Simulation and Analysis using Ansys workbench		Semester	IV
Course Code	BAGL456A	CIE Marks	50
Teaching Hours/Week (L:T:P: S)	0:0:2:0	SEE Marks	50
Total Hours of Pedagogy	14 sessions	Total Marks	100
Credits	01	Exam Hours	03
Examination nature (SEE)	Practical		

Course objectives:

- Analyzing the force and stress in mechanical components.
- Analyzing deflection in mechanical components.
- Analyzing thermal stress of mechanical components.
- Analyzing heat transfer in mechanical components.
- Analyzing the vibration of mechanical components.

Sl.NO	Experiments
1	Study of Basics in ANSYS
2	Stress analysis of a plate with a circular hole
3	Stress analysis of rectangular L bracket
4	Stress analysis of cantilever beam
5	Stress analysis of simply supported beam
6	Stress analysis of fixed beam
7	Stress analysis of an axi-symmetric component
8	Thermal stress analysis of a 2D component
	Demonstration Experiments (For CIE)
9	Conductive heat transfer analysis of a 2D component
10	Convective heat transfer analysis of a 2D component
11	Mode frequency analysis of cantilever beam
12	Mode frequency analysis of simply supported beam

Course outcomes (Course Skill Set):

At the end of the course the student will be able to:

- Find out the effect of force and impact of stress on the mechanical components.
- Calculate the deflection occurring on the mechanical components.
- Get a detailed understanding of the thermal stress creation and its mechanism of spreading in mechanical components.
- Gain knowledge regarding the mechanism of heat transfer in mechanical components.
- Find out the vibration effects on mechanical components.

Assessment Details (both CIE and SEE)

The weightage of Continuous Internal Evaluation (CIE) is 50% and for Semester End Exam (SEE) is 50%. The minimum passing mark for the CIE is 40% of the maximum marks (20 marks out of 50) and for the SEE minimum passing mark is 35% of the maximum marks (18 out of 50 marks). A student shall be deemed to have satisfied the academic requirements and earned the credits allotted to each subject/ course if the student secures a minimum of 40% (40 marks out of 100) in the sum total of the CIE (Continuous Internal Evaluation) and SEE (Semester End Examination) taken together

Continuous Internal Evaluation (CIE):

CIE marks for the practical course are **50 Marks**.

The split-up of CIE marks for record/ journal and test are in the ratio **60:40**.

- Each experiment is to be evaluated for conduction with an observation sheet and record write-up. Rubrics for the evaluation of the journal/write-up for hardware/software experiments are designed by the faculty who is handling the laboratory session and are made known to students at the beginning of the practical session.
- Record should contain all the specified experiments in the syllabus and each experiment write-up will be evaluated for 10 marks.
- Total marks scored by the students are scaled down to **30 marks** (60% of maximum marks).
- Weightage to be given for neatness and submission of record/write-up on time.
- Department shall conduct a test of 100 marks after the completion of all the experiments listed in the syllabus.
- In a test, test write-up, conduction of experiment, acceptable result, and procedural knowledge will carry a weightage of 60% and the rest 40% for viva-voce.
- The suitable rubrics can be designed to evaluate each student's performance and learning ability.
- The marks scored shall be scaled down to **20 marks** (40% of the maximum marks).

The Sum of scaled-down marks scored in the report write-up/journal and marks of a test is the total CIE marks scored by the student.

Semester End Evaluation (SEE):

- SEE marks for the practical course are 50 Marks.
- SEE shall be conducted jointly by the two examiners of the same institute, examiners are appointed by the Head of the Institute.
- The examination schedule and names of examiners are informed to the university before the conduction of the examination. These practical examinations are to be conducted between the schedule mentioned in the academic calendar of the University.
- All laboratory experiments are to be included for practical examination.
- (Rubrics) Breakup of marks and the instructions printed on the cover page of the answer script to be strictly adhered to by the examiners. **OR** based on the course requirement evaluation rubrics shall be decided jointly by examiners.
- Students can pick one question (experiment) from the questions lot prepared by the examiners jointly.
- Evaluation of test write-up/ conduction procedure and result/viva will be conducted jointly by examiners.

General rubrics suggested for SEE are mentioned here, writeup-20%, Conduction procedure and result in -60%, Viva-voce 20% of maximum marks. SEE for practical shall be evaluated for 100 marks and scored marks shall be scaled down to 50 marks (however, based on course type, rubrics shall be decided by the examiners)

Change of experiment is allowed only once and 15% of Marks allotted to the procedure part are to be made zero.

The minimum duration of SEE is 02 hours

Semester-End Examination:

Theory SEE will be conducted by University as per the scheduled timetable, with common question papers for the course (**duration 03 hours).**

- The question paper will have ten questions. Each question is set for 20 marks. .
- There will be 2 questions from each module. Each of the two questions under a module (with a maximum of 3 sub-questions), **should have a mix of topics** under that module.
- The students have to answer 5 full questions, selecting one full question from each module.

Marks scored shall be proportionally reduced to 50 marks

Suggested Learning Resources:

Books

1. Robert. J. Schilling , "Fundamentals of robotics – Analysis and control", Prentice Hall of India 1996.
2. Introduction to Robotics (Mechanics and control), John. J. Craig, Pearson Education Asia 2002.
3. Introduction to Robotics by S K Saha, Mc Graw Hill Education
4. R K Mittal and I J Nagrath, "Robotics and Control", Tata McGraw Hill, New Delhi,2003.
5. Ashitava Ghosal, "Robotics-Fundamental concepts and analysis", Oxford University press.
6. Robotics Technology and Flexible Automation, Second Edition, S. R. Deb
7. Introduction to Autonomous Mobile Robots, Siegwart, Roland, Cambridge, Mass. : MIT Press, 2nd ed.

Additional References:

1. Sicilliano, Khatib , "Handbook of Robotics", Springer
2. John J. Craig, Introduction to Robotics – Mechanics and Control
3. Kevin M. Lynch, Frank C. Park, Modern Robotics Mechanics, Planning and Control

Activity Based Learning (Suggested Activities in Class)/ Practical Based learning

- Quizzes
- Assignments
- Seminars

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