

<b>B. E. MECHANICAL ENGINEERING</b> <b>Choice Based Credit System (CBCS) and Outcome Based Education (OBE)</b> <b>SEMESTER – VII</b>			
<b>CONTROL ENGINEERING</b>			
Course Code	<b>18ME71</b>	CIE Marks	40
Teaching Hours / Week (L:T:P)	3:0:0	SEE Marks	60
Credits	03	Exam Hours	03
<b>Course Learning Objectives:</b> <ul style="list-style-type: none"> <li>To develop comprehensive knowledge and understanding of modern control theory, industrial automation, and systems analysis.</li> <li>To model mechanical, hydraulic, pneumatic and electrical systems.</li> <li>To represent system elements by blocks and its reduction techniques.</li> <li>To understand transient and steady state response analysis of a system.</li> <li>To carry out frequency response analysis using polar plot, Bode plot.</li> <li>To analyse a system using root locus plots.</li> <li>To study different system compensators and characteristics of linear systems.</li> </ul>			
<b>Module-1</b>			
<b>Introduction:</b> Components of a control system, Open loop and closed loop systems. <b>Types of controllers:</b> Proportional, Integral, Differential, Proportional-Integral, and Proportional- Integral-Differential controllers. <b>Modelling of Physical Systems: Mathematical Models of Mechanical, Electrical, Thermal, Hydraulic Systems.</b>			
<b>Module-2</b>			
Time domain performance of control systems: Typical test signal, Unit step response and time domain specifications of first order, second order system. Steady state error, error constants.			
<b>Module-3</b>			
Block diagram algebra, Reduction of block diagram, Signal flow graphs, Gain formula for signal flow graphs, State diagram from differential equations.			
<b>Module-4</b>			
<b>Stability of linear control systems:</b> Routh's criterion, Root locus, Determination of phase margin and gain margin using root locus.			
<b>Module-5</b>			
Stability analysis using Polar plot, Nyquist plot, Bode plot, Determination of phase margin and gain margin using Bode plot.			
<b>Assignment:</b> <ol style="list-style-type: none"> <li>Study of On-Off Controller for Flow/ Temperature.</li> <li>Study of Control Modes like P, PD, PI, PID for Pressure / Temperature / Flow.</li> <li>Assignment on Root Locus, Bode Plots and Polar Plots.</li> <li>Use of Software 'MATLAB' on the above topics.</li> </ol> <b>Course Outcomes:</b> At the end of the course, the student will be able to: <ul style="list-style-type: none"> <li>CO1: Identify the type of control and control actions.</li> <li>CO2: Develop the mathematical model of the physical systems.</li> <li>CO3: Estimate the response and error in response of first and second order systems subjected standard input signals.</li> <li>CO4: Represent the complex physical system using block diagram and signal flow graph and obtain transfer function.</li> <li>CO5: Analyse a linear feedback control system for stability using Hurwitz criterion, Routh's criterion and root Locus technique in complex domain.</li> </ul>			

CO6: Analyse the stability of linear feedback control systems in frequency domain using polar plots, Nyquist and Bode plots.

**Question paper pattern:**

- The question paper will have ten full questions carrying equal marks.
- Each full question will be for 20 marks.
- There will be two full questions (with a maximum of four sub- questions) from each module.
- Each full question will have sub- question covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

Sl. No.	Title of the Book	Name of the Author/s	Name of the Publisher	Edition and Year
<b>Textbook/s</b>				
1	Automatic Control Systems	Farid G., Kuo B. C	McGraw Hill Education	10th Edition, 2018
2	Control systems	Manik D. N	Cengage	2017
<b>Reference Books</b>				
1	Modern control Engineering	K. Ogata	Pearson	5th Edition, 2010
2	Control Systems Engineering	Norman S Nice		Fourth Edition, 2007
3	Modern control Systems	Richard C Dorf	Pearson	2017
4	Control Systems Engineering	IjNagrath, M Gopal	New Age International (P) Ltd	2018
5	Control Systems Engineering	S Palani	Tata McGraw Hill Publishing Co Ltd	ISBN-13 978007067193