L-T-P	Assessment		Exam Duration
				SEE	CIA	
Project Work, Phase II	17MTP85	6	0-6-0	100	100	3 Hrs

Seminar

Course	Code	Credits	L-T-P	Assessment		Exam Duration
				SEE	CIA	
Seminar	17MTS86	1	0-4-0	100	-	-